

Minimum sample size for estimating the Bayes error at a predetermined level.

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Declaration

I, Ryno Potgieter, declare that the dissertation, which I hereby submit for the degr	ee
MSc: Mathematical Statistics at the University of Pretoria, is my own work and has n	ot.
previously been submitted by me for a degree at this or any other tertiary institution.	

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Abstract

Determining the correct sample size is of utmost importance in study design. Large samples yield classifiers or parameters with more precision and conversely, samples that are too small yield unreliable results. Fixed sample size methods, as determined by the specified level of error between the obtained parameter and population value, or a confidence level associated with the estimate, have been developed and are available. These methods are extremely useful when there is little or no cost (consequences of action), financial and time, involved in gathering the data. Alternatively, sequential sampling procedures have been developed specifically to obtain a classifier or parameter estimate that is as accurate as deemed necessary by the researcher, while sampling the least number of observations required to obtain the specified level of accuracy.

This dissertation discusses a sequential procedure, derived using Martingale Limit Theory, which had been developed to train a classifier with the minimum number of observations to ensure, with a high enough probability, that the next observation sampled has a low enough probability of being misclassified. Various classification methods are discussed and tested, with multiple combinations of parameters tested. Additionally, the sequential procedure is tested on microarray data. Various advantages and shortcomings of the sequential procedure are pointed out and discussed.

This dissertation also proposes a new sequential procedure that trains the classifier to such an extent as to accurately estimate the Bayes error with a high probability. The sequential procedure retains all of the advantages of the previous method, while addressing the most serious shortcoming. Ultimately, the sequential procedure developed enables the researcher to dictate how accurate the classifier should be and provides more control over the trained classifier.



Summary

Determining the correct sample size is of utmost importance in study design. Samples that are large can more accurately estimate unknown parameters, whilst underestimating the required sample size will yield unreliable results. Therefore the sample needs to be large enough for the results obtained to be representative. Quite often there are multiple costs involved, including the financial cost of acquiring the data, and the time needed to obtain or physically sample the observations.

Multiple fixed-sample size methods have been developed to calculate the minimum required number of observations in a sample. One such method is Stein's two stage sampling method. In Stein's method, the first stage samples observations to obtain estimates of parameters needed to calculate the final sample size. The second stage then entails sampling the remainder of the required observations. The sample size required in study design, is often limited by cost, time or the availability of data. Consequently, sequential sampling procedures have been developed to sample the least number of observations necessary to accurately train a classifier or derive an estimate. These procedures sample only the minimum number of observations to ensure the classifier or parameter obtained is as accurate as need be.

In this dissertation, a sequential procedure previously proposed, using Martingale Limit Theory, is discussed. This sequential procedure had been developed to sample the minimum number of observations required to train a classifier to such an extent as to ensure, with a probability of at least 1-a, that the probability of the next observation being misclassified is acceptably low. For the purpose of this dissertation, various simulation studies were conducted to assess the predictive ability of the classifiers derived from the sequential procedure. Some of the classification methods used include linear discriminant analysis (LDA), quadratic discriminant analysis (QDA), K-nearest neighbours (KNN) and linear regression of an indicator matrix (LRIM). Additionally, multiple combinations of input parameters are tested. The sequential procedure is then also tested on a microarray dataset containing data on the breast cancer prognosis of 295 patients. The dataset has been used extensively in the medical field, primarily to derive a 70-gene signature that could more accurately predict a patient's prognosis. The primary disadvantage of this sequential procedure is its inability to account for Bayes errors larger than the desired maximum rate of error as specified by the researcher, which ultimately results in the sequential procedure continuing ad infinitum. Other shortcomings of the sequential procedure are also briefly discussed.



In conclusion, a new sequential procedure that samples the minimum number of observations required to derive a classifier that estimates the Bayes error at a predetermined level is also proposed. Therefore the classifier is trained until the error rate obtained estimates the Bayes error within a predetermined level. The classifier will never try and obtain an unfeasibly low misclassification rate. The sequential procedure retains all of the advantages (being independent of the classification method used, assessing stopping criteria after each iteration, etc.) of the previous method, while addressing the most serious shortcoming. Various simulation studies are conducted, and the two sequential methods are compared. The proposed sequential procedure is also tested on the microarray dataset. Ultimately, the sequential procedure developed enables the researcher to dictate how accurate the classifier should be and provides more control over the trained classifier.

Future work could comprise of testing the proposed sequential procedure on other classification methods not specifically tested in this dissertation, such as Classification and regression trees (CART) or Neural networks. Additionally, the sequential procedure can be enhanced in such a manner that it automatically estimates the values for the input parameters α (the level of significance required to obtain a coverage probability of $100(1-\alpha)\%$) and a (a parameter used to change the bounds of the rate of misclassification from [0;1] to (0;1)).



Chapter 1

Introduction

In study design, it is of utmost importance to determine the correct sample size. Large samples yield greater precision when unknown parameters are estimated, and therefore, the obtained results tend to be reliable. There could, however, be multiple costs involved in sampling the required data. These costs often include, and are not necessarily limited to, the actual time needed to obtain the required number of observations and the financial impact associated. When the sample size is too small, the results obtained are often unreliable and inaccurate. This makes a sound or optimal decision, based on these results, impossible. Therefore, it is imperative that the size of the sample be large enough to attain a prespecified level of accuracy.

In this Chapter, fixed-sample size methods of calculating the sample size required to train a classifier or obtain an estimate of an unknown parameter at a particular level of accuracy are briefly discussed. Stein (1945) proposed a two stage sampling procedure to calculate the required sample size. If the cost of sampling data is a limiting factor, a sequential sampling procedure can be used to sample only the minimum number of observations required. Sequential sampling procedures will also be briefly discussed in this chapter, with an emphasis on a sequential procedure derived to train a classifier that would yield a predetermined rate of misclassification. The sequential procedure discussed was originally tested only with one method of classification, however, different methods of classification are presented and discussed in this chapter.

1.1 Fixed-sample size methods and Stein's two-stage sampling method

In most scenarios the sample size needed to train a classifier or derive a sample estimate for some unknown parameter, can be calculated theoretically by specifying an allowed level of error between the obtained parameter estimate and the actual population's value and a level of confidence associated with the estimate. Prescribing the power of the test may also be used to determine the sample size needed.



$1.1.\ FIXED\text{-}SAMPLE\ SIZE\ METHODS\ AND\ STEIN'S\ TWO\text{-}STAGE\ SAMPLING\ METHOD$

Assuming that there is a random sample of size n generated from a $N(\mu, \sigma^2)$ distribution, $X \sim N(\mu, \sigma^2)$ with σ^2 known, a $100(1-\alpha)\%$ confidence interval for the unknown population mean μ is given by

$$\left(\overline{x} - z_{1-\frac{\alpha}{2}} \frac{\sigma}{\sqrt{n}}; \ \overline{x} + z_{1-\frac{\alpha}{2}} \frac{\sigma}{\sqrt{n}}\right)$$

where \overline{x} is the sample estimate for μ , $z_{1-\frac{\alpha}{2}}$ is the 100 $\left(1-\frac{\alpha}{2}\right)^{th}$ percentile of the standard normal distribution and n is the sample size required. Solving for n in the equation would yield the sample size needed, for a given value of α , to obtain a confidence interval of half-width $z_{1-\frac{\alpha}{2}}\frac{\sigma}{\sqrt{n}}$.

If the value of σ is not known, there is no fixed-sample size procedure that can be used to derive a $100 (1 - \alpha) \%$ confidence interval for the population mean μ . Stein (1945) proposed a two stage sampling method that addresses this by drawing two samples sequentially. The first sample is used to estimate σ , which in turn is used to calculate the required sample size needed for a particular level of accuracy, and the second sample comprises the remaining observations of the total sample required.

Stein (1945) states that it was proven by Dantzig (1940) that there was no fixed sample-size test for Student's Hypothesis where the power of the test was independent of the variance. Stein (1945) proposed a two-sample test to test the null-hypothesis $H_0: \mu = \mu_0$, where the power of the test is only dependent on $\mu - \mu_0$ and not on σ^2 . In this context, Stein (1945) defines x_i , i = 1, 2, ... to be a series of independent observations from a $N(\mu, \sigma^2)$ distribution.

For $n \geq 2$ the sample variance is defined as $s_n^2 = \frac{\sum_1^n (x_i - \overline{x}_n)^2}{n-1}$. In the first stage of Stein's sampling method, an initial sample of size n_0 is randomly selected and the sample variance $s_{n_0}^2$ is calculated. This serves as an estimate for the population variance. Once the population variance has been estimated with $s_{n_0}^2$, the second stage of Stein's sampling method estimates the required sample size as

$$N = \max \left\{ n_0, \left[\frac{\left(t_{1 - \frac{\alpha}{2}, n_0 - 1} \right)^2 s_{n_0}^2}{d^2} \right] + 1 \right\}$$

where d is the half-width of the confidence interval and [z] denotes the greatest integer less than z.

In the derivation, Stein (1945) defined the required sample size as

$$n = \max\left\{n_0 + 1, \left\lceil \frac{s_{n_0}^2}{\varpi} \right\rceil + 1\right\}$$



$1.1.\ FIXED\text{-}SAMPLE\ SIZE\ METHODS\ AND\ STEIN'S\ TWO\text{-}STAGE\ SAMPLING\ METHOD$

and the statistic

$$t' = \frac{\sum_{1}^{n} a_{i} x_{i} - \mu_{0}}{\sqrt{\overline{\omega}}} = \frac{\sum_{1}^{n} a_{i} (x_{i} - \mu)}{\sqrt{\overline{\omega}}} + \frac{\mu - \mu_{0}}{\sqrt{\overline{\omega}}}$$
$$= u + \frac{\mu - \mu_{0}}{\sqrt{\overline{\omega}}}$$

where ϖ is a predefined positive constant and $a_1, ..., a_n$ is a series of real numbers chosen in such a manner that

$$\sum_{1}^{n} a_{i} = 1$$
and
$$s^{2} \sum_{1}^{n} a_{i}^{2} = \varpi$$

u then has a t-distribution with $n_0 - 1$ degrees of freedom. The optimal selection of a and ϖ will not be discussed as it falls outside the scope of this dissertation.

Stein (1945) defines the random variable $t_{n_0-1} = y/s$ as a normally distributed random variable with mean 0 and variance σ^2 , and states that the random variable $(n_0 - 1) s^2/\sigma^2$ has a $\chi^2_{n_0-1}$ distribution. Furthermore, the conditional distribution of u, provided s, is $N\left(0, \frac{\sigma^2}{s^2}\right)$ and both t_{n_0-1} and u have the same distribution. This theorem is then used by Stein (1945) to derive an unbiased test for $H_0: \mu = \mu_0$ where the power of the test is independent of σ^2 . Stein (1945) notes that using the proposed tests and confidence intervals result in too many required observations to ensure that the power of the test or the confidence intervals are truly independent of σ^2 .

This fact then induced Stein (1945) to redefine the required sample size as

$$n = \max \left\{ n_0, \left\lceil \frac{s_{n_0}^2}{\varpi} \right\rceil + 1 \right\}$$

and the statistic t'' as

$$t'' = \frac{\left(\frac{1}{n}\sum_{1}^{n} x_{i} - \mu_{0}\right)\sqrt{n}}{s}$$

$$= \frac{\frac{1}{n}\sum_{1}^{n} (x_{i} - \mu)}{s}\sqrt{n} + \frac{\mu - \mu_{0}}{s}\sqrt{n}$$

$$= u' + \frac{\mu - \mu_{0}}{s}\sqrt{n}$$

It is proven that u' has a t-distribution with $n_0 - 1$ degrees of freedom.



1.2. SEQUENTIAL SAMPLING METHODS

Assuming that

$$n = \max\left\{n_0 + 1, \left[\frac{s_{n_0}^2}{\varpi}\right] + 1\right\}$$

Stein (1945) concluded that $n \geq s^2/\varpi$, leading to

$$\left| \frac{\mu - \mu_0}{s} \sqrt{n} \right| \ge \left| \frac{\mu - \mu_0}{\sqrt{\overline{\omega}}} \right|$$

Therefore, if $|t''| > t_{1-\frac{\alpha}{2},n_0-1}$ or $t'' > t_{1-\alpha,n_0-1}$ the power of the test will always be increased.

A confidence interval for the population mean μ is then provided by

$$\left(\overline{x} - \frac{l}{2}, \ \overline{x} + \frac{l}{2}\right)$$

where the probability that the true mean μ is covered is a function of σ , however, it is always larger than $1 - \alpha$ with only a minor difference from $1 - \alpha$ if $\sigma^2 > n \frac{d^2}{\left(t_{1-\frac{\alpha}{2},n_0-1}\right)^2}$.

In this context l is defined as

$$l = \frac{2\sigma t_{1-\frac{\alpha}{2},n_0-1}}{\sqrt{E(n)}}$$

Since $s_{n_0}^2$ is an estimate of the population variance, the value of N derived is also an estimate. Therefore, there is a level of dependency between the two samples taken in the two stages. Mukhopadhyay (1980) notes that "Stein's procedure is not 'asymptotically efficient'". As cited by Mukhopadhyay (1980), Chow and Robbins (1965) and Ray (1957) proposed a rule that would address the asymptotic inefficiency, resulting in the new estimate for N as:

$$N = \inf \left\{ n : n \ge n_0 \text{ and } n \ge \frac{a^2 s_n^2}{d^2} \right\}$$

where a is such that $\Phi(a) = 1 - \frac{\alpha}{2}$.

1.2 Sequential sampling methods

Sequential sampling is a sampling technique where no predetermined sample size is specified. Observations are either sampled individually or in groups, and after each single or group of observations has been randomly sampled, the researcher's study is conducted and the pre-defined stopping rule or hypothesis is evaluated. Depending on the outcome, another observation or group of observations might need to be sampled and the relevant rules and tests are again evaluated and conducted.



In certain scenarios, the cost associated with sampling observations can be severe, and a researcher might wish to sample the minimum number of observations possible while still being able to make the best informed decision at a prescribed level of accuracy. The greatest benefit, perhaps, of sequentially sampling observations is the impact it has on the study's cost - both financial and time. Sampling fewer observations will have a direct impact on the financial cost of a study. If the process of sampling observations is laborious, a sequential procedure can significantly reduce the amount of time required to obtain enough information for a sound decision to be made.

Fu et al. (2005) proposed a sequential approach to determine the sample size needed to build a classifier. The object of the article was to derive stopping criteria for a sequential procedure so that, with a probability of at least $100 (1 - \alpha) \%$, the classifier obtained would yield a probability of a misclassification less than or equal to ε . Therefore, the approach seeks to find the minimum number of observations needed for training a classifier in such a way that there is a high probability, $100 (1 - \alpha) \%$, that the probability of the next sampled observation being misclassified is acceptably low, ε .

In this dissertation, the sequential procedure proposed by Fu et al. (2005) will be discussed and the shortcomings of the procedure will be examined. An alternative sequential procedure, addressing the largest shortcoming of the sequential procedure proposed by Fu et al. (2005), is proposed and will be discussed.

1.3 Methods of classification

Classification entails the identification of which group a new observation should be assigned to, based on a number of observed attributes. A separate training dataset, whose observations and corresponding classes are known, is used to derive criteria for the allocation of random observations to any particular class. The attributes, used for assigning an observation to a particular class, can be categorical (blood type or hair colour), ordinal ("High", "Average" or "Low"), integer-valued (the number of people who own dogs) or real valued (a person's height). To group any observation into a specific group, a rule or function is required that will take the inherent information contained in the attributes into account and assign the observation into the correct predefined group. The function is known as the classifier.

Fu et al. (2005) chose to use linear discriminant analysis (LDA) as the classifier in the simulation studies, stating that the sequential procedure is independent of the classifier. For the purposes of this dissertation, LDA, quadratic discriminant analysis (QDA), K-nearest neighbours (KNN) and linear regression of an indicator matrix (LRIM) were



tested. It stands to reason that a classifier that is performing well, or alternatively more efficiently, will on average stop retraining the classifier quicker as the stopping criteria will be met earlier. In the particular case where the predictor takes on values in a discrete set (i.e. the predictor can be any of a list of discrete values), the input space can be divided into regions depending on the classification. A decision boundary is a partition or hypersurface in p-dimensional vector space that divides the vector space into two or more response regions. Depending on which classification method is used, the decision boundaries between the regions can either be smooth (as is the case with a linear decision boundary for example) or rough (as is the case with a decision boundary like K-nearest neighbours). A brief summary of the underlying theory for each of the above mentioned classification procedures follows to familiarise the reader with the methods proposed.

1.3.1 Linear discriminant analysis (LDA)

Linear discriminant analysis is a popular method used for classification. From statistical decision theory, it is known that the optimal classification can be obtained if the class posteriors are known, i.e. if $P(class\ G|X=x)$ is known. If $f_k(x)$ is the class-conditional density of X for class G=k, the prior probability of class k is denoted by π_k and $\Sigma_{k=1}^K \pi_k = 1$, where K is the total number of classes, using the Bayes Theorem the class posterior for class k can be written as:

$$P(G = k|X = \underline{x}) = \frac{f_k(\underline{x})\pi_k}{\sum_{l=1}^K f_l(\underline{x})\pi_l}$$

If each class density is then modelled as a multivariate Gaussian, the density function of class k is given by:

$$f_k(\underline{x}) = \frac{1}{(2\pi)^{p/2} |\boldsymbol{\Sigma}_k|^{1/2}} e^{-\frac{1}{2} \left(\underline{x} - \underline{\mu}_k\right)^T \boldsymbol{\Sigma}_k^{-1} \left(\underline{x} - \underline{\mu}_k\right)}$$

where $\underline{\mu}_k$ is a $p \times 1$ matrix that denotes the population mean for class k, Σ_k is a $p \times p$ matrix denoting the population covariance matrix for class k, \underline{v}^T denotes the transpose of \underline{v} and \underline{x} is a p-dimensional row vector.

LDA considers the specific case where all the classes have a common covariance matrix $\Sigma_k = \Sigma \forall k$.



Hastie, Tibshirani and Friedman (2001) note that looking at the log ratio of the class posteriors is sufficient for comparing any two classes, k and l. Therefore the following holds:

$$\log \frac{P\left(G = k | X = \underline{x}\right)}{P\left(G = l | X = \underline{x}\right)} = \log \frac{\frac{f_{k}(\underline{x})\pi_{k}}{\sum_{j=1}^{K} f_{j}(\underline{x})\pi_{j}}}{\frac{f_{k}(\underline{x})\pi_{l}}{\sum_{j=1}^{K} f_{j}(\underline{x})\pi_{j}}}$$

$$= \log \left(\frac{\pi_{k}}{\pi_{l}}\right) - \frac{1}{2}\left(\underline{\mu}_{k} + \underline{\mu}_{l}\right)^{T} \mathbf{\Sigma}^{-1}\left(\underline{\mu}_{k} - \underline{\mu}_{l}\right) + \underline{x}^{T} \mathbf{\Sigma}^{-1}\left(\underline{\mu}_{k} - \underline{\mu}_{l}\right)$$

which is a linear equation in x. The linear discriminant functions can be defined as:

$$\delta_k \left(\underline{x} \right) = \underline{x}^T \mathbf{\Sigma}^{-1} \underline{\mu}_k - \frac{1}{2} \underline{\mu}_k^T \mathbf{\Sigma}^{-1} \underline{\mu}_k + \log \pi_k$$

If the parameters are not known, sample estimates for $\underline{\pi}_k$, $\underline{\mu}_k$ and Σ can be used. Therefore, if N_k is the total number of observations sampled from class k, the parameters can be estimated as:

1.
$$\widehat{\pi}_k = \frac{N_k}{\sum_{l=1}^K N_l}$$

2.
$$\underline{\widehat{\mu}}_k = \frac{\Sigma_{x \in k} \underline{x}}{N_k}$$

3.
$$\widehat{\Sigma} = \sum_{k=1}^{K} \sum_{x \in k} (\underline{x} - \widehat{\underline{\mu}}_k) (\underline{x} - \widehat{\underline{\mu}}_k)^T / (N - K)$$

as defined in Hastie, Tibshirani and Friedman (2001).

When comparing two classes, say k and l, an observation would be classified as a member of l if $\delta_l(\underline{x}) > \delta_k(\underline{x})$. A complete derivation of the linear discriminant function and the decision boundary between any two classes is provided in Appendix A.

1.3.2 Quadratic discriminant analysis (QDA)

One of the assumptions of LDA is $\Sigma_k = \Sigma \forall k$. However, if this is not the case, the discriminant functions are no longer linear as many of the factors no longer cancel in the derivations, and the resulting discriminant functions are quadratic. This leads to quadratic discriminant analysis. Again looking at the log ratio of the class posteriors, the following results:

$$\log \frac{P\left(G = k | X = \underline{x}\right)}{P\left(G = l | X = \underline{x}\right)} = \log \frac{f_k(\underline{x})\pi_k}{f_l(\underline{x})\pi_l}$$

$$= \left(\log \pi_k - \frac{1}{2}\log |\mathbf{\Sigma}_k| - \frac{1}{2}\left(\underline{x} - \underline{\mu}_k\right)^T \mathbf{\Sigma}_k^{-1}\left(\underline{x} - \underline{\mu}_k\right)\right)$$

$$- \left(\log \pi_l - \frac{1}{2}\log |\mathbf{\Sigma}_l| - \frac{1}{2}\left(\underline{x} - \underline{\mu}_l\right)^T \mathbf{\Sigma}_l^{-1}\left(\underline{x} - \underline{\mu}_l\right)\right)$$



leading to the quadratic discriminant functions:

$$\delta_k\left(\underline{x}\right) = \log \pi_k - \frac{1}{2}\log |\mathbf{\Sigma}_k| - \frac{1}{2}\left(\underline{x} - \underline{\mu}_k\right)^T \mathbf{\Sigma}_k^{-1} \left(\underline{x} - \underline{\mu}_k\right)$$

In general the estimates derived from QDA should be similar and slightly better than those obtained using LDA, with the only real difference being that separate covariance matrices need to be estimated for each class. If the number of dimensions p in R^p is large the number of parameters can increase substantially. If the necessary parameters are not known, sample estimates for π_k , μ_k and Σ_k can again be used.

Therefore:

1.
$$\widehat{\pi}_k = \frac{N_k}{\sum_{l=1}^K N_l}$$

$$2. \ \widehat{\underline{\mu}}_k = \frac{\Sigma_{x \in k} \underline{x}}{N_k}$$

3.
$$\widehat{\Sigma}_k = \sum_{x \in k} (\underline{x} - \widehat{\mu}_k) (\underline{x} - \widehat{\mu}_k)^T / (N - 1)$$

When comparing two classes, say k and l, an observation would be classified as a member of l if $\delta_l(\underline{x}) > \delta_k(\underline{x})$. A complete derivation of the quadratic discriminant function and the decision boundary between any two classes is provided in Appendix B.

1.3.3 K-nearest neighbours (KNN)

K-nearest neighbours is an intuitively simple classification method that uses the K observations in the training set nearest to the input observation to derive the classifier \widehat{Y} . Nearest in this case implies some form of a distance metric and it is usually assumed to be Euclidean distance. The Euclidean distance between two vectors \underline{a} and \underline{b} is defined as:

$$d(\underline{a},\underline{b}) = \sqrt{(b_1 - a_1)^2 + \dots + (b_p - a_p)^2} = \sqrt{(\underline{b} - \underline{a}) \bullet (\underline{b} - \underline{a})} = ||\underline{a} - \underline{b}||$$

If the set \mathcal{N} is defined to be the K observations nearest to the input vector, based on the chosen distance metric, the K-nearest neighbour classifier is defined as:

$$\widehat{Y} = \frac{1}{K} \Sigma_{y_i \in \mathcal{N}} y_i$$

In the case where the y_i 's are binary observations (i.e. $y_i \in \{0,1\}$), $0 \le \widehat{Y} \le 1$. If $\widehat{Y} < 0.5$ the observation would be classified as a 0, otherwise if $\widehat{Y} \ge 0.5$ the observation would be classified as a 1. This is equivalent to taking a "majority vote" of the response variable for the K observations in \mathcal{N} .

Smaller values of K yield a localised classifier, usually leading to smaller misclassification error. However, this can lead to very irregular or rough decision boundaries.



1.3.4 Linear regression of an indicator matrix (LRIM)

In Simple linear regression, the aim is to derive a linear function that models the relationship between the dependent variable and the independent variable(s), whilst minimising the total sum of squared errors. Assuming that the relationship between the dependent variable and the independent variables is linear, and the elements of \underline{Y} are independent $N(\beta_0 + \beta_1 x_{i1} + ... + \beta_p x_{ip}, \sigma^2)$ distributed, the following holds: $E[\underline{y}] = \mathbf{X}^T \underline{\beta}$, where \mathbf{X}^T denotes a $N \times (p+1)$ matrix consisting of N rows denoting the p-dimensional input observations. The first column of \mathbf{X}^T is entirely populated with 1's, corresponding to a dummy variable for the intercept. $\underline{\beta} = (\beta_0, \beta_1,, \beta_p)$ is a $(p+1) \times 1$ matrix, β_0 denoting the intercept and $\beta_1, ..., \beta_p$ denoting the coefficients of the p input variables. If the error term \underline{e} is defined as $\underline{e} = \underline{y} - \mathbf{X}\underline{\beta}$, the minimum sum of squared errors is obtained for $\widehat{\beta} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^Ty$. A complete derivation of this is provided in Appendix C.

In the case where the response variable can be an element of any one of a multiple of G classes, \mathbf{Y} is defined as a $n \times G$ matrix with each column populated either with a 1 (if the response variable is an element of that respective class) or a zero. Each observation of the response variable can be an element of only one class. In this case, the $(p+1) \times G$ parameter matrix is defined as $\widehat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$. Any new observation is classified to the class corresponding to the largest value of $\underline{y}_{new} = \underline{x}\widehat{\beta}$, which is equivalent to the column of \underline{y}_{new} with the largest value.



Chapter 2

A sequential procedure to attain a predetermined probability of a future misclassification

2.1 Introduction

In this chapter a sequential procedure, that ultimately samples the minimum number of observations required to train a classifier that attains a predetermined probability of misclassifying the next sampled observation, will be discussed. Fu et al. (2005) proposed a procedure that sequentially samples an observation, classifies the observation accordingly, and then evaluates the stopping criteria proposed. The stopping criteria depends on a theorem derived using Martingale Limit Theory and, when satisfied, yields a classifier that, with a probability of at least $100 (1 - \alpha) \%$, has a maximum probability ε of misclassifying the next observation sampled. A series of simulations were run to observe the sequential procedure's performance. Various classification methods were tested (LDA, QDA, KNN and LRIM) as well as the effect of changing one of the underlying distributions' variance for all classification methods. The effect of a change in other input parameters was also tested using LDA, as well as the sequential procedure's predictive ability on a microarray dataset. Furthermore, shortcomings of the sequential procedure are discussed and a general conclusion is provided.

2.2 Sequential procedure

In formulating the stopping rule, Fu et al. (2005) defined $\mathcal{Y}_i = \{Y_1, ..., Y_i\}, i = 1, 2, 3,$ to be a set of independent and uncorrelated binary observations; Q_i to be an indicator function that Y_i is misclassified based on the i-1 previous observations, i.e. $Q_i = 1$ if Y_i is misclassified and 0 otherwise; and $\pi_i = P(Q_i = 1 | \mathcal{Y}_{i-1})$, or the conditional probability of misclassifying observation Y_i provided the prior i-1 results are known.





In the derivation of their stopping rule, two assumptions are made:

- π_n is weakly monotonically decreasing. Therefore, $\pi_{n+j} \leq \pi_n \ \forall \ j \geq n, \ j \geq 1$; i.e. as the number of observations available for classifier training increases, the conditional probability of a misclassification will either decrease, or remain constant. π_n will therefore converge weakly towards $\pi_\infty \geq 0$ as $n \to \infty$.
- $\pi_{\infty} > 0$. Therefore, a positive probability of misclassification exists. For a given classification problem with a non-zero Bayes error, the probability $\pi_{\infty} > 0$ regardless of the type of classifier.

In a scenario where there is a non-zero Bayes error, no trained classifier should be able to perform better and achieve a rate of error lower than the Bayes error. In this context, if the Bayes error is denoted by π_{Bayes} then $\pi_{\infty} \geq \pi_{Bayes}$.

The stopping rule proposed by Fu et al. (2005) depends on a theorem derived in Fu et al. (2005). Theorem 1, as provided below, depends on the Martingale Central Limit Theorem. Theorem 1 will not be derived or expatiated in this dissertation, but is provided for reference purposes to the reader.

Theorem 1 For $0 < \alpha < 1$

$$P(\pi_N \leq N^{-1} \Sigma_{i=1}^N Q_i + z_{1-\alpha} \widehat{\kappa}_N / N^{1/2}) \to 1 - \alpha \text{ as } N \to \infty$$
 where $z_{1-\alpha}$ is the $(1-\alpha)$ quantile of the standard normal distribution $N(0,1)$.

$$\widehat{\kappa}_N = N^{-1} \sum_{i=1}^N \widehat{\pi}_i (1 - \widehat{\pi}_i)$$
and
$$\widehat{\pi}_i = i^{-1} \sum_{j=1}^i Q_j$$

 $\hat{\pi}_i$ is an estimator for the conditional probability of a misclassification, π_i , as it is the proportion of observations that have been misclassified from the *i* observations sampled.



Theorem 1 seeks to minimise the sample size needed to obtain $P(\pi_N \leq \varepsilon) \geq 1 - \alpha$. Setting

$$\varepsilon = N^{-1} \sum_{i=1}^{N} Q_i + z_{1-\alpha} \widehat{\kappa}_N / N^{1/2}$$

$$\Rightarrow \varepsilon - N^{-1} \sum_{i=1}^{N} Q_i = z_{1-\alpha} \widehat{\kappa}_N / N^{1/2}$$

$$\Rightarrow \frac{z_{1-\alpha} \widehat{\kappa}_N}{\varepsilon - N^{-1} \sum_{i=1}^{N} Q_i} = N^{1/2}$$

$$\Rightarrow N = \left(\frac{z_{1-\alpha} \widehat{\kappa}_N}{\varepsilon - N^{-1} \sum_{i=1}^{N} Q_i}\right)^2$$

with $\varepsilon > N^{-1} \sum_{i=1}^{N} Q_i$ and $\widehat{\kappa}_N > 0$.

An additional rule is provided by Fu et al. (2005) to stop the sequential procedure should a large number (N_0) of consecutive correct classifications occur. This would typically be the case if the classifier is performing admirably, or if there are very large Bayes errors. Bayes errors larger than the specified acceptable level of error, ε , result in the sequential procedure continuing ad infinitum. In both cases it is better to induce an early stop to the procedure, as this will save processing time and more importantly, resources. Fu et al. (2005) suggested $N_0 = \log(\alpha)/\{\log(1-\varepsilon)\}$ be used as a limit to stop the sequential procedure should N_0 consecutive perfect classifications occur.

The number of required sequential observations in the stopping rule therefore is:

$$N \ge \min \left\{ \left(\frac{z_{1-\alpha} \widehat{\kappa}_N}{\varepsilon - N^{-1} \sum_{i=1}^N Q_i} \right)^2, N_0 \right\} \text{ where } 0 < N^{-1} \sum_{i=1}^N Q_i < \varepsilon \text{ and } \widehat{\kappa}_N > 0$$

Assume now that the requirement for $\widehat{\kappa}_N > 0$ was not present. If any number of consecutive perfect classifications occur from the first observation sampled in the sequential procedure, $\widehat{\pi}_i$ would be equal to 0, resulting in $\widehat{\kappa}_N$ equalling 0. If $\widehat{\kappa}_N = 0$ then $\left(\frac{z_{1-\alpha}\widehat{\kappa}_N}{\varepsilon-N^{-1}\sum_{i=1}^N Q_i}\right)^2 = 0$ and the stopping rule would simplify to $N \ge \min\{0, N_0\}$. Therefore, the sequential procedure would stop at the very first observation sampled if that observation were correctly classified. The same would occur if no observations were correctly classified - $\widehat{\pi}_i$ would equal 1, resulting in $\widehat{\kappa}_N$ equalling 0. If no observations were correctly classified the stopping criteria would also not evaluate against N_0 .



Consequently, the stopping criteria is dependent on two factors:

- Firstly, there must be at least one correct classification. This holds for both parts of the rule (i.e. N_0 and $\left(\frac{z_{1-\alpha}\widehat{\kappa}_N}{\varepsilon-N^{-1}\sum_{i=1}^N Q_i}\right)^2$)
- Secondly, the first parameter in the rule $\left(\left(\frac{z_{1-\alpha}\widehat{\kappa}_N}{\varepsilon-N^{-1}\sum_{i=1}^NQ_i}\right)^2\right)$ depends on at least one incorrect classification.

If $\varepsilon = 0$, the $N_0 = \log(\alpha)/\{\log(1 - \varepsilon)\}$ equality would not be defined. It is also required that $\varepsilon > N^{-1}\sum_{i=1}^{N}Q_i$. This would be the case only if there is at least one correct classification.

Taking the above into consideration, suggests that the stopping criteria should be slightly amended to reflect these rules. The following is therefore proposed for ease of reference:

• If $\max(\underline{Q}) = 1$ and $\min(\underline{Q}) = 0$ (i.e. there are both correct and incorrect classifications) the number of sequential observations in the stopping rule is

$$N \ge \min \left\{ \left(\frac{z_{1-\alpha} \widehat{\kappa}_N}{\varepsilon - N^{-1} \sum_{i=1}^N Q_i} \right)^2, N_0 \right\}$$

• If $\max(\underline{Q}) = 0$ (i.e. there are no incorrect classifications) the number of sequential observations in the stopping rule is $N \geq N_0$

If $\min(\underline{Q}) = 1$ (i.e. there are no correct classifications) the sequential procedure will continue ad infinitum as the classifier has not been successfully trained. If, however, a maximum sample size is specified, the sequential procedure can at least be stopped. Therefore,

• If $\min(\underline{Q}) = 1$ (i.e. there are no correct classifications) the number of sequential observations in the stopping rule is N = M, where M is a selected maximum sample size.

Fu et al. (2005) defined M to be the maximum allowed number of sequential observations sampled. It is important to note that this is an artificial upper bound on the number of observations available for sampling. The following sequential procedure, as defined by Fu et al. (2005), can be used to determine the minimum number of observations needed to train the classifier and to obtain the final trained classifier:

An initial sample of size S_0 is chosen and the variable N_0 , denoting the number of consecutive correct classifications, is set to 0. At the i^{th} step of the sequential procedure,



the particular chosen classifier is trained. An additional observation is randomly and independently sampled and classified using the trained classifier. If a successful classification was observed, Q_i is set to 0 and N_0 is set equal to $N_0 + 1$. Alternatively, if the classification was incorrect Q_i is set to 1 and N_0 is set equal to 0. $\hat{\kappa}_i$ is now calculated using the observed values of Q. Depending on which of the stopping rules are applicable, the respective rule is evaluated, and if the rule is satisfied then the procedure is stopped. If the selected maximum sample size (M) has not yet been reached, another observation should be randomly sampled and the process of training the classifier, classifying the sampled observation and evaluating the applicable stopping rule, should be repeated. If, however, a stopping rule has not yet been satisfied and the number of observations chosen (N) is equal to the maximum number of predefined observations (M), the procedure should also be stopped. The sequential procedure can be summarised as follows:

- 1. Start with the initial sample S_0 and set $N_0 = 0$.
- 2. At the i^{th} step, train the classifier using all observations available.
- 3. Randomly sample a new observation and classify the observation using the classifier trained in step 2.
- 4. If a correct classification is observed, set $Q_i = 0$ and $N_0 = N_0 + 1$. Otherwise, set $Q_i = 1$ and $N_0 = 0$.
- 5. Calculate $\widehat{\pi}_i$ and $\widehat{\kappa}_N$.
- 6. Evaluate the stopping criteria and if any of the stopping criteria is met, or if N = M, stop the recursive procedure. If this is not the case, return to step 2 and repeat steps 2 to 6.

It is important to note that the number of sequential steps in training the classifier is reported, as was done by Fu et al. (2005). This is different to the number of observations needed to train the classifier, as the number of sequential steps do not include the initial sample S_0 .



2.3 Simulation study

A series of simulations were run to observe the sequential procedure's performance by comparing the observed misclassification rate of the trained classifier with the theoretical error, i.e. the Bayes error. The minimum possible error, or the Bayes error, depends on the underlying distributions of the data, the associated parameters of these distributions, and the respective probabilities of drawing a random observation from each respective distribution.

For the simulations however, the underlying distributions and their respective parameters can be specified, and the probability to select a random observation from each distribution is a function of the initial random sample size of each distribution. The trained classifier can then be used to classify observations in a hold-out sample, and the observed error rate can be compared to the Bayes error. A classifier that is performing well will tend to the Bayes error. Therefore, testing the different classification methods, as well as the effect that a change in the underlying distributions' parameters have, should highlight some of the benefits of using a specific classification method (such as the stopping criteria being satisfied quicker, smaller observed misclassification rates or more/less sensitivity to a shift in the underlying distributions) or possible flaws of the sequential procedure. A classifier that is performing well is expected to satisfy the stopping criteria quicker, or alternatively should yield lower rates of misclassification.

2.3.1 Bayes error

The Bayes error rate is the lowest achievable error rate for any given classifier. Consider a scenario where data is generated from two different overlapping independent normal distributions. The Bayes error is the probability of a misclassification, i.e. the sum of the probabilities to misclassify an observation as being an element from one distribution when, in fact, it is from the other. To calculate the Bayes error, assume a random sample is generated from a $N(\mu_1, \sigma_1^2)$ distribution with probability p, and another random sample is generated from a $N(\mu_2, \sigma_2^2)$ distribution with probability (1-p). Assume the classifier is denoted by λ . The probability of a misclassification is then calculated as:

$$\begin{aligned} \text{Bayes error} &= (1-p)P[X \leq \lambda | X \sim N(\mu_2, \sigma_2^2)] + pP[X > \lambda | X \sim N(\mu_1, \sigma_1^2)] \\ &= (1-p)P\left[Z \leq \frac{\lambda - \mu_2}{\sqrt{\sigma_2^2}}\right] + pP\left[Z > \frac{\lambda - \mu_1}{\sqrt{\sigma_1^2}}\right] \\ &= (1-p)\Phi\left(\frac{\lambda - \mu_2}{\sqrt{\sigma_2^2}}\right) + p\left(1 - \Phi\left(\frac{\lambda - \mu_1}{\sqrt{\sigma_1^2}}\right)\right) \end{aligned}$$



Consider the case of equal probability of selection, then ...

Bayes error
$$= (1-p)\Phi\left(\frac{\lambda-\mu_2}{\sqrt{\sigma_2^2}}\right) + p\left(1-\Phi\left(\frac{\lambda-\mu_1}{\sqrt{\sigma_1^2}}\right)\right)$$
$$= \frac{1}{2}\left[\Phi\left(\frac{\lambda-\mu_2}{\sqrt{\sigma_2^2}}\right) + \left(1-\Phi\left(\frac{\lambda-\mu_1}{\sqrt{\sigma_1^2}}\right)\right)\right]$$

Consider the case where $\mu_1=0,\,\mu_2=\Delta,\,\sigma_1^2=1,\,\sigma_2^2=1.$

$$\begin{aligned} \text{Bayes error} &= \frac{1}{2} \left[\Phi \left(\frac{\lambda - \mu_2}{\sqrt{\sigma_2^2}} \right) + \left(1 - \Phi \left(\frac{\lambda - \mu_1}{\sqrt{\sigma_1^2}} \right) \right) \right] \\ &= \frac{1}{2} \left[\Phi \left(\frac{\lambda - \Delta}{\sqrt{1}} \right) + \left(1 - \Phi \left(\frac{\lambda}{\sqrt{1}} \right) \right) \right] \\ &= \frac{1}{2} [\Phi(\lambda - \Delta) + (1 - \Phi(\lambda))] \end{aligned}$$

Consider the case where $\lambda = \frac{\Delta}{2}$.

Bayes error
$$= \frac{1}{2} \left[\Phi(\lambda - \Delta) + (1 - \Phi(\lambda)) \right]$$
$$= \frac{1}{2} \left[\Phi\left(-\frac{\Delta}{2}\right) + \left(1 - \Phi\left(\frac{\Delta}{2}\right)\right) \right]$$
$$= \frac{1}{2} \left[\left(1 - \Phi\left(\frac{\Delta}{2}\right)\right) + \left(1 - \Phi\left(\frac{\Delta}{2}\right)\right) \right]$$
$$= 1 - \Phi\left(\frac{\Delta}{2}\right)$$



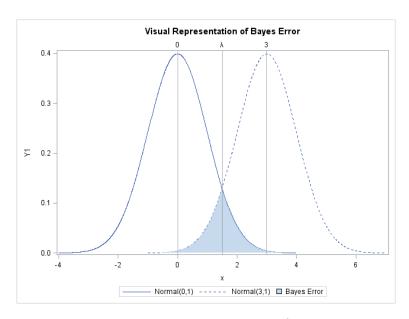


Figure 2.1: Visual Representation of Bayes error

Figure 2.1 provides a visual representation of two normal distributions with unit variance, one centered at 0 and the other centered at 3. If λ is considered to be the classifier, an observation from the N(3,1) distribution would be misclassified if it were smaller or equal to λ , and an observation from the N(0,1) distribution would be misclassified if it were larger than λ .

In this particular case the Bayes error is calculated as follows:

Bayes error =
$$P[X \le \lambda | X \sim N(3,1)] (1-p) +$$

 $P[X > \lambda | X \sim N(0,1)]p$
= $0.5\Phi(\lambda - 3) + 0.5(1 - \Phi(\lambda))$
= $1 - \Phi(1.5)$
= 0.06681

2.3.2 Simulation design

For this particular series of simulations, 5 observations were generated from a $N(\mu_1, \sigma_1^2)$ distribution and 5 observations were generated from a $N(\Delta, \sigma_2^2)$ distribution, with probabilities $\hat{p}_1 = \frac{n_1}{n_1 + n_2} = 0.5$ and $\hat{p}_2 = 0.5$ respectively. For each simulation the effect of a shift in the underlying distributions is tested, and therefore $\Delta \in \{1, 1.3, 1.5, 2, 2.3, 2.5, 3, 4\}$. A change in the allowed level of error, ε , is also tested and therefore $\varepsilon \in \{0.05, 0.10, 0.15, 0.20\}$. The maximum allowed number of sequential steps is set to M = 90 and M = 40 respectively. To keep track of the number of consecutive correct or perfect classifications, a count variable, denoted N_0 , is set equal to 0. In the case of LDA, QDA and LRIM, the initial 10 observations are then used to train the initial classifier $\hat{\lambda}$.



Note that the same simulation design as that employed in Fu et al. (2005) is used in order for the results to be comparable. The initial sample sizes of 5 and 5 records respectively are the same as employed in Fu et al. (2005).

A single random observation, denoted o_1 in this case, is generated either from a $N(\mu_1, \sigma_1^2)$ distribution with a probability \widehat{p}_1 , or from a $N(\Delta, \sigma_2^2)$ distribution with a probability \hat{p}_2 and is then evaluated against $\hat{\lambda}$. In the specific scenarios where either the LDA or QDA classifier is used, o_1 was generated from the $N(\mu_1, \sigma_1^2)$ distribution and $o_1 > \widehat{\lambda}$, the observation is considered to be misclassified. If, however, $o_1 \leq \widehat{\lambda}$ the observation is considered correctly classified. A similar rule applies if it is assumed that o_1 was generated from a $N(\Delta, \sigma_2^2)$ distribution: if $o_1 \leq \hat{\lambda}$ then the observation is considered to be misclassified, otherwise it is considered to be correctly classified. If the KNN classifier is used, the K observations considered "nearest" to o_1 are used to train the classifier. If o_1 was generated from the $N(\mu_1, \sigma_1^2)$ distribution and $\hat{\lambda} = 0$, or o_1 was generated from the $N(\mu_2, \sigma_2^2)$ distribution and $\hat{\lambda} = 1$ the observation is considered correctly classified. In all other scenarios o_1 would be considered incorrectly classified. When using linear regression of an indicator matrix, o_1 is considered to be correctly classified if the largest value in $o_1\widehat{\beta}$ is in the first column - provided o_1 was generated from the $N(\mu_1, \sigma_1^2)$ distribution. If o_1 was generated from the $N\left(\mu_2,\sigma_2^2\right)$ distribution and the largest value in $o_1\widehat{\beta}$ is in the second column, o_1 is also considered to be correctly classified. In any other scenario the observation is deemed to be incorrectly classified.

Correctly classifying the first observation would result in the perfect-classification variable N_0 being incremented with 1, i.e. setting $N_0 = N_0 + 1$. This would also result in the value of Q_1 being set equal to 0. However, a misclassification would result in setting N_0 equal to 0 and $Q_1 = 1$. Using these variables, $\hat{\kappa}_1$ can be calculated and the stopping rules evaluated. This procedure is continued until N = M or the stopping rules are satisfied.

After each repetition of the simulation was finalised, the final value of $\hat{\lambda}$ was kept in memory and used to classify a random holdout sample to gauge classifier performance and the actual observed error rate. For the holdout sample, 5000 observations were generated from a $N(0, \sigma_1^2)$ distribution and 5000 observations were generated from a $N(\Delta, \sigma_2^2)$ distribution. Depending on the specific classification method used, it was possible to classify the 10000 observations randomly generated accordingly, and the misclassification rate was calculated. The simulations were iterated 1000 times. Afterwards, the average and standard deviation of the observed misclassification rates were calculated, and the minimum, maximum, average and standard deviation of the number of sequential steps required were also calculated.



It is important to note that the method used for classifier testing in this dissertation is different to the method used by Fu et al. (2005). The method used by Fu et al. (2005) is provided below.

"To examine classifier performance, we drew random samples of 10,000 data points, 5000 from N(0,1) and 5000 from $N(\Delta,1)$, and tested the LDA classifier to estimate its cutoff value λ . Thus a data point is categorized as class 0 if less than λ , or class 1 otherwise. We repeated the drawing of random samples 50 times to obtain accurate estimation of λ . The error of the LDA classifier was then calculated with $e(C_N) = \{1 - \Phi(\lambda) + \Phi(\lambda - \Delta)\}/2$ for each fixed value Δ . The sequential training and testing procedure was repeated 1000 times for each fixed pair (Δ, ε) to compare the LDA error with the Bayes error, which was calculated with $\{1 - \Phi(\Delta/2)\}$."

The reason for using a different testing method is that the method used by Fu et al. (2005) does not use the classifier derived using the sequential procedure for testing classifier performance (calculating the misclassification rate). Therefore the misclassification results provided by Fu et al. (2005) do not completely correspond to what would have been achieved by the proposed sequential procedure. Attempts to contact the author of the article for clarification proved unsuccessful.

The purpose of the initial LDA simulation study was, to an extent, to imitate the results obtained by Fu et al. (2005). The original article proved quite vague in certain respects, and comparing the results obtained and provided in this dissertation to those presented by Fu et al. (2005), to an extent, validates the correctness of the coding. Minor differences, however, are expected as the methods for testing the derived classifier are different. The results, however, compare favourably.

Large sections of pages have deliberately been left empty to facilitate reading within a section and to keep the relevant tables and discussions grouped together.

2.3.3 LDA simulation

The purpose of the initial LDA simulation study was to imitate the results obtained by Fu et al. (2005). For the initial simulation study the results can be found in Table 2.3.1 and Table 2.3.2. The results for M = 90 are provided in Table 2.3.1 and Table 2.3.2 provides the results for M = 40.



TABLE 2.3.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.31285 (0.008577) 30; 90 89.94; 1.8974	0.31353 (0.010736) 11; 90 86.211; 16.706	0.31391 (0.012429) 8; 90 77.613; 28.7596	0.3158 (0.015819) 6; 90 64.031; 36.7603
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.26124 (0.006895) 23; 90 89.933; 2.1187	0.26207 (0.008684) 11; 90 81.487; 23.9947	0.26336 (0.011322) 8; 90 67.721; 35.1793	0.26426 (0.013017) 6; 90 50.69; 38.028
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.22982 (0.006442) 21; 90 88.831; 8.6495	0.23049 (0.00771) 11; 90 77.771; 27.8412	0.23177 (0.00996) 8; 90 63.872; 35.8741	0.23356 (0.011494) 6; 90 42.472; 36.4448
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.16116 (0.00541) 21; 90 84.815; 17.6119	0.16267 (0.007501) 11; 90 64.702; 34.6758	0.16441 (0.00912) 8; 90 40.695; 34.5987	0.16733 (0.013879) 6; 90 22.144; 23.7994
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.12746 (0.005157) 21; 90 80.384; 22.864	0.12984 (0.009084) 11; 90 51.86; 35.6802	0.13126 (0.010644) 8; 90 27.003; 26.2447	0.13253 (0.011599) 6; 90 15.99; 15.2084
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.10817 (0.005146) 21; 90 76.252; 25.9617	0.11035 (0.007881) 11; 90 44.843; 33.1998	0.11243 (0.010427) 8; 90 24.203; 22.5269	0.11262 (0.00991) 6; 90 14.495; 12.9519
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.06921 (0.004828) 21; 90 61.15; 30.2236	0.07131 (0.007756) 11; 90 29.956; 23.5537	0.07233 (0.008137) 8; 90 16.907; 11.2557	0.07321 (0.009446) 6; 67 11.783; 5.0827
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.02424 (0.002595) 21; 90 44.574; 18.6972	0.02493 (0.003738) 11; 90 23.972; 8.3582	0.02554 (0.004493) 8; 28 16.261; 4.073	0.02581 (0.00516) 6; 27 12.694; 2.5121

For each value of Δ in Table 2.3.1, specifying a smaller value of ε does not lead to a significant reduction in the average misclassification rate. The maximum absolute reduction of 0.00617 is observed where $\Delta = 2$ and ε decreases from 0.2 to 0.05. This, however, leads to an increase in the average number of steps necessary to train the classifier from 22.144 to 84.815. If it is very costly or takes a very long time to sample additional observations, it would not be practical to specify a small ε .

Note that the maximum number of steps, M, was reached at least once in 29 of the 32 scenarios. This indicates cases where either the procedure did not train the classifier successfully (i.e. the procedure was stopped because N=M and not because the probability of the next observation being misclassified was sufficiently small) or it took 90



sequential steps to ensure that the probability of the next observation being misclassified is sufficiently small.

Large values for the average number of sequential steps indicate that the maximum was reached many times. For $\varepsilon = 0.05$, the average number of sequential steps is larger than 80 for all values of Δ up to 2.3. Even for $\Delta = 2.5$ the average number of steps is still larger than 75. This indicates that M was reached more often than not. For all these cases ($\varepsilon = 0.05$ and $\Delta \leq 3$) the Bayes error is larger than ε . Therefore the sequential procedure is trying to train the classifier to adhere to a maximum error rate ε that is impossible to achieve as it is smaller than the Bayes error, the smallest possible error. To successfully train the classifier with an error rate $\varepsilon = 0.05$, the Bayes error must be smaller than 0.05. This is the case only for a tested $\Delta = 4$. Note that for $\Delta \in \{1, 1.3, 1.5\}$ the values of ε tested were too small as the Bayes error was larger than ε in all cases.

The sequential procedure frequently trains the classifier to obtain a rate of misclassification lower than the specified acceptable error ε . For $\Delta=4$, the Bayes error is lower than ε and the classifier should have been trained to yield a rate of misclassification of at most ε . For all the values of ε tested where $\Delta=4$, the observed rate of misclassification is lower than ε and is closer to the Bayes error. Therefore the sequential procedure has overtrained the classifier and the classifier does not yield a rate of misclassification near ε , but rather near the Bayes error. Overtraining the classifier results in too many observations sampled to derive a classifier that yields the specific rate of misclassification.



TABLE 2.3.2 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.31836 (0.01892) 21; 40 39.883; 1.4083	0.31798 (0.017691) 11; 40 39.07; 4.9693	0.31777 (0.018296) 8; 40 36.24; 9.9424	0.3199 (0.021928) 6; 40 31.856; 13.7534
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.26455 (0.010733) 21; 40 39.879; 1.4479	0.26433 (0.010924) 11; 40 37.412; 7.9402	0.26512 (0.012389) 8; 40 33.072; 12.5064	0.26661 (0.016065) 6; 40 26.845; 15.1226
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.23182 (0.008526) 21; 40 39.82; 1.7206	0.23284 (0.010207) 11; 40 36.06; 9.4627	0.23367 (0.011749) 8; 40 31.002; 13.4306	0.23519 (0.015349) 6; 40 23.204; 14.9484
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.1633 (0.007031) 21; 40 39.184; 3.4983	0.16423 (0.009126) 11; 40 32.098; 11.7571	0.16565 (0.010787) 8; 40 23.712; 13.749	0.16598 (0.011324) 6; 40 17.322; 12.474
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.12908 (0.006612) 21; 40 37.962; 5.2923	0.13059 (0.008686) 11; 40 29.214; 12.4479	0.13182 (0.010737) 8; 40 21.282; 12.6159	0.1332 (0.013106) 6; 40 14.408; 9.8875
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.10958 (0.006624) 21; 40 37.433; 5.7521	0.11071 (0.008069) 11; 40 26.502; 12.1397	0.11222 (0.009899) 8; 40 19.034; 11.6084	0.11296 (0.010682) 6; 40 13.396; 8.5505
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.06985 (0.005286) 21; 40 34.435; 7.2197	0.07113 (0.00717) 11; 40 23.894; 10.6262	0.07234 (0.008239) 8; 40 15.787; 7.5031	0.07235 (0.008693) 6; 40 11.952; 4.6989
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.02438 (0.002865) 21; 40 34.013; 7.0158	0.02511 (0.003857) 11; 40 23.38; 7.1047	0.02558 (0.004484) 8; 40 16.523; 4.1098	0.02622 (0.005359) 6; 27 12.611; 2.6767

Similar to the results seen for M=90 in Table 2.3.1, for small values of ε in Table 2.3.2, the mean misclassification rate does not decrease substantially as ε is decreased and the average number of sequential steps also does not increase substantially as ε is decreased. For larger values of Δ the average misclassification rate decreases more and the average number of sequential steps increases substantially as ε is decreased.

It is interesting to note that the maximum number of sequential steps allowed, M=40, was reached for nearly all combinations of Δ and ε tested. Considering that the maximum M was reached for most combinations of ε and Δ where M=40 and for most of the combinations where M=90 in Table 2.3.1, it seems as if M should be increased to see how well the sequential procedure performs - this could be a case where the chosen M is



just too small. It is also interesting to note that the observed rate of misclassification was again lower than ε for large values of Δ , resulting in an overtrained classifier.

Comparing the results from Table 2.3.1 to Table 2.3.2, the average rate of misclassification is mostly larger when M=40 compared to when M=90. This is mainly because there are less observations available for training the classifier. The differences are very small though, and in some cases the LDA classifier trained for M=40 performs better (has a lower misclassification rate) than the LDA classifier trained for M=90. One example of this is where $\Delta=3$ and $\varepsilon=0.2$.

Various simulations were also conducted where the variance σ_2^2 was allowed to vary $(\sigma_2^2 \in \{2, 3, 4\})$ for both M = 90 and M = 40. The results are provided in Appendix D. Increasing σ_2^2 resulted in an increase in the Bayes error as there is a greater overlap in the underlying distributions. Increasing σ_2^2 resulted in the average misclassification rate increasing. For each value of σ_2^2 tested, however, no significant change in the average rate of misclassification was observed when ε was decreased, and the average number of sequential steps again increases significantly as ε is decreased for large values of Δ . The average number of sequential steps has also increased in nearly all of the scenarios tested, but the standard deviation in the number of sequential steps has decreased mostly for those scenarios where the Bayes error is larger than ε . This indicates that the observations are more clustered around the high average.

Considering that M seems arbitrarily chosen, and no evidence supporting the choice of M was provided by Fu et al. (2005), it should be tested how often the sequential procedure reaches the maximum without actually successfully training the classifier to such an extent that there is a high probability that the probability of the next observation being misclassified is acceptably low. In nearly all of the scenarios tested, the maximum number of allowed sequential steps M was reached at least once. The high averages and low standard deviations in the observed number of sequential steps for some scenarios indicate that the sequential procedure reaches the maximum M often.

2.3.4 QDA simulation

For the initial simulation study done by Fu et al. (2005) the only classification method used was LDA. QDA is a natural extension of LDA and should be investigated. A better, or more efficient, classification method should result in the sequential procedure stopping earlier, due to more correct classifications. This was investigated with the use of the QDA classifier. The results for M=90 are presented in Table 2.3.3 and the results for M=40 are presented in Table 2.3.4.



TABLE 2.3.3 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the QDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.31397 (0.00923) 24; 90 89.871; 2.8839	0.31414 (0.01024) 11; 90 86.851; 15.2427	0.31603 (0.015517) 8; 90 80.946; 25.178	0.31901 (0.021923) 6; 90 66.654; 35.5186
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.26132 (0.006525) 21; 90 89.726; 4.3262	0.26226 (0.008705) 11; 90 84.16; 20.2321	0.26409 (0.012111) 8; 90 72.089; 32.566	0.26769 (0.020528) 6; 90 57.337; 37.0855
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.22973 (0.00644) 21; 90 89.535; 5.545	0.23128 (0.010826) 11; 90 80.467; 25.1086	0.23321 (0.012781) 8; 90 65.884; 35.0633	0.2353 (0.017312) 6; 90 45.707; 36.6818
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.16133 (0.00577) 21; 90 85.455; 16.5387	0.16338 (0.011158) 11; 90 67.449; 33.5311	0.16679 (0.015677) 8; 90 43.151; 34.8855	0.16981 (0.019561) 6; 90 24.382; 25.0485
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.12763 (0.005282) 21; 90 82.003; 21.1957	0.13097 (0.011992) 11; 90 56.117; 35.418	0.13333 (0.01531) 8; 90 31.179; 28.9003	0.13655 (0.018565) 6; 90 17.212; 16.7096
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.10846 (0.005396) 21; 90 78.76; 24	0.11168 (0.011747) 11; 90 47.48; 34.2825	0.11475 (0.016952) 8; 90 24.633; 22.7084	0.11815 (0.022259) 6; 90 14.782; 12.6707
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.07025 (0.006341) 21; 90 65.312; 29.5199	0.07445 (0.014003) 11; 90 30.507; 23.3342	0.07626 (0.015157) 8; 90 17.629; 11.6041	0.07906 (0.021901) 6; 57 11.787; 5.657
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.02649 (0.006099) 21; 90 45.591; 20.4195	0.02836 (0.00919) 11; 84 23.893; 8.8553	0.03023 (0.012759) 8; 59 16.119; 4.6282	0.03255 (0.018398) 6; 28 12.253; 2.9766

Similar to the LDA results, for a given Δ in Table 2.3.3, the mean misclassification rate does not decrease substantially as ε is decreased. The maximum absolute reduction of 0.00969 is observed where $\Delta = 2.5$ and ε decreases from 0.2 to 0.05. This leads to an increase in the average number of steps necessary to train the classifier from 14.782 to 78.76, which is slightly higher than the LDA results. In general the average number of steps needed to train the classifier is slightly higher for the QDA method when compared to the LDA method.

The maximum number of steps, M, was reached at least once in 28 of the 32 scenarios, compared to the 29 times of the LDA classifier. Consider those results where ε is considerably smaller than the Bayes error. The standard deviation of the number of sequential



steps required is smaller for the QDA classifier than it is for the LDA classifier. This indicates a bit less variation in the number of steps observed, and taking into account that the averages are slightly lower for the LDA classifier compared to the QDA classifier, it shows that the QDA classifier tends to reach the maximum number of steps, M, more often than the LDA classifier. This in turn indicates that the LDA classifier satisfies the stopping criteria at an earlier stage when compared to the QDA classifier. This is to be expected, however, as the underlying data was generated from two distributions with equal variances, and optimal separation would occur with a linear decision boundary.



TABLE 2.3.4 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the QDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.32127 (0.021685) 26; 40 39.986; 0.4427	0.32144 (0.021382) 11; 40 39.002; 5.1098	0.32221 (0.022308) 8; 40 36.253; 9.8887	0.32377 (0.025475) 6; 40 32.695; 13.196
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.26611 (0.012922) 22; 40 39.931; 1.0906	0.26729 (0.016484) 11; 40 37.868; 7.2336	0.26811 (0.016903) 8; 40 33.341; 12.3194	0.27057 (0.024011) 6; 40 29.067; 14.5582
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.2336 (0.013372) 21; 40 39.856; 1.5018	0.234 (0.013442) 11; 40 37.13; 8.212	0.23525 (0.014998) 8; 40 31.792; 13.0979	0.23869 (0.022481) 6; 40 25.104; 15.0572
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.16384 (0.008868) 21; 40 39.164; 3.5414	0.1656 (0.012193) 11; 40 32.904; 11.4121	0.16716 (0.014617) 8; 40 25.525; 13.9239	0.1716 (0.022827) 6; 40 17.772; 12.8796
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.12938 (0.007179) 21; 40 38.609; 4.4036	0.13147 (0.011205) 11; 40 30.538; 12.0179	0.13435 (0.015214) 8; 40 21.587; 12.9199	0.13624 (0.018431) 6; 40 15.577; 10.761
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.10983 (0.006733) 21; 40 37.777; 5.343	0.11228 (0.011063) 11; 40 28.195; 12.0778	0.11522 (0.014401) 8; 40 19.503; 11.7862	0.11842 (0.020734) 6; 40 13.941; 9.0266
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.07129 (0.00818) 21; 40 35.241; 6.9009	0.07374 (0.012444) 11; 40 23.423; 10.6314	0.07666 (0.017198) 8; 40 15.949; 7.8427	0.07865 (0.021983) 6; 40 12.116; 5.2397
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.02667 (0.006709) 21; 40 34.089; 6.9336	0.02913 (0.012181) 11; 40 23.301; 7.5656	0.03024 (0.011991) 8; 40 16.146; 4.5236	0.0306 (0.014022) 6; 28 12.38; 2.7938

Similar to those results seen where M=90 in Table 2.3.3, the average rate of misclassification does not decrease substantially as ε is decreased in Table 2.3.4. The results are very similar to those seen where the LDA classifier's maximum number of steps was decreased from 90 to 40. The average misclassification rate for QDA where M=40 is generally also slightly larger than it is for QDA with M=90, and the maximum M=40 was reached at least once for 31 of the 32 scenarios.

Various simulations were also conducted where the variance σ_2^2 was allowed to vary $(\sigma_2^2 \in \{2, 3, 4\})$ for both M = 90 and M = 40. The results are provided in Appendix D. Increasing σ_2^2 resulted in the average misclassification rate increasing by a similar value when compared to the increase in variance for the LDA classifier. As ε is decreased there



is no significant change in the misclassification rate, and for large values of Δ the average number of sequential steps increases significantly as the allowed error ε decreases. Similar to the LDA results, the average number of steps increased while the standard deviation in the number of sequential steps decreased for those scenarios where the Bayes error is larger than ε . In the scenarios where the Bayes error is smaller than ε the standard deviation increased as was seen for the LDA classifier.

TABLE 2.3.5 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the QDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,3)$ distribution and $\alpha = 0.05$. The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} ; Sd	0.32764 (0.009462) 24; 90 89.934; 2.0871	0.32816 (0.010577) 11; 90 87.219; 14.4033	0.32921 (0.01703) 8; 90 82.343; 23.4365	0.33253 (0.019323) 6; 90 69.098; 34.5981

Increasing σ_2^2 from 1 to 3 for M=90 resulted in the average misclassification rate increasing while the corresponding standard deviations remained relatively stable. The maximum number of steps was also reached at least once in 31 of the 32 scenarios tested. It is, however, very interesting to note that the observed average misclassification rate for $\Delta=1$ and $\varepsilon\in\{0.05,\ 0.1\}$ is actually lower than the Bayes error, which theoretically should not be the case as the Bayes error is the theoretical minimum error. This result is provided in Table 2.3.5. Increasing σ_2^2 from 1 to 4 for both M=90 and M=40 resulted in multiple cases where the Bayes error was larger than the average misclassification rate. These seem to be consigned to the scenarios where there is a significant overlap in the generating distributions and the specified error rate, ε , is much smaller than the Bayes error. This is explained in more detail in Section 2.6.2.

As the variance σ_2^2 is increased, the average rate of misclassification for the QDA classifier is generally lower than it is for the corresponding LDA classifier. LDA classification assumes that the underlying distributions have equal variances and therefore the pooled variance is used as an estimate for the population variance. QDA assumes that the underlying distributions have unequal variances, therefore QDA is more applicable in this specific scenario where $\sigma_2^2 \neq \sigma_1^2$. Consequently, the observed misclassification rates are lower for QDA than observed for LDA as optimal separation of the distributions occur with a quadratic decision boundary.



2.3.5 5-nn simulation

TABLE 2.3.6 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were sampled from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.35454 (0.024912) 22; 90 89.798; 3.6847	0.35241 (0.024755) 11; 90 87.545; 13.5176	0.35162 (0.026369) 8; 90 80.497; 25.8278	0.35063 (0.028713) 6; 90 71.401; 33.3352
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.29387 (0.021254) 21; 90 89.864; 3.0399	0.29535 (0.022765) 11; 90 85.077; 18.4837	0.2919 (0.023932) 8; 90 72.929; 32.1678	0.2901 (0.027223) 6; 90 57.788; 37.8642
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.2602 (0.021338) 21; 90 89.468; 5.9309	0.25781 (0.022441) 11; 90 80.934; 24.7025	0.25712 (0.023622) 8; 90 66.538; 35.4507	0.25608 (0.029484) 6; 90 49.108; 37.9617
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.18069 (0.018189) 21; 90 86.55; 14.6248	0.17957 (0.019988) 11; 90 67.479; 33.9346	0.1786 (0.022296) 8; 90 43.989; 35.7108	0.17806 (0.023966) 6; 90 27.319; 28.6949
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.14245 (0.016034) 21; 90 83.716; 19.1087	0.14055 (0.018397) 11; 90 55.223; 36.0437	0.14223 (0.020074) 8; 90 32.254; 30.5644	0.1418 (0.022865) 6; 90 19.336; 20.7586
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.11899 (0.013705) 21; 90 77.677; 25.037	0.11936 (0.016974) 11; 90 47.99; 34.5804	0.12 (0.019556) 8; 90 26.738; 25.7567	0.12045 (0.020212) 6; 90 16.22; 16.3111
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.0758 (0.011213) 21; 90 64.719; 29.8551	0.07652 (0.01345) 11; 90 32.401; 25.5257	0.07657 (0.014421) 8; 90 16.809; 11.2941	0.0776 (0.014715) 6; 89 12.534; 7.3361
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.02648 (0.005645) 21; 90 44.369; 19.7192	0.02711 (0.006628) 11; 66 23.855; 7.6815	0.02746 (0.006985) 8; 52 16.522; 4.62	0.028 (0.00778) 6; 22 12.586; 2.6225

To test whether a localised classifier used in the sequential procedure would yield smaller misclassification rates and stop the sequential procedure quicker, K-nearest neighbours was used as a classification method. A small value of K should yield a localised classifier and slightly lower misclassification errors. A better, or more efficient, classification method should result in the sequential procedure stopping earlier, due to more correct classifications. This was investigated with the use of the K-nearest neighbours classifier, testing the 3-nearest neighbours and 5-nearest neighbours respectively. The results for M=90 and M=40, where K=5, are provided in Table 2.3.6 and Table 2.3.7 respectively. The results for M=90 and M=40, where K=3, are provided in



Table 2.3.9 and Table 2.3.10 respectively.

The mean misclassification rate in Table 2.3.6 does not exhibit much variation and only shows minor increases or decreases, contrary to the results seen for the LDA and QDA classifiers where the average rate of misclassification decreases as ε is decreased. For cases where the Bayes error is much larger than ε the misclassification rate is larger than it is for both the LDA and QDA classifiers, and as Δ is further increased and the Bayes error decreases, the misclassification rate tends towards the Bayes error. As ε increases and Δ increases, the 5-nearest neighbour classifier performs better than the QDA classifier as it obtains a lower average rate of misclassification. This, however, only occurs for large values of Δ . In the specific scenarios where the Bayes error is larger than the prespecified minimum acceptable error, ε , the 5-nearest neighbour classifier required, on average, more sequential observations to satisfy the stopping criteria as the average number of sequential steps is slightly higher. The maximum M is still reached at least once for 28 of the 32 different scenarios tested.



TABLE 2.3.7 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.35489 (0.037584) 23; 40 39.967; 0.7379	0.35553 (0.037201) 11; 40 39.244; 4.4885	0.35453 (0.038088) 8; 40 36.487; 9.649	0.35468 (0.038407) 6; 40 32.508; 13.4186
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.2951 (0.031845) 22; 40 39.951; 0.8986	0.29555 (0.031743) 11; 40 37.998; 7.0863	0.29327 (0.032009) 8; 40 33.927; 11.9413	0.29242 (0.035234) 6; 40 29.322; 14.6241
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.25929 (0.027827) 21; 40 39.903; 1.2622	0.25879 (0.029235) 11; 40 36.767; 8.7228	0.25804 (0.030713) 8; 40 31.714; 13.1978	0.25797 (0.034809) 6; 40 26.453; 15.0632
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.18018 (0.023782) 21; 40 39.208; 3.4671	0.17997 (0.023326) 11; 40 32.718; 11.5026	0.17966 (0.024959) 8; 40 24.706; 14.1394	0.18198 (0.03001) 6; 40 18.685; 13.467
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.14183 (0.020223) 21; 40 38.316; 4.9068	0.14232 (0.020739) 11; 40 30.204; 12.0718	0.14148 (0.022718) 8; 40 21.506; 12.973	0.14264 (0.023288) 6; 40 15.413; 11.026
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.12032 (0.017918) 21; 40 37.669; 5.5325	0.12117 (0.019682) 11; 40 27.84; 12.3494	0.11978 (0.019052) 8; 40 19.676; 11.8988	0.12212 (0.022606) 6; 40 13.318; 8.6156
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.07597 (0.012831) 21; 40 35.388; 6.8662	0.07677 (0.014552) 11; 40 24.215; 10.8472	0.07756 (0.015463) 8; 40 16.458; 8.3848	0.07747 (0.015617) 6; 40 12.008; 4.9879
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.02682 (0.006048) 21; 40 34.152; 7.0013	0.0277 (0.007403) 11; 40 23.275; 7.281	0.02777 (0.00798) 8; 40 16.28; 4.2696	0.02819 (0.00863) 6; 21 12.466; 2.684

The results presented in Table 2.3.7 are similar to the results seen for the 5-nearest neighbour classifier with M=90. As the value of ε is decreased, the mean misclassification rate does not decrease substantially. The misclassification rate is nearly equal to those results when M=90. The average number of sequential steps is roughly equal to the average number observed with the LDA classifier, and the maximum M was reached at least once for 31 of the 32 different scenarios tested.

It is also interesting to note that the standard deviation in the number of sequential steps is lower than it is when M = 90. This indicates that there is less variation in the number of steps observed, and the observations are closer to the observed averages. Considering that the average number of sequential steps is relatively high in many of the



scenarios tested, it suggests that the maximum M might have been reached more often than liked.

Various simulations were also conducted where the variance σ_2^2 was allowed to vary $(\sigma_2^2 \in \{2, 3, 4\})$ for both M = 90 and M = 40. The results are provided in Appendix D. Increasing σ_2^2 , for both M = 90 and M = 40, results in the average misclassification rate increasing for all combinations of Δ and ε . The average number of sequential steps required to train the classifier has also increased for nearly all combinations of Δ and ε tested, and the maximum M was reached at least once for the majority of the different combinations tested. The standard deviation in the number of sequential steps has increased for nearly all of the different scenarios tested, indicating more spread in the observed values. In those cases where the standard deviation has decreased, the average number of sequential steps has increased towards the maximum M. Taking into account that the maximum was reached for all of these scenarios indicates that the observations are clustered more closely to the maximum, with more of the observations being equal to the maximum.

Increasing σ_2^2 to 3 results in an increase in the average rate of misclassification, however the average rate of misclassification does no longer decrease as substantially when Δ is increased. As was seen in Table D.3.1 the standard deviation in the number of sequential steps has increased for nearly all of the scenarios tested. In those cases where the standard deviation has decreased, the average number of steps has increased towards the maximum M.



TABLE 2.3.8 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.46677 (0.01336) 90; 90 90; 0	0.46384 (0.01958) 11; 90 88.295; 11.3756	0.45815 (0.03408) 8; 90 83.282; 22.2223	0.4502 (0.04189) 6; 90 75.013; 30.679

It is very interesting to note the specific results for $(\Delta, \varepsilon) = (1, 0.05)$ where M = 90 and $\sigma_2^2 = 4$, as provided in provided in Table 2.3.8. The maximum M was reached in all 1000 repetitions of the simulation. This indicates that the stopping procedure reaches the maximum M too often and it is very possible that the classifiers obtained have not been trained to such an extent to ensure, with a probability of at least $100 (1 - \alpha) \%$, that the probability of a misclassification on the next observation is acceptably low - ε . It is necessary to test what the impact will be if the maximum M is increased.



2.3.6 3-nn simulation

TABLE 2.3.9 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 3-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were sampled from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.50001 (0.003822) 23; 90 89.933; 2.1187	0.49982 (0.006826) 11; 90 87.698; 13.1105	0.50001 (0.010108) 8; 90 81.371; 24.7328	0.50007 (0.01617) 6; 90 71.088; 33.7997
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.4999 (0.004537) 22; 90 89.736; 4.1737	0.49984 (0.008761) 11; 90 83.947; 20.6926	0.49963 (0.015131) 8; 90 73.757; 31.8854	0.50042 (0.020688) 6; 90 59.877; 37.9165
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.5003 (0.004934) 21; 90 89.406; 6.2434	0.50047 (0.010315) 11; 90 81.595; 23.8542	0.49981 (0.018173) 8; 90 68.79; 34.5188	0.49952 (0.026773) 6; 90 51.754; 38.3739
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.50029 (0.006131) 21; 90 86.685; 14.3701	0.50031 (0.017051) 11; 90 69.961; 32.6527	0.50043 (0.026352) 8; 90 48.792; 37.2594	0.50263 (0.040599) 6; 90 29.298; 30.4767
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.49994 (0.007648) 21; 90 83.615; 19.2003	0.49914 (0.023401) 11; 90 57.039; 35.5977	0.50127 (0.034256) 8; 90 35.672; 32.7518	0.5005 (0.046521) 6; 90 20.655; 22.4392
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.49966 (0.008003) 21; 90 81.143; 21.9089	0.49813 (0.026024) 11; 90 47.279; 34.9445	0.50074 (0.035897) 8; 90 29.026; 28.5033	0.50215 (0.047212) 6; 90 17.143; 17.7356
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.50054 (0.01438) 21; 90 63.474; 30.5024	0.49946 (0.030915) 11; 90 32.262; 26.4758	0.4977 (0.043238) 8; 90 18.31; 13.9272	0.49756 (0.055892) 6; 90 12.388; 7.5503
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.49992 (0.017517) 21; 90 44.958; 19.9403	0.49817 (0.034344) 11; 90 24.163; 9.0895	0.49897 (0.048283) 8; 44 16.323; 4.2662	0.49817 (0.059611) 6; 42 12.476; 2.9967

For a given value of Δ the mean misclassification rate does not vary much and does not decrease as the value of ε is decreased. The average rate of misclassification is much higher than it is for the 5-nearest neighbour classifier or any of the other classifiers tested.

It is also interesting to note that the average rate of misclassification does not decrease or increase significantly as the value of Δ is increased, nor does the average misclassification rate tend towards the Bayes error as is the case for the 5-nearest neighbour classifier. The maximum number of steps is still reached at least once for 30 of the 32 different scenarios tested. Due to the much localised nature of the classifier, the average rate of misclassification is nearly equal to the probability of sampling a random observation from



TABLE 2.3.10 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 3-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.37042 (0.033812) 21; 40 39.981; 0.6008	0.36978 (0.036017) 11; 40 39.065; 4.93	0.36723 (0.036705) 8; 40 37.397; 8.4857	0.36647 (0.038177) 6; 40 33.334; 12.8725
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.31134 (0.032428) 22; 40 39.954; 0.8465	0.31072 (0.034552) 11; 40 38.107; 6.7995	0.30777 (0.035396) 8; 40 34.72; 11.4129	0.30807 (0.039892) 6; 40 29.825; 14.4063
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.27375 (0.031387) 21; 40 39.782; 1.9147	0.27307 (0.0339) 11; 40 36.778; 8.6834	0.27031 (0.03459) 8; 40 32.47; 12.8421	0.26957 (0.03649) 6; 40 26.707; 15.2458
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.1922 (0.027093) 21; 40 39.206; 3.4365	0.18868 (0.027018) 11; 40 32.988; 11.4715	0.18777 (0.028954) 8; 40 25.991; 14.1064	0.19084 (0.033597) 6; 40 20.695; 14.2897
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.15228 (0.025653) 21; 40 38.29; 4.9153	0.14855 (0.023536) 11; 40 30.767; 12.1085	0.14975 (0.027648) 8; 40 22.638; 13.4216	0.14898 (0.030125) 6; 40 16.392; 11.966
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.12736 (0.022359) 21; 40 37.866; 5.3508	0.12663 (0.023176) 11; 40 28.394; 12.2265	0.12737 (0.026785) 8; 40 20.398; 12.0902	0.12646 (0.026262) 6; 40 14.215; 9.943
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.08096 (0.017869) 21; 40 35.246; 6.961	0.08027 (0.017573) 11; 40 23.748; 10.6441	0.08119 (0.01864) 8; 40 16.96; 9.1041	0.08198 (0.02091) 6; 40 12.388; 5.9794
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.02776 (0.007788) 21; 40 34.261; 7.1004	0.02864 (0.008598) 11; 40 23.498; 7.2707	0.0293 (0.010103) 8; 40 16.539; 4.4215	0.03001 (0.012156) 6; 27 12.478; 2.7527

either of the underlying distributions. Due to the unexpected results obtained, the simulations were repeated multiple times and all results verified.

The results obtained in Table 2.3.10 are very similar to those obtained in Table 2.3.7. For a given Δ the average misclassification rate does not decrease or increase substantially as the value of ε is decreased. Contrary to the results obtained in Table 2.3.9 the average rate of misclassification decreases as Δ is increased, a result comparable to the other classification methods tested. The maximum M is reached at least once for 31 of the 32 different combinations tested.

It is important to note here, that the classifier obtained from the sequential procedure is used for testing purposes against the holdout sample, irrespective of whether the classifier has been correctly trained or not. The unexpected results for the K-nearest neighbour



classifier, particularly the fact that the misclassification rate in Table 2.3.9 does not decrease as Δ is increased, but the misclassification rate in Table 2.3.10 does decrease as Δ is increased, could be related to the classifiers being unsuccessfully trained.

Various simulations were also conducted where the variance σ_2^2 was allowed to vary $(\sigma_2^2 \in \{2, 3, 4\})$ for both M = 90 and M = 40. The results are provided in Appendix D. Increasing σ_2^2 from 1 to 2 and from 1 to 4 for M = 90 results in the average rate of misclassification decreasing. The additional spread in the observations and the very local nature of the trained classifier has resulted in the trained classifiers being able to predict better on the testing set. The average number of sequential steps has increased and the maximum M was reached at least once for all the scenarios tested. In those scenarios where the Bayes error is substantially larger than ε the standard deviation of the number of sequential steps has decreased, indicating that the observations are located nearer to the average, and consequently nearer to the maximum M.

Increasing σ_2^2 from 1 to 3 for M=90 results in the average rate of misclassification increasing, albeit to a level lower than observed where $\sigma_2^2=1$. Contrary to the results observed for $\sigma_2^2 \in \{1, 2\}$, for a given Δ an increase in ε results in the average rate of misclassification decreasing. These results are similar to those seen for the 5-nearest neighbour classifier where $\sigma_2^2=3$ and M=90. The average number of sequential steps has increased, and for those particular scenarios where the Bayes error is larger than ε the standard deviation of the number of sequential steps has decreased.

Increasing σ_2^2 for M=40, results in an increase in the average rate of misclassification. The increase is more severe as σ_2^2 increases. The average number of sequential steps has also increased and for most cases where the Bayes error is much larger than ε the standard deviation in the average number of sequential steps has decreased. The maximum number of steps M was reached at least once for all the different scenarios tested.

Due to the much localised nature of the classifier, and the artificial upper bounds placed on the number of observations available to train the classifier, the results obtained using 3-nearest neighbours as a classifier are very mixed. In some scenarios the average rate of misclassification would increase as σ_2^2 is increased, and in other scenarios the average rate of misclassification would decrease. This behaviour was also apparent for the maximum level of acceptable error ε - in some scenarios a decrease in ε would result in the average rate of misclassification increasing substantially, whilst in other scenarios negligible changes were observed. The only consistent observation was that the average number of sequential steps required to "train" the classifier increased as σ_2^2 increased. This particular classifier is very sensitive to the observations already sampled, and to a far lesser extent the underlying distribution of the sampled data.



2.3.7 LRIM simulation

TABLE 2.3.11 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LRIM classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.31304 (0.008768) 25; 90 89.873; 2.8392	0.31302 (0.00858) 11; 90 87.389; 13.9298	0.31508 (0.013732) 8; 90 77.631; 28.8084	0.31585 (0.01381) 6; 90 64.965; 36.4448
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.26137 (0.006592) 21; 90 89.599; 5.1677	0.26172 (0.008215) 11; 90 82.812; 22.3402	0.2634 (0.010747) 8; 90 69.775; 33.7926	0.26481 (0.015812) 6; 90 52.109; 38.1097
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.22964 (0.006087) 21; 90 89.401; 6.2903	0.23036 (0.006932) 11; 90 79.57; 25.9278	0.2325 (0.010924) 8; 90 61.626; 36.7391	0.23337 (0.011981) 6; 90 42.967; 36.5363
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.16108 (0.005268) 21; 90 86.059; 15.5265	0.16277 (0.008838) 11; 90 64.283; 34.9277	0.16472 (0.010922) 8; 90 42.141; 35.6687	0.1669 (0.012821) 6; 90 23.443; 24.7779
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.12745 (0.005018) 21; 90 81.993; 20.9127	0.12931 (0.008816) 11; 90 54.653; 35.67	0.13151 (0.009714) 8; 90 29.204; 28.4085	0.1335 (0.013364) 6; 90 15.837; 14.7272
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.10792 (0.004539) 21; 90 77.935; 24.7681	0.11075 (0.009306) 11; 90 44.781; 33.9002	0.11204 (0.010535) 8; 90 22.55; 21.5898	0.11272 (0.011007) 6; 90 14.206; 11.6808
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.06935 (0.004978) 21; 90 62.715; 29.8291	0.07124 (0.008202) 11; 90 28.742; 22.1182	0.07229 (0.008603) 8; 88 16.388; 9.7278	0.0728 (0.009045) 6; 56 11.994; 5.1344
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.02419 (0.002681) 21; 90 45.162; 19.3027	0.02491 (0.003775) 11; 90 23.779; 7.8708	0.0255 (0.004829) 8; 36 16.423; 4.1332	0.02541 (0.004168) 6; 33 12.658; 2.6714

To test whether the sequential procedure takes longer to stop with a less efficient classification method, linear regression of an indicator matrix is used. The results for M = 90 and M = 40 are provided in Table 2.3.11 and Table 2.3.12 respectively.

Similar to the results for the LDA classifier, for a given Δ in Table 2.3.11 the mean misclassification rate does not decrease substantially as ε is decreased from 0.2 to 0.05. It is however very interesting to note how stable the misclassification rate remains as the values of ε are varied. The results are comparable to those obtained using the LDA classifier. When the variances of the underlying distributions are equal, the QDA classifier



is much more sensitive to a change in ε than either LDA or LRIM.

The average misclassification rate is lower for this particular classifier than it is using QDA as the classifier. The average rate of misclassification is considerably lower for those cases where the specified error rate, ε , is higher than the Bayes error, and the observed misclassification rate is much closer to the Bayes error than it is for QDA.

The average number of steps required to train the classifier is also lower in nearly all of the scenarios than the average number of sequential steps required when QDA is used as a classifier. The maximum number of sequential steps, M, was still reached at least once in 28 of the 32 scenarios. Using LRIM as a classifier results in lower misclassification rates, and the classifier needs less sequential steps on average than the QDA classifier to be trained to a satisfactory level.



TABLE 2.3.12 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LRIM classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	0.31774 (0.016796) 22; 40 39.982; 0.5692	0.31748 (0.01834) 11; 40 38.975; 5.1762	0.31889 (0.017421) 8; 40 35.557; 10.7193	0.31995 (0.021251) 6; 40 31.384; 13.9984
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.2643 (0.01233) 21; 40 39.876; 1.4795	0.26585 (0.013546) 11; 40 37.384; 7.9589	0.26602 (0.015285) 8; 40 33.523; 12.2513	0.26685 (0.016189) 6; 40 26.7; 15.0979
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.23273 (0.009912) 21; 40 39.865; 1.5116	0.23308 (0.010232) 11; 40 36.198; 9.228	0.23377 (0.012186) 8; 40 30.15; 13.8879	0.23488 (0.013774) 6; 40 25.021; 15.121
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.16346 (0.008319) 21; 40 38.895; 4.0331	0.16451 (0.010249) 11; 40 31.46; 12.0157	0.16525 (0.010291) 8; 40 24.437; 13.6192	0.16673 (0.012453) 6; 40 17.537; 12.6661
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.12914 (0.006487) 21; 40 37.951; 5.3823	0.13073 (0.009225) 11; 40 28.519; 12.4319	0.13208 (0.011092) 8; 40 20.46; 12.375	0.13299 (0.011991) 6; 40 15.182; 10.5985
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.10948 (0.006176) 21; 40 37.19; 5.9603	0.11088 (0.008229) 11; 40 26.637; 12.1424	0.11209 (0.00977) 8; 40 18.425; 11.0815	0.11396 (0.013201) 6; 40 13.338; 8.5283
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.06993 (0.005081) 21; 40 35.058; 7.0125	0.07145 (0.007643) 11; 40 23.451; 10.0324	0.07248 (0.008286) 8; 40 16.207; 7.5478	0.07306 (0.009119) 6; 40 11.916; 4.7228
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.02448 (0.00284) 21; 40 33.729; 7.0338	0.02493 (0.003587) 11; 40 23.67; 6.9984	0.02506 (0.003754) 8; 40 16.46; 4.2363	0.02598 (0.005258) 6; 26 12.568; 2.6729

The results obtained by limiting the maximum number of sequential steps to 40 are very similar to those obtained for this particular classifier when the maximum number of sequential steps was set at M=90. The average rate of misclassification is lower for this classifier than it is for QDA classifier, and in some cases the average rate of misclassification is lower than it is for the LDA classifier, albeit slightly. The classifier performs quite well and only estimates marginally worse than when M=90 as the average rate of misclassification is only slightly higher.

Various simulations were also conducted where the variance σ_2^2 was allowed to vary $(\sigma_2^2 \in \{2, 3, 4\})$ for both M = 90 and M = 40. The results are provided in Appendix D.



2.4. INFLUENCE OF PARAMETER CHANGES

Increasing σ_2^2 results in the average rate of misclassification increasing for all combinations of Δ and ε . The average number of sequential steps required to "train" the classifier has also increased, with the increases being significant for those cases where the Bayes error is larger than ε . For those specific cases where the Bayes error is significantly larger than ε , the standard deviation of the number of sequential steps decreases slightly. There are multiple scenarios as well where the maximum allowed number of sequential steps allowed, M, is reached at least once. The decrease in the standard deviation of the number of sequential steps and the increase observed in the average number of sequential steps again indicates that the model reaches the maximum specified (M) far more often.

The results obtained from using LRIM are comparable to the results obtained using LDA. The two sets of results should be comparable though as both classification methods use linear decision boundaries for optimal separation of the data. However, care must be taken when using the regression approach as it easily masks other classes if the response variable Y has more than two classes (i.e. is not binary). This happens when the boundaries found by LRIM pass through one of the classes. Consequently that particular class will never dominate the output from the regression model as there is only 1 linear decision boundary. LDA, on the other hand, has p-1 linear decision boundaries when the response variable has p classes.

2.4 Influence of parameter changes

To test how sensitive the procedure is to a change in parameters, various input parameters were changed. Additional simulations were run where the assumption of equal proportions for the sampled data $\hat{p}_1 = \hat{p}_2$ was no longer adhered to $(\hat{p}_2 \in \{0.1, 0.2, 0.4\})$ with all other assumptions kept constant; and where the maximum number of sequential steps allowed was increased to 300 with all other parameters kept constant. For the purpose of this section, the only classification method tested was LDA. As seen in the results provided, the sequential procedure often reaches the maximum allowed number of sequential steps M. This was not limited to any specific classification method tested (i.e. in all methods of classification tested, the sequential procedure reached M at least once), and it therefore seems necessary to test the effects of the parameter changes on only one classification method. LDA was chosen as the variances from the underlying distributions are equal (thereby negating the need for QDA), LRIM yields similar results (the response variable has only two classes and therefore only one linear decision boundary will be obtained) and the K-nearest neighbour classifiers are too computationally intensive for the current purpose.



2.4. INFLUENCE OF PARAMETER CHANGES

2.4.1 Changing sampling probabilities

To test how sensitive the procedure is to a change in the sampling probabilities, the input parameter \hat{p}_2 was varied ($\hat{p}_2 \in \{0.1, 0.2, 0.4\}$). For this section, 3 separate simulations were conducted. To keep the total initial sample size equal to 10 observations, 9 observations were randomly generated from a N(0, 1) distribution and an additional 1 observation was randomly generated from a $N(\Delta, 1)$ ($\Delta \in \{1, 1.3, 1.5, 2, 2.3, 2.5, 3, 4\}$) distribution. For the other two simulations the initial sample size combinations were (8; 2) and (6; 4) respectively. The initial sample sizes were kept small to limit the total number of initial observations to 10 for comparative purposes. The maximum number of sequential steps allowed was set at 90 (i.e. M = 90). The results are available in Appendix D in Table D.6.1, Table D.6.2 and Table D.6.3.

Similar to the results presented for the LDA classifier with equal sampling probabilities, for each value of Δ , specifying a smaller value of ε does not lead to a significant reduction in the average misclassification rate. The average rate of misclassification is, however, lower than observed when sampling with equal probabilities. Additionally, the Bayes errors have been greatly reduced, therefore many of the scenarios can now be correctly tested as the maximum error threshold for the model, ε , is larger than the Bayes error. The average number of sequential steps has been greatly reduced in many scenarios where the separation between the samples is small, i.e. Δ is small. This is mainly due to the fact that in the simulation with equal sampling probabilities, the maximum error threshold specified was too small, forcing the sequential procedure to try and correctly train the classifiers to an error rate that is impossible to achieve. The standard deviation in the number of sequential steps has also increased significantly, indicating a much greater spread in the observed number of sequential steps. When the majority of the data is generated from the N(0, 1) distribution, the average number of sequential steps is more dependent on ε than it is on a change in Δ , but as the difference in the sampling probabilities decreases the sensitivity towards Δ increases substantially. It is still very important to note that in all three simulations, the maximum allowed number of sequential steps M was reached at least once for the majority of the (Δ, ε) combinations tested. The sequential procedure is unable to account for Bayes errors larger than the prespecified level of acceptable error ε . Therefore, the sequential procedure tries to train the classifier to obtain an unfeasibly low rate of misclassification.

2.4.2 Changing maximum number of sequential steps

In all results presented, the maximum allowed number of sequential steps M was reached at least once for the majority of the (Δ, ε) combinations tested. As there was no evidence supporting the particular choice of M, an increase could result in the sequential



procedure successfully training the classifier more often before N=M. If the average number of sequential steps required increases dramatically while the standard deviation in the number of sequential steps remains relatively low, it is indicative of how often the recursive procedure reached the maximum allowed. To test how sensitive the procedure is to a change in the maximum number of sequential steps allowed, a simulation was run where the maximum allowed was set at 300 observations. 5 observations were generated from a N(0,1) distribution and 5 additional observations were generated from a N(0,1) distribution ($\Delta \in \{1,1.3,1.5,2,2.3,2.5,3,4\}$). The effect of a change in ε was also investigated ($\varepsilon \in \{0.05, 0.1, 0.15, 0.2\}$). The level of significance was kept constant at 0.05 (i.e. $\alpha = 0.05$). The results are available in Appendix D in Table D.7.1.

Similar to the LDA results observed for M=90 and $\sigma_2^2=1$, for each value of Δ , specifying a smaller value of ε does not lead to a significant reduction in the average misclassification rate. The maximum absolute reduction of 0.03566 is observed where $\Delta=3$ and ε decreases from 0.2 to 0.05. This, however, leads to an increase in the average number of sequential steps necessary to train the classifier from 11.982 to 210.269. This suggests that the maximum number of steps allowed, M=300, was again reached multiple times. For small values of Δ ($\Delta \in \{1, 1.3, 1.5, 2\}$) and ε ($\varepsilon \in \{0.05, 0.1\}$) the average number of sequential steps remained above 200. In all of these cases the maximum M=300 was reached at least once. For all of these cases though the Bayes error is much larger than the error rate used in training the classifier, i.e. ε . This would suggest that the sequential procedure is trying to train the classifier to an unrealistic error rate that can not be achieved. The maximum is still reached at least once for 26 of the 32 scenarios tested. It therefore seems plausible to investigate how often the procedure reaches the maximum M, and how often the classifier is successfully trained.

2.5 Microarray sample data application

To test the sequential procedure's performance on real-world data, the sequential procedure was applied to a dataset containing breast-cancer patient prognosis data. In Van't Veer et al. (2002) a gene expression signature that is highly predictive of disease outcome is derived. The sample data is freely available and is widely used in the Biometric field and the sample size is relatively large. It is also possible to compare the results obtained from this analysis to results obtained in other experiments. The dataset consists of 295 observations in total, with measurements on the 70 genes that were found to be highly predictive of the prognosis. The prognosis variable had to be derived from 2 separate variables (conservFlag and C1used) as stated in the original article. The total number of "good prognosis" observations derived equalled the number provided in the article.



TABLE 2.5.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier on the sample data. The initial sample sizes are provided. $\alpha = 0.05$ and the minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier on the 3 genes most highly correlated to the prognosis variable is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Initial Sample	Maximum Allowed		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
(5,5)	50	Error (Std) Min; Max \bar{n} ; Sd	0.25007 (0.030842) 8; 50 41.622; 15.9589	0.25493 (0.034387) 6; 50 33.248; 19.478	0.26314 (0.037582) 5; 50 23.597; 19.0874	0.26707 (0.038849) 4; 50 16.363; 15.5845
(5,5)	80	Error (Std) Min; Max \bar{n} ; Sd	0.24659 (0.031182) 8; 80 62.399; 29.4154	0.25301 (0.034455) 6; 80 47.478; 33.0945	0.26198 (0.038551) 5; 80 32.155; 29.8622	0.26865 (0.041054) 4; 80 18.147; 20.486
(10, 10)	50	Error (Std) Min; Max \bar{n} ; Sd	0.24483 (0.025483) 8; 50 39.706; 17.1464	0.24804 (0.026697) 6; 50 30.746; 19.5965	0.25123 (0.029396) 5; 50 22.935; 18.4514	0.25442 (0.028819) 4; 50 14.966; 14.3404
(10, 10)	80	Error (Std) Min; Max \bar{n} ; Sd	0.24172 (0.026975) 8; 80 61.146; 29.9166	0.24592 (0.028477) 6; 80 45.144; 33.0221	0.24985 (0.027322) 5; 80 28.472; 28.2134	0.25288 (0.0296) 4; 80 17.95; 19.9879

For the application to sample data, LDA, 5-nearest neighbours and 3-nearest neighbours were tested. For all scenarios, the sampling probabilities were kept equal sampling either 5 initial observations from both the good prognosis and the bad prognosis groups or 10 initial observations from either. The maximum allowed number of sequential steps was set at 50 and 80 respectively, and the values of ε tested were $\varepsilon \in (0.15, 0.2, 0.25, 0.3)$. To test each respective classifier's predictive ability the remainder of the sample was used as a testing set, comparing the predicted outcome to the clinical outcome. The sequential procedure is repeated 1000 times and the level of significance is kept at $\alpha = 0.05$. The results for the LDA classifier are available in Table 2.5.2 and the results for the 5-nearest neighbour classifier are available in Table 2.5.3.

The LDA classifier was trained on the 3 genes most highly correlated to the prognosis variable. Similar to what was observed by Fu et al. (2005), as the minimum allowed error ε decreases from 0.3 to 0.15 the average rate of misclassification decreases and the minimum number and average number of sequential steps increases. This holds for all tested combinations of the different initial sample sizes and the maximum allowed number of sequential steps. For all tested scenarios the maximum number of sequential steps allowed M was reached at least once. Increasing the number of observations in the



TABLE 2.5.2 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 3-nn classifier on the sample data. The initial sample sizes are provided. $\alpha = 0.05$ and the minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier on the 5 genes most highly correlated to the prognosis variable is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Initial Sample	Maximum Allowed		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
(5,5)	50	Error (Std) Min; Max \bar{n} ; Sd	0.27078 (0.028696) 8; 50 41.428; 16.216	0.27594 (0.033705) 6; 50 32.992; 19.774	0.2786 (0.037529) 5; 50 25.794; 19.843	0.27915 (0.037641) 4; 50 19.126; 17.6267
(5,5)	80	Error (Std) Min; Max \bar{n} ; Sd	0.26728 (0.29908) 8; 80 63.303; 27.9452	0.27129 (0.033772) 6; 80 48.792; 33.4317	0.27503 (0.03662) 5; 80 36.047; 31.4503	0.27865 (0.041416) 4; 80 21.581; 24.4526
(10, 10)	50	Error (Std) Min; Max \bar{n} ; Sd	0.26799 (0.028542) 8; 50 41.26; 16.305	0.27156 (0.030456) 6; 50 34.326; 19.3775	0.27299 (0.03094) 5; 50 25.053; 19.513	0.27276 (0.032012) 4; 50 18.429; 17.1498
(10, 10)	80	Error (Std) Min; Max \bar{n} ; Sd	0.263 (0.027597) 8; 80 65.011; 28.1259	0.26798 (0.029094) 6; 80 48.615; 33.3866	0.27203 (0.030933) 5; 80 33.572; 30.4035	0.27318 (0.030399) 4; 80 21.057; 23.1812

initial sample results in slightly lower average number of sequential steps as well as slightly lower misclassification rates. Increasing the number of observations in the initial sample does little, however, to change the standard deviation in the number of average steps. This indicates that the distribution of the observed number of sequential steps is shifted slightly. The classifier therefore seems to be better trained, which in general should result in earlier stopping.

The 3-nearest neighbour classifier was trained on the 5 genes most highly correlated to the prognosis variable. As the value of ε is decreased the average rate of misclassification decreases for all scenarios tested. The results are not directly comparable to those obtained from the LDA classifier as that particular classifier was trained on the 3 genes most highly correlated with the prognosis variable. Increasing the number of observations in the initial sample again leads to a minor reduction in the average misclassification rate and the average number of sequential steps needed to train the classifier.



TABLE 2.5.3 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier on the sample data. The initial sample sizes are provided. $\alpha = 0.05$ and the minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier on the 3 genes most highly correlated to the prognosis variable is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Initial Sample	Maximum Allowed		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
(5,5)	50	Error (Std) Min; Max \bar{n} ; Sd	0.26499 (0.035146) 8; 50 41.711; 15.9212	0.26984 (0.035986) 6; 50 34.297; 19.2945	27.137 (0.038206) 5; 50 26.395; 19.5876	0.27457 (0.040335) 4; 50 19.169; 17.5116
(5,5)	80	Error (Std) Min; Max \bar{n} ; Sd	0.26146 (0.030778) 8; 80 62.567; 29.5083	0.26456 (0.036375) 6; 80 50.842; 33.1719	0.27366 (0.041771) 5; 80 31.633; 29.6903	0.2749 (0.044655) 4; 80 22.45; 24.2241
(10, 10)	50	Error (Std) Min; Max \bar{n} ; Sd	0.26114 (0.027926) 8; 50 41.395; 16.2267	0.26365 (0.028544) 6; 50 33.375; 19.5803	0.26573 (0.031888) 5; 50 24.379; 19.1291	0.27009 (0.033119) 4; 50 16.937; 15.8617
(10, 10)	80	Error (Std) Min; Max \bar{n} ; Sd	0.25843 (0.027138) 8; 80 63.137; 29.109	0.26057 (0.029336) 6; 80 49.277; 33.1269	0.26498 (0.031295) 5; 80 32.988; 30.4162	0.26885 (0.033495) 4; 80 20.722; 23.0017

The 5-nearest neighbour classifier was also trained on the 5 genes most highly correlated to the prognosis variable. Similar to the results reported for the 3-nearest neighbour classifier, decreasing the value of ε results in a decrease in the average rate of misclassification, while the average and minimum number of sequential steps needed to train the classifier increases. The 5-nearest neighbour classifier, although being less localised than the 3-nearest neighbour classifier, performs slightly better with lower average misclassification rates and lower average values for the number of sequential steps required.

In all of the scenarios tested, the maximum allowed number of sequential steps was reached. The same result was observed in all of the simulation studies. This indicates that the sequential procedure did not train the classifiers quickly enough. Taking into account that the procedure was specifically developed to minimise the number of observations needed for a sample to train a classifier that yields an acceptably low rate of misclassification, it is quite worrying that there are only a few simulated scenarios where the maximum was not reached. This leads to the question of what would happen if the maximum were to be increased. Increasing the maximum number of sequential steps allowed to 300 proved ineffective as the classifier was still not successfully trained. Increasing the maximum number of allowed sequential steps surely is one possible solution to ensure that the maximum is not reached, but it seems inconsistent with the goal of minimising the amount of data needed.



2.6 Sequential procedure shortcomings and suggestions

In the results presented in the simulation study, it was evident that the sequential procedure reached the maximum allowed number of sequential steps M at least once for the majority of the parameter combinations tested. This occurrence was not limited to any particular classifier either. Furthermore, for the QDA simulation study it was noted that the observed average misclassification rates for some of the combinations of $(\Delta, \varepsilon, \sigma_2^2)$ were lower than the Bayes error. This should not be case, as the Bayes error is the theoretical minimum achievable rate of error. Additionally, the classifier obtained from the sequential procedure often yields a rate of misclassification lower than the specified maximum rate of error ε . This results in an overtrained classifier. These shortcomings will be discussed in the following sub-sections.

2.6.1 Artificial upper bound

While testing the sequential procedure's performance using LDA as the classifier, it was noted that the procedure reached the maximum selected number of sequential steps allowed, M, at least once for most of the combinations of (Δ, ε) . This result is repeated for all the other classifiers tested. Changing the input variance of one of the samples had no effect on this, and changing the sampling probabilities also did not remedy this. When the maximum number of sequential steps allowed, M, was increased to 300 the maximum was still reached at least once for more than 80% of the scenarios tested. In many of the different scenarios tested, high average and low standard deviation values for the observed number of sequential steps were observed, indicating that most of the actual contributing results are very near to the average. Increasing the maximum number of sequential steps allowed, M, from 90 to 300 for the LDA classifier decreased the average misclassification rate for all tested combinations of (Δ, ε) . However this also brought to light that the sequential procedure reaches M quite often. This leads to the question of whether the sequential procedure actually successfully trained the classifier by the time N = M or whether the sequential procedure was stopped because the maximum M was reached.

Suppose the rule to stop the sequential procedure if N=M were not applicable. If the classifier is not successfully trained, none of the other stopping criteria would be met and the procedure would continue training the classifier, sampling more and more observations. This particular scenario was tested as well. After more than a week of processing the commands on the server, the procedure was manually forced stop. If the procedure were allowed to continue like this the number of steps required before the stopping criteria is met would increase drastically, possibly resulting in an infinite loop.



Arbitrarily choosing a stopping point M and then using those unsuccessfully trained classifiers (obtained classifier value when N=M) to estimate classifier performance or report the average number of steps needed to "train" the classifier seems flawed, as the classifiers obtained in such a manner to do not conform to the theoretical requirements derived for the procedure. It is therefore necessary to test how many times the classifier is successfully trained.

To test how many of the 1000 iterations stopped due to the classifier being successfully trained, another series of 1000 simulations were conducted where the classifier would only be recorded if:

- The stopping criteria for $\hat{\kappa}$ etc. were met and $N \neq M$.
- The stopping criteria for $\hat{\kappa}$ etc. were met and N=M.

where $\hat{\kappa}$ is defined as on page 11.

Those scenarios where the sequential procedure was stopped purely because N=M were not taken into account.



TABLE 2.6.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 300 (i.e. M=300). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively). For this particular series of simulations the number of sequential steps was not recorded in the case where the stopping criteria had not been met but N=M. Also provided is the number of times the classifier was successfully trained, denoted by Classifiers Correctly Trained.

Δ	Bayes error			$\epsilon = 0.05$		$\epsilon = 0.10$		$\epsilon = 0.20$	
1	0.30854	Error (Std) Min; Max \bar{n} ; Sd	Classifiers Correctly Trained	0.3336 (.) 23; 23 23; .	1	0.33412 (0.040835) 11; 282 21.8333; 49.2244	30	0.32725 (0.031165) 6; 300 80.4625; 91.3745	493
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	Classifiers Correctly Trained	0.31268 (0.050675) 21; 25 23; 1.633	4	0.28119 (0.031684) 11; 227 25.3263; 43.0337	95	0.27505 (0.030343) 6; 300 80.3699; 88.4056	784
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	Classifiers Correctly Trained	0.25832 (0.023908) 21; 28 23.8333; 2.4833	6	0.25557 (0.04693) 11; 296 48.9597; 71.3845	124	0.25024 (0.04034) 6; 297 67.5142; 78.8897	914
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	Classifiers Correctly Trained	0.18279 (0.03293) 21; 42 25.0357; 4.9627	28	0.18313 (0.044645) 11; 297 68.9559; 84.7527	408	0.1884 (0.04551) 6; 294 31.9759; 43.9518	995
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	Classifiers Correctly Trained	0.15815 (0.052234) 21; 274 34.4024; 39.4032	82	0.14816 (0.038196) 11; 300 72.1351; 82.8633	666	0.16371 (0.056179) 6; 206 21.831; 26.6442	1000
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	Classifiers Correctly Trained	0.13359 (0.036073) 21; 281 44.6242; 53.8841	149	0.13181 (0.04461) 11; 297 67.3628; 77.0527	827	0.14407 (0.05527) 6; 164 16.473; 18.8261	1000
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	Classifiers Correctly Trained	0.09137 (0.045484) 21; 297 79.9362; 83.0275	392	0.0949 (0.050693) 11; 299 46.2181; 54.7282	986	0.11365 (0.068465) 6; 66 12.607; 7.6007	1000
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	Classifiers Correctly Trained	0.042 (0.037184) 21; 296 65.9722; 58.72	971	0.0566 (0.057581) 11; 180 24.767; 17.939	1000	0.06785 (0.07258) 6; 49 11.915; 3.7552	1000

Provided in Table 2.6.1 is the number of times the classifier was successfully trained (denoted classifiers correctly trained). Note that for $\varepsilon = 0.05$ and $\Delta \in \{1, 1.3, 1.5, 2, 2.3, 2.5\}$ the classifier was successfully trained in less than 15% of the cases, and for $\varepsilon = 0.05$ and $\Delta = 1$ the classifier was successfully trained only once. This corresponds to a correct result in only 0.1% of the repetitions.

In calculating the average number of sequential steps, Fu et al. (2005) seem to have taken those cases into account where the classifier was not successfully trained but N = M. This seems flawed as the classifier has not been trained to such an extent to ensure that, with a probability of at least $100 (1 - \alpha) \%$, the probability of the next observation being misclassified is smaller or equal to ε . For all purposes those trained classifiers should not be used as enough evidence has not yet been obtained to show that the classifiers should perform adequately.



In those cases where the Bayes error is larger than ε the sequential procedure often fails to correctly train the classifier. When $\Delta=1$ the classifier is correctly trained at most nearly 50% of the time ($\varepsilon=0.2$). Only in those cases where ε is substantially larger than the Bayes error is the classifier correctly trained every time. The sequential procedure aims to derive a classifier that yields, with a high probability, an acceptably low rate of misclassification. If the specified rate of misclassification is unfeasible, the sequential procedure is unable to account for this and continues ad infinitum. What is required, however, is a sequential procedure that will train the classifier to obtain a feasible error rate. The researcher need not specify the feasible error rate, merely how accurately he/she wishes to estimate this error rate. This will cater specifically for those scenarios where the rate of misclassification that the researcher wishes to achieve is lower than the Bayes error.

2.6.2 Misclassification rates smaller than the Bayes error

The Bayes error is the theoretical minimum rate of achievable error for a given classifier. To calculate the Bayes error, the underlying distribution of the data, the associated parameters of these distributions, as well as the respective probabilities of sampling a random observation from each respective distribution needs to be known, and in practice this is often not the case. Therefore the Bayes error often needs to estimated rather than calculated.

In the simulation studies, particularly in Table D.2.2, Table D.2.3 and Table D.2.6 the observed misclassification rate was lower than the Bayes error. This was observed in the specific scenarios where one of the two underlying distributions exhibited more variation. The misclassification rate reported is the average of the observed misclassification rates over all iterations for each of the variable combinations of (Δ, ε) tested.

It is possible, due to sampling variation, that a calculated error rate for any particular iteration is lower than the Bayes error. A level of confidence or a measure of the error associated with the estimated error rate is required. This measure of error has been defined in the literature as Monte Carlo Error (MCE).



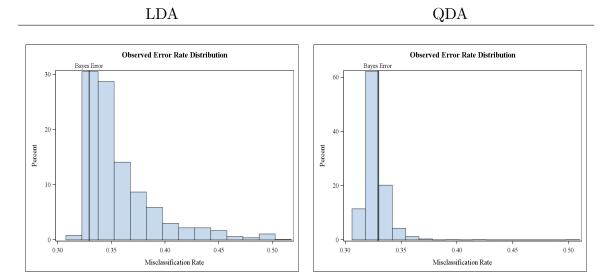


Figure 2.6.2: Observed Misclassification Rate for LDA and QDA classifiers. Results correspond to Table D.1.2 and Table D.2.2.

A visual representation of the distribution of the observed classification error is provided in Figure 2.6.2. The images display the observed misclassification rates for Table D.1.2 and Table D.2.2 respectively, for $\Delta=1$ and $\varepsilon=0.05$. In both scenarios, data was generated from a N(0,1) and a N(1,3) distribution. Although some of the observed misclassification rates for the LDA classifier is smaller than the Bayes error, the majority of the observations contributing to the average rate of observed misclassification are larger than the Bayes error, resulting in the reported value being larger than the Bayes error.

For the QDA classifier however, the majority of the contributing observations are smaller than the Bayes error. It is interesting to note how skewed both of the distributions are. Furthermore, it is also important to take into account that both sets of results were obtained from simulations where the maximum acceptable rate of error was unfeasibly low (i.e. smaller than the Bayes error). Consequently the classifiers and all parameters used in calculating the Bayes error are incomplete and the classifiers have not been successfully trained to ensure, with a high probability, a sufficiently low probability of misclassification.

Provided in Figure 2.6.3 are the distributions of the observed misclassification rate if the maximum number of allowed sequential steps in training both the LDA and the QDA classifier (for a N(0,1) distribution and a N(1,3) distribution, $\varepsilon = 0.05$ and $\alpha = 0.05$) is increased from M = 90 to M = 1000.

The distribution of the misclassification rates for M=1000 is much more symmetric than it is for M=90. For the LDA classifier, however, the distribution is still slightly skewed. Similar to Figure 2.6.2, the majority of the observations contributing to the LDA distribution are larger than the Bayes error, resulting in the observed average misclassification rate being larger than the Bayes error. For the QDA classifier, however, the



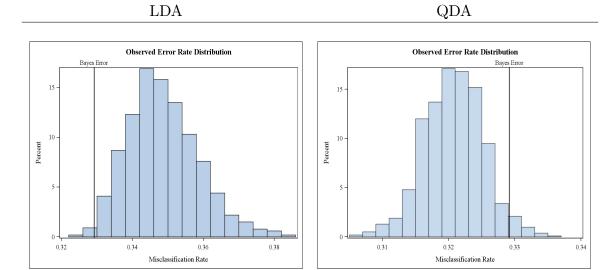


Figure 2.6.3: Observed Misclassification Rate while training the LDA and QDA classifier. 5 initial observations were generated from a N(0,1) distribution and 5 observations were generated from a N(1,3) distribution, $\alpha = 0.05$, $\Delta = 0.05$.

majority of contributing observations are smaller than the Bayes error. The distribution is also centered around a value lower than the Bayes error. This is caused mainly by the over- and under-estimation of the parameters (the mean and covariance matrices) that are used when calculating $\hat{\lambda}$. As these matrices differ from the actual population matrices for the mean and covariance, their over- and under-estimation result in unexpectedly low misclassification rates. For a fixed value of $\hat{\lambda}$, a sample covariance matrix Σ_2 that is larger than the $\hat{\Sigma}_2$ used in calculating $\hat{\lambda}$ for example results in a lower than expected probability of misclassification. Since the classifier $\hat{\lambda}$ that is used in the Bayes error calculation is the $\hat{\lambda}$ obtained from the sequential procedure, the small misclassification rates indicate that the sample covariance and mean matrices are either too large or too small.

2.6.3 Overtrained classifier

In the results presented, the observed average rate of misclassification is often lower than the specified level of acceptable error ε . This is mostly prevalent in the scenarios where there is more separation between the underlying distributions (i.e. Δ is large). In the specific scenarios where a feasible acceptable rate of error is specified, i.e. the Bayes error is smaller than ε , the classifier is trained to such an extent that the rate of misclassification it obtains is smaller than ε . Therefore the classifier is performing better than required. Usually this would not pose a problem, but in a sequential procedure this implies that more observations were sampled than needed to obtain a particular level of accuracy, and consequently the classifier is overtrained. The sequential procedure was proposed to sample only the minimum number of observations required to obtain a classifier that



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would yield a small enough rate of misclassification, but unfortunately samples more records than required and this would result in additional costs. Therefore the sequential procedure does not perform according to it's intended design.

2.7 Conclusion

In this chapter, a sequential procedure, developed to train a classifier that would yield, with a high probability, an acceptably low rate of misclassification, was discussed. The sequential procedure proposed by Fu et al. (2005) has been developed to sample the minimum number of observations necessary to train a classifier to such an extent that there is a probability of at least $100(1-\alpha)\%$ that the probability of misclassifying the next randomly sampled observation is at most ε . Therefore the sequential procedure tries to adhere to a prespecified probability of misclassifying the next randomly sampled observation, while still sampling only the minimum required number of observations.

The sequential procedure has multiple advantages: it evaluates the stopping criteria after each iteration, thereby ensuring the procedure will not sample observations unnecessarily once the stopping criteria have been met; it is not dependent on one method of classification, but rather depends only on a series of binary input variables, i.e. variables indicating whether a sampled observation was incorrectly (denoted 1) or correctly (denoted 0) classified; it recursively obtains a trained classifier that yields a specified rate of misclassification with a high probability.

Unfortunately, the sequential procedure can not account for Bayes errors larger than the prespecified maximum rate of allowable error ε . In these scenarios the sequential procedure tries to train the classifier to obtain an unfeasibly low rate of misclassification. Considering that the Bayes error is often not known, it is easy to specify a desired maximum level of acceptable error lower than the Bayes error. This results in the sequential procedure continuing ad infinitum. Additionally, the sequential procedure occasionally samples too many observations and trains the classifier to obtain an error level smaller than the specified error level. Multiple cases were observed where the average observed rate of misclassification is smaller than the prespecified acceptable level of error, ε . Therefore the classifier is trained to obtain a level of error which is smaller than required or specified.

The sequential procedure was proposed to aid in scenarios where data is not freely available, possibly due to high costs (in gathering data or the cost of a misclassification) or for some other reason, so that the classifier used could be trained with the least amount of data to ensure, with a high enough probability of at least $100 (1 - \alpha)$ %, that after



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the classifier had been successfully trained the probability of the very next observation sampled being incorrectly classified is acceptably low ε . As stated, the procedure can not account for unfeasibly low levels of specified error and continues indefinitely. Rather than trying to attain a specified rate of error, which could be impossibly low, the minimum feasible rate of error should be pursued. Therefore, a sequential procedure that ultimately yields a classifier that has been trained to accurately estimate the minimum feasible rate of error is proposed. This sequential procedure will not continue indefinitely, provided an acceptable level of accuracy is specified, and will always yield a classifier that estimates the minimum rate of error - the Bayes error.



Chapter 3

A sequential procedure for estimating the Bayes error at a predetermined level of accuracy

3.1 Introduction

In this chapter a sequential procedure, that ultimately samples the minimum number of observations required to derive a classifier that estimates the Bayes error at a predetermined level, is proposed and will be discussed. Fu et al. (2005) proposed a sequential method that samples the minimum number of observations required to train a classifier that yields prespecified rate of misclassification with a high probability. The sequential procedure, unfortunately, is unable to account for Bayes errors larger than the acceptable rate of error and continues ad infinitum. A sequential procedure that yields a classifier that can, as accurately as deemed necessary, estimate the Bayes error is proposed. Using the same approach of sequentially training a classifier, randomly sampling an observation and classifying the observation accordingly, a series of binary observations is obtained. These binary observations are used to obtain the sample rate of misclassification, which is an estimate of the Bayes error. Therefore, a confidence interval for the proportion of misclassified observations can be derived, and a sequential procedure is proposed that utilises these confidence intervals to accurately estimate the Bayes error within a halfwidth h.

A series of simulations were run to observe the sequential procedure's performance using LDA as the classification method. Furthermore, the sequential procedure is also tested on the microarray dataset. A general conclusion is provided.

3.2 Obtaining input observations

In practice it is nearly never an easy task to estimate or calculate the Bayes error. If the underlying distribution of the data is not available this task could prove very time consuming and cost-ineffective. The sequential procedure discussed by Fu et al. (2005),





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unfortunately, can not take into account cases where the specified level of acceptable error, ε , is smaller than the Bayes error.

As shown in the results obtained, the sequential procedure proposed by Fu et al. (2005) frequently reaches the prespecified maximum. Also, in simulations where the allowed maximum number of sequential steps had been removed the procedure continued ad infinitum. In the specific scenarios where the maximum is reached, the classifier obtained from the sequential procedure will, in most cases, not have been trained to such an extent to ensure, with a probability of at least $100 (1 - \alpha) \%$, that the probability of the next observation being misclassified is less than or equal to ε . No additional evidence supports the selected maximum and it could be some arbitrarily chosen number. Allowing the sequential procedure to continue ad infinitum, is not practical and is of no meaningful value.

An alternative approach to use would be to sample observations and train the classifier until the observed rate of misclassification converges towards a feasible value. This suggests an alternative approach to train the classifier. Each respective method of classification yields it's own Bayes error, provided the underlying distribution(s) and related parameters are kept constant. Since the Bayes error is the minimum feasible error, an optimally trained classifier will yield a rate of misclassification \hat{p} that estimates the Bayes error. Therefore, the proposed approach is to obtain a classifier that yields a rate of misclassification comparable to the Bayes error.

As the Bayes error is typically not known, the ideal would be for the sequential procedure to continue until the rate of misclassification stabilises within a certain range of the Bayes error, or an accurate estimate thereof. Therefore the classifier would be trained until, with a probability of at least $100 (1 - \alpha) \%$, the rate of misclassification obtained from the classifier is within h of the Bayes error, i.e. $P(MR \in [BE - h; BE + h]) \ge 1 - \alpha$, with BE denoting the Bayes error and MR denoting the misclassification rate. In essence this involves finding a fixed width confidence interval for a proportion p.

Let a correct classification be denoted by $Q_i = 0$ and an incorrect classification denoted by $Q_i = 1$. Therefore a series of binary observations are obtained from the sequential procedure, irrespective of which classification method is used. The ratio of incorrect classifications to all records classified, $\hat{p} = \sum \frac{Q_i}{n}$, is an estimate of the global rate of misclassification - the Bayes error (π) . The recursive process of sampling observations and training a classifier that yields, with a high probability, a rate of misclassification near the Bayes error can be thought of as a "Wrapping" Procedure.



The Wrapping Procedure can be summarised as follows:

- 1. Obtain an initial sample of data.
- 2. Train the classifier with all available data.
- 3. Sample one or more additional observations.
- 4. Classify the observation(s) sampled in step 3 accordingly using the trained classifier.

 Denote a correct classification with a 0 and an incorrect classification with a 1.
- 5. Calculate \hat{p} and evaluate the respective stopping criteria.
- 6. If the stopping criteria are not satisfied, return to step 2. Otherwise exit the procedure.

The Wrapping Procedure is independent of the method of classification used and produces a list of Bernoulli observations which can then be used to obtain an estimate for π within a particular accuracy level.

3.3 A sequential procedure for the estimation of a proportion

The sequential procedure proposed derives a confidence interval for the proportion of observations misclassified, as the proportion of observations misclassified is an estimate of the Bayes error. Deriving a confidence interval for a proportion p from a series of independent and identically distributed Bernoulli observations is one of the best studied problems in statistics. Many fixed-sample-size and variable-sample-size methods have already been developed and are available. Training a classifier to estimate the Bayes error at a certain level of accuracy, however, depends on a fixed-width confidence interval. A fixed width confidence interval will enable the researcher to specify to what level of accuracy he/she would like the Bayes error to be estimated, while using the minimum number of required observations. In Frey (2010) various methods for obtaining a fixed-width confidence interval for a proportion for sequential procedures are discussed. Specifics of all the methods discussed and specifics of analyses done will not be provided in this dissertation. However, an outline of the method proposed will be provided in what follows as it is the method employed in the proposed sequential approach.

In the derivation of the fixed-width confidence interval estimator, Frey (2010) notes that "fixed-sample-size methods" for obtaining a confidence interval for a proportion p



often "tend to be narrower when p is near 0 or 1 than when p is near $\frac{1}{2}$ ", stating that these methods require too many observations to estimate p at a predetermined level. Therefore, he proposed a sequential procedure that would ensure a coverage probability of at least $100 (1-\alpha)\%$ for p. Deriving the confidence interval, the author defined h to be the halfwidth of the confidence interval and the confidence interval is centered at \widehat{p} as it is the maximum likelihood estimate of p. If all values outside the interval [0,1] are excluded, a confidence interval for π is provided by $[\max(0,\widehat{p}-h), \min(1,\widehat{p}+h)]$. With the confidence interval defined, a stopping rule needs to be derived.

The first stopping rule considered in Frey (2010) is based on the Wald's confidence interval. Assume X is a binomial random variable denoting the number of successes observed in n independent trails and \widehat{p} then denotes the probability to observe a success. Therefore $X \sim Bin(n, \widehat{p})$. From the central limit theorem it is known that $X \sim N(n\widehat{p}, n\widehat{p}(1-\widehat{p}))$ and $p = \frac{X}{n} \sim N\left(\widehat{p}, \frac{\widehat{p}(1-\widehat{p})}{n}\right)$ provided n is large enough (Steyn et al., 1982). Therefore

$$Z = \frac{p - \widehat{p}}{\sqrt{\frac{\widehat{p}(1-\widehat{p})}{n}}}$$

and $Z \cong N(0,1)$ provided n is large enough.

The $100 (1-\alpha)$ % Wald's confidence interval for a proportion p is $\widehat{p}\pm z_{\alpha/2}\sqrt{\widehat{p}(1-\widehat{p})/n}$, $z_{\alpha/2}$ being the upper $\alpha/2^{th}$ percentile of a Standard Gaussian distribution, and $\widehat{p}=\frac{x}{n}$ with x being the number of successes observed. In this particular scenario a success is defined as a misclassification, i.e. $Q_i=1$. In the specific cases where $x\in\{0,n\}$ the confidence interval always has a length of 0 as $\sqrt{\widehat{p}(1-\widehat{p})/n}=0$. This is addressed by replacing the estimate of the variance with a non-zero constant $\widetilde{p}_a(1-\widetilde{p}_a)/n$, where $\widetilde{p}_a\equiv(x+a)(n+2a)$, effectively pulling \widehat{p} towards 0.5. For a chosen interval half-width of h and a>0, the sequential procedure is stopped if the adapted Wald's confidence interval $\widehat{p}\pm z_{\alpha/2}\sqrt{\widetilde{p}_a(1-\widetilde{p}_a)/n}$ in its entirety is contained in the interval $\widehat{p}\pm h$. This is analogous to stopping the sequential procedure when $\widetilde{p}_a(1-\widetilde{p}_a)/n \leq (h/z_{\alpha/2})^2$.

If a=0 the resulting confidence interval is just the nominal Wald's confidence interval for a proportion. Khan (1969) (as cited in Frey, 2010) concluded that stopping rules based on estimates of the Fisher Information worked well when fixed-width confidence intervals were required in continuous settings with nuisance parameters. In this particular scenario the Fisher Information is n/((1-p)p), for which an estimate is $(\tilde{p}_a(1-\tilde{p}_a)/n)^{-1}$. The stopping criteria for the sequential procedure proposed in this dissertation is based on this adjusted version of the fixed-sample size confidence interval. If this interval is entirely contained in $[\hat{p}-h; \hat{p}+h]$, where h is the halfwidth of the interval around the Bayes error, the sequential procedure is stopped.



Some of the other stopping rules tested by Frey (2010) were based on:

• The Wilson confidence interval for a proportion p

$$\frac{\widehat{p} + z_{\alpha/2}^2/(2n)}{1 + z_{\alpha/2}^2/n} \pm \frac{z_{\alpha/2}\sqrt{\widehat{p}(1-\widehat{p})/n + z_{\alpha/2}^2/(4n^2)}}{1 + z_{\alpha/2}^2/n}$$

• The Clopper and Pearson confidence interval for a proportion p

For
$$0 < x < n$$

$$[p_l, p_u]$$
where
$$\sum_{i=x}^{n} \binom{n}{i} p_l^i (1 - p_l)^{n-i} = \alpha/2$$

$$\sum_{i=0}^{x} \binom{n}{i} p_u^i (1 - p_u)^{n-i} = \alpha/2$$

For x = 0

 $[0, p_u]$

For x = n

 $[p_l, 1]$

Frey (2010) notes that the methods used for developing the stopping rules have flaws as fixed-sample size methods. While the Wald's confidence interval actually has a confidence coefficient of 0, the Clopper-Pearson interval's true confidence coefficient often exceeds the nominal level. Consequently, many refined methods have been developed that have a less pronounced difference between the actual confidence coefficient and the nominal confidence coefficient. Since a sequential method negates the greater control of the confidence coefficient, the author chose his specified rules.

To determine which of the sequential confidence interval methods yield the best results, Frey (2010) conducted multiple studies testing different values for h and the coverage probability $100 (1 - \alpha) \%$, calculating the mean average run length, the mean coverage probability, as well as the restricted mean coverage probability.

Frey (2010) notes that the width of the confidence intervals are always 2h, except when \hat{p} tends towards either 0 or 1, and consequently the expected length of the confidence intervals is nearly equal for all methods. An alternative measure to consider when gauging performance of a particular method is Average Run Length, and this is defined



as $ARL(p) = \sum_{i=1}^{k} H(x_i, n_i) p^{x_i} (1-p)^{n_i-x_i} n_i$. Integrating this function with regards to p from 0 to 1 yields the average of ARL(p) over all values of p, i.e. $\int_0^1 ARL(p) dp$.

The mean coverage probability is defined as $\int_0^1 T(p;\alpha) dp$ and is the average $T(p;\alpha)$ over all values of p. Frey (2010) notes that the mean coverage probability is close to 1 when $p \in [0, h]$ and $p \in [1 - h, 1]$. Due to this, the restricted mean coverage probability, defined as $(1 - 2h)^{-1} \int_h^{1-h} T(p;\alpha) dp$, is also considered. The integrals are approximated using numerical integration. Frey (2010) found that, while no approach proved to be consistently better than any other over every value of h and a tested, the adapted Wald's confidence interval provided the most flexibility. Adjusting the value of a accordingly always led to better results. Consequently this is the sequential confidence interval method that will be used further, as it is intuitively simple to understand and implement.

Frey (2010) also noted that if an actual coverage probability of $100 (1 - \alpha)$ % is desired, α should not be chosen equal to the desired value (e.g. $\alpha = 0.05$) as this would result in a confidence coefficient lower than $1 - \alpha$. Using the path-counting ideas published by Girshik, Mosteller and Savage (2006) and Schultz et al. (1973) as cited in Frey (2010), based on the fact that the confidence coefficient of α usually decreases as α is increased, Frey (2010) was able to search for a value of α that would yield a confidence coefficient tending towards $1 - \alpha$, however not being less than it. New values for α or α will not be derived in this dissertation and therefore the values obtained in Frey (2010) were used. The appropriate values for α and α are also provided for reference purposes in Table D.8.1 of Appendix D.

To derive the critical values, Frey (2010) defined $(x_1, n_1), ..., (x_k, n_k)$ as the stopping points for a fixed α and a fixed stopping rule, H(x, n) (where $n \ge 1$ and $0 \le x \le n$) as the number of ways that x successes can be obtained in n trials without reaching or equalling a stopping point prior to the n^{th} trial. Therefore, $H(x_i, n_i) p^{x_i} (1-p)^{n_i-x_i}$ is the probability to end the procedure at the point (x_i, n_i) , and $\sum_{i=1}^k H(x_i, n_i) p^{x_i} (1-p)^{n_i-x_i} = 1 \forall p \in [0, 1]$. If the stopping point is (x_i, n_i) , the confidence interval is provided by $\left[\max\left(0, \frac{x_i}{n_i} - h\right), \min\left(1, \frac{x_i}{n_i} + h\right)\right]$, with the coverage probability for p defined as

$$T(p; \alpha) \equiv \sum_{i=1}^{k} H(x_i, n_i) p^{x_i} (1-p)^{n_i-x_i} I\left(|p-\frac{x_i}{n_i}| \le h\right)$$

where I(A) is an indicator function for the event A, and the confidence coefficient is derived as $CP(\alpha) = \inf_{p \in [0,1]} T(p; \alpha)$.

As defined by Frey (2010), $T(p; \alpha)$ is a piecewise polynomial in p, with jumps at points in the set $C = \left\{ \frac{x_i}{n_i} \pm h, \ i = 1, \dots, \ k \right\} \cap [0, \ 1]$.

Frey (2010) used a two-step procedure to derive exact critical values. The first step entails, for a fixed α , approximating $CP(\alpha)$ by obtaining the minimum value of $T(p; \alpha)$



3.4. PROPOSED SEQUENTIAL PROCEDURE FOR ESTIMATING THE BAYES ERROR AT A PREDETERMINED LEVEL

over a set of values $p = c \pm \epsilon$ where $c \in C$ and $\epsilon = 10^{-10}$. Using the bisection root-finding algorithm, a value for α is obtained that ensures $CP(\alpha)$ tends towards $1 - \alpha$ while never being less than it. The second step entails ensuring that $T(p; \alpha)$ is never less than $1 - \alpha$ for the particular choice of α . This is done using a checking algorithm derived in Frey (2010). The algorithm will not be provided in this dissertation.

3.4 Proposed sequential procedure for estimating the Bayes error at a predetermined level

Using this adapted Wald's confidence interval enables the researcher to sequentially sample and train the classifier until the misclassification rate obtained is within h of the Bayes error with a certain probability. Rather than training a classifier to attain a certain misclassification rate, a classifier should be trained to attain the minimum feasible error rate. This will ensure that the classifier is always predicting as well as possible, and the sequential procedure will not continue ad infinitum. Using the adapted Wald's confidence interval derived by Frey (2010), a sequential procedure is proposed where the observed rate of misclassification converges to within h of the Bayes error. The researcher therefore has the ability to specify to what level he/she wishes to estimate the minimum feasible error, i.e. the Bayes error.

A sequential procedure is proposed where the recursive sampling, training and classifying steps are continued until the observed rate of misclassification stabilises within h of the Bayes error. The following algorithm can be used to determine the number of observations needed:

- 1. Draw an initial random sample of size N_0 and train the relevant classifier.
- 2. At the i^{th} iteration sample an additional observation and classify the sampled observation accordingly.
- 3. If the complete adapted Wald's confidence interval is contained in $\widehat{p} \pm h$ the sequential procedure can be stopped, i.e. if $\widehat{p} \pm z_{\alpha/2} \sqrt{\widetilde{p}_a (1 \widetilde{p}_a)/n} \in [\widehat{p} h; \ \widehat{p} + h]$ the sequential procedure can be stopped. This is equivalent to stopping the procedure if $z_{\alpha/2} \sqrt{\widetilde{p}_a (1 \widetilde{p}_a)/n} \leq h$.
- 4. Otherwise retrain the classifier with all observations sampled thus far and thereafter return to step 2 and continue.

Note that this is essentially the Wrapping Procedure previously discussed. Therefore the proposed sequential approach is independent of the method of classification used and only depends on a set of binary input observations.



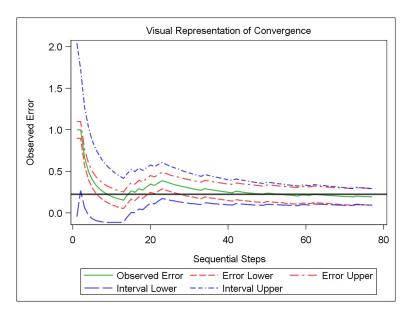


Figure 3.1: Proposed Sequential Procedure Convergence for $\Delta = 1.5$, $\alpha = 0.05$ and h = 0.1.

The convergence process of the adjusted Wald's interval towards the interval [p-h; p+h] is provided in Figure 3.1. The solid horisontal black line indicates the theoretical Bayes error, with the two outermost spiked blue curves representing the upper and lower bounds of the adapted Wald's confidence interval, denoted by Interval Upper and Interval Lower respectively. The sequential procedure continues until the two spiked red curves, denoted Error Lower and Error Upper, completely contain the adapted Wald's confidence interval's blue curves. The observed classifier error is denoted by the solid spiked green curve.

The primary advantage of this approach is that it enables the researcher to have more control over the feasible rate of misclassification, at a predetermined level. The classifier can be trained to within h of the minimum error rate obtainable, thereby lending more credibility to an obtained classifier. The researcher therefore has control to decide when the sequential procedure has to terminate, given their experimental specifications or design.

3.5 Simulation study

A series of simulations were run to observe the proposed sequential procedure's performance by comparing the observed misclassification error of the trained classifier with the theoretical error, i.e. the Bayes error. The results obtained are not directly comparable to those in Table 2.3.1 as the criteria for stopping the sequential procedures are different, and the method proposed by Fu et al. (2005) had an artificial upper bound imposed on



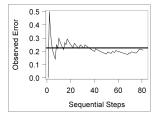
the number of observations available for sampling. It should still suffice, however, to show how the proposed sequential procedure performs.

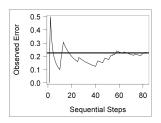
The sequential approach proposed by Fu et al. (2005) evaluates whether the probability of a misclassification is sufficiently small, whereas the proposed approach evaluates whether the adjusted confidence interval for the observed error rate is sufficiently small. It should still suffice however to show the benefits of the proposed sequential procedure. The results of the simulations can be found in Tables 3.5.2 to Tables 3.5.4.

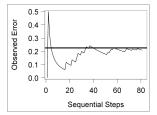
To ensure that the simulation environments were as similar as possible, the same simulation design as employed in Chapter 2 was used. 5 observations were randomly generated from a N(0, 1) distribution and 5 additional observations were randomly generated a $N(\Delta, 1)$ distribution. Once a sampled observation had been classified accordingly, the adapted Wald's confidence interval was obtained and if the complete interval was contained in $[\hat{p} - h; \hat{p} + h]$ the sequential procedure was stopped and the number of sequential steps required was recorded. Simulations were run for $h \in \{0.1, 0.05, 0.01\}$ and $\alpha \in \{0.01, 0.05, 0.1\}$, and the only classification method used was LDA. The results obtained from LDA and LRIM should be comparable, and as the underlying data is generated from two distributions with equal variances the need to use QDA is negated. If a very small value for h is chosen, the sequential procedure will most likely sample many observations. KNN is not tested in this chapter as it would be very computationally intensive to sort such large matrices for multiple iterations.



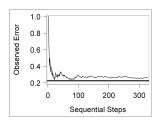
h = 0.10

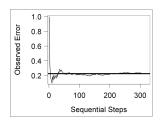


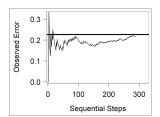




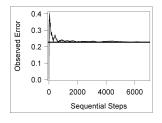
$$h = 0.05$$

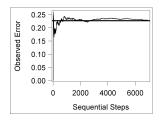






$$h = 0.01$$





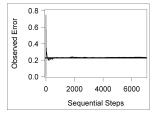


Figure 3.5.1: Observed classifier error for various values of h and $\alpha = 0.05$

A visual representation of the error rate observed in training the LDA classifier is provided in Figure 3.5.1. The observed classifier error is displayed against the total number of observations classified. The graphs are displayed for 3 iterations of the sequential procedure, for $\alpha = 0.05$, $\Delta = 1.3$ and for $h \in \{0.1, 0.05, 0.01\}$. The solid horisontal line denotes the theoretical Bayes error. As is evident in the graphs, there is a lot of initial variation in the observed rate of misclassification, but as the number of sequential steps increase (and the classifier is better trained) the rate of misclassification converges towards the Bayes error. For a large value of h = 0.1 the sequential procedure is stopped before 100 observations are sampled, but as the value of h is decreased to h = 0.01 the number of sequential steps required has increased to more than 6000. in all of these cases, though, the classifier is successfully trained and estimates the Bayes error at a predetermined level.



TABLE 3.5.2 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from aN(Δ , 1) distribution and $\alpha = 0.1$. The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		h = 0.1	h = 0.05	h = 0.01
1	0.3085	Error (Std) Min; Max \bar{n} ; Sd	0.3135 (0.009259669) 45; 80 70.302; 5.4826	0.31021 (0.005192205) 195; 282 254.73; 12.6219	0.30863 (0.004592991) 5677; 6071 5879.49; 62.822
1.3	0.2578	Error (Std) Min; Max \bar{n} ; Sd	0.26209 (0.008078367) 34; 78 65.184; 6.86887	0.2595 (0.004834442) 163; 274 230.503; 16.1511	0.25811 (0.004376857) 5016; 5495 5280.47; 79.022
1.5	0.2266	Error (Std) Min; Max \bar{n} ; Sd	0.23075 (0.006569723) 30; 77 61.194; 7.21793	0.22817 (0.00454338) 133; 254 212.825; 17.371	0.22666 (0.004228055) 4439; 5096 4840.79; 86.876
2	0.1587	Error (Std) Min; Max \bar{n} ; Sd	0.16239 (0.006593837) 30; 71 52.038; 7.28626	0.15984 (0.004088071) 100; 216 169.932; 19.6716	0.15871 (0.003642087) 3319; 4114 3698.84; 110.875
2.3	0.1251	Error (Std) Min; Max \bar{n} ; Sd	0.12846 (0.005875874) 30; 68 47.273; 7.09809	0.12649 (0.003868138) 71; 197 146.095; 20.5516	0.12512 (0.00331319) 2489; 3512 3052.72; 123.276
2.5	0.1056	Error (Std) Min; Max \bar{n} ; Sd	0.10906 (0.005922502) 30; 64 44.246; 7.05445	0.10689 (0.00364893) 71; 186 132.634; 19.7482	0.10601 (0.003167984) 2221; 3049 2652.39; 120.216
3	0.0668	Error (Std) Min; Max \bar{n} ; Sd	0.06954 (0.004779777) 30; 59 39.116; 5.65991	0.06792 (0.002998095) 63; 157 104.686; 16.7073	0.06681 (0.002481202) 1246; 2247 1805.66; 138.479
4	0.0228	Error (Std) Min; Max \bar{n} ; Sd	0.02426 (0.002619354) 30; 48 33.037; 3.3134	0.02346 (0.001840469) 63; 118 76.099; 9.726	0.022809 (0.00152069) 512; 1162 846.005; 102.639

For h=0.1 in Table 3.5.2, the maximum number of sequential steps previously imposed (M=90) is not exceeded once, yet the classifier is successfully trained for all 1000 iterations. The average number of sequential steps required to successfully train the classifier decreases from 70.302 for $\Delta=1$ to less than half of that (33.037) for $\Delta=4$. The average rate of misclassification is fractionally higher than the Bayes error, never being less than it. The standard deviation of the rate of misclassification decreases from 0.0092 for $\Delta=1$ to 0.0026 for $\Delta=4$, and are significantly lower than those observed in the initial simulation study using the method proposed by Fu et al. (2005), indicating that the observed rates of misclassification display much less variance.

For h = 0.05 the maximum number of sequential steps previously imposed (M = 90) is exceeded at least once for all Δ , and is exceeded in all iterations for $\Delta \leq 2$. For h = 0.01



the maximum number of sequential steps previously imposed (M=90) is exceeded in all iterations for all values of Δ tested. In all scenarios the average rate of misclassification is near the Bayes error, and as h decreases the standard deviation in the rate of misclassification decreases. Additionally, as h decreases from 0.1 to 0.01 the average number of sequential steps required to successfully train the classifier increases, with the most significant increase evident for $\Delta=1$.

In all of the scenarios tested, the proposed sequential procedure successfully trained the classifier to yield, with a high probability, a rate of misclassification within h of the Bayes error. The maximum number of sequential steps required to successfully train the classifier was 6071 and was observed for $\Delta=1$ and h=0.01. Therefore the sequential procedure required at most 6071 observations to ensure, with a probability of at least 90%, that the trained classifier will yield a misclassification rate within only 0.01 of the Bayes error, and on average only about 5880 observations were needed.



TABLE 3.5.3 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from aN(Δ , 1) distribution and $\alpha = 0.05$. The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		h = 0.1	h = 0.05	h = 0.01
1	0.3085	Error (Std) Min; Max	0.31251 (0.007410005) 68; 111	0.30952 (0.004871182) 307; 392	0.30865 (0.004613307) 8067; 8514
		\bar{n} ; Sd	96.818; 6.67663	354.477; 14.0576	8297.83; 76.344
1.3	0.2578	Error (Std)	0.26154 (0.00698033)	0.25867 (0.004668742)	0.25795 (0.004299132)
		Min; Max	41; 108	247; 373	7135; 7728
		\bar{n} ; Sd	88.796; 8.37248	321.256; 17.547	$7452.12;\ 97.559$
1.5	0.2266	Error (Std)	0.22966 (0.006291187)	0.22767 (0.004460538)	0.22669 (0.004227758)
		Min; Max	45; 106	235; 351	6463; 7157
		\bar{n} ; Sd	83.048; 9.50316	$296.959;\ 20.2312$	$6830.21;\ 107.814$
2	0.1587	Error (Std)	0.16159 (0.0056926)	0.15974 (0.00397432)	0.15881 (0.003733498)
_		Min; Max	41: 95	152; 301	4763; 5592
		\bar{n} ; Sd	69.544; 9.40045	236.982; 22.5843	5227.51; 132.366
2.3	0.1251	Error (Std)	0.12786 (0.005471891)	0.1261 (0.003517343)	0.12521 (0.00323402)
		Min; Max	37; 87	143; 273	3894; 4663
		\bar{n} ; Sd	62.197; 9.22894	205.718; 22.9336	4306.72; 140.696
2.5	0.1056	Error (Std)	0.10832 (0.004958729)	0.10654 (0.003442556)	0.10563 (0.002998168)
		Min; Max	37; 81	117; 256	3161; 4184
		\bar{n} ; Sd	57.992; 8.88566	186.194; 22.203	3743.74; 154.259
3	0.0668	Error (Std)	0.06908 (0.004303877)	0.06766 (0.002716346)	0.06681 (0.002484673)
-		Min; Max	37: 76	91; 217	2001; 3064
		$\bar{n}; \mathrm{Sd}$	49.609; 7.45182	147.322; 19.4157	2541.23; 154.344
4	0.0228	Error (Std)	0.02416 (0.002407678)	0.02336 (0.001695299)	0.02286 (0.001523874)
-	0 0	Min; Max	37: 58	91; 152	747; 1535
		\bar{n} ; Sd	41.021; 4.21762	108.245; 11.8624	1155.86; 126.71

Changing the level of significance from $\alpha=0.1$ to $\alpha=0.05$, as provided in Table 3.5.3, has resulted in an increase in the average number of sequential steps required to successfully train the classifier. The average observed rate of misclassification is slightly lower for $\alpha=0.05$ than for $\alpha=0.1$ as the classifier is trained to estimate the Bayes error better. The standard deviation of the observed rate of misclassification is also slightly lower than it is for $\alpha=0.1$.

For h=0.1 the maximum number of sequential steps previously imposed (M=90) is not exceeded once for $\Delta \geq 2.3$, yet the classifier is trained successfully for all 1000 iterations. The average number of sequential steps required to successfully train the classifier decreases from 96.818 for $\Delta=1$ to 41.021 for $\Delta=4$. The average rate of misclassification



is fractionally higher than the Bayes error, albeit lower than the misclassification rate observed for $\alpha = 0.1$. The standard deviation of the rate of misclassification decreases from 0.0074 for $\Delta = 1$ to 0.0023 for $\Delta = 4$.

For h=0.05 the maximum number of sequential steps previously imposed (M=90) is exceeded in all iterations for all Δ tested. For h=0.01 the maximum number of sequential steps previously imposed (M=90) is exceeded in all iterations for all values of Δ tested. In all scenarios the average rate of misclassification is again near the Bayes error, and as h decreases the standard deviation in the rate of misclassification decreases. Additionally, as h decreases from 0.1 to 0.01 the average number of sequential steps required to successfully train the classifier increases, with the most significant increase evident for $\Delta=1$.

In all of the scenarios tested, the proposed sequential procedure successfully trained the classifier to yield, with a high probability, a rate of misclassification within h of the Bayes error. The maximum number of sequential steps required to successfully train the classifier was 8514 and was observed for $\Delta = 1$ and h = 0.01. Therefore the sequential procedure required at most 8514 observations to ensure, with a probability of at least 95%, that the trained classifier will yield a misclassification rate within only 0.01 of the Bayes error, and on average only about 8298 observations were needed.



TABLE 3.5.4 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from aN(Δ ,1) distribution and $\alpha = 0.01$. The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		h = 0.1	h = 0.05	h = 0.01
1	0.3085	Error (Std) Min; Max \bar{n} ; Sd	0.31125 (0.005851223) 122; 179 161.021; 8.6423	0.30916 (0.0046575) 492; 646 602.282; 18.5281	0.3087 (0.004685672) 13954; 14604 14288.45; 97.1696
1.3	0.2578	Error (Std) Min; Max \bar{n} ; Sd	0.26004 (0.00532608) 105; 175 147.58; 10.8953	0.25873 (0.004457055) 456; 609 544.552; 23.6328	0.25805 (0.004212218) 12329; 13209 12821.81; 124.198
1.5	0.2266	Error (Std) Min; Max \bar{n} ; Sd	0.22867 (0.004922768) 82; 169 138.121; 11.3515	0.22721 (0.004310056) 421; 577 502.668; 25.0011	0.22665 (0.004269492) 11344; 12118 11745.68; 135.154
2	0.1587	Error (Std) Min; Max \bar{n} ; Sd	0.16046 (0.004505461) 71; 147 113.804; 12.3818	0.15937 (0.003687151) 286; 487 397.828; 30.5143	0.15873 (0.003740153) 8185; 9451 8985.55; 174.79
2.3	0.1251	Error (Std) Min; Max \bar{n} ; Sd	0.127 (0.004437459) 58; 134 101.765; 12.6856	0.12555 (0.003460164) 224; 435 341.235; 32.0364	0.1252 (0.00330591) 6804; 7921 7383.71; 183.92
2.5	0.1056	Error (Std) Min; Max \bar{n} ; Sd	0.10725 (0.003938885) 63; 129 94.909; 11.5608	0.10615 (0.003140704) 190; 384 306.228; 31.0325	0.10579 (0.003090732) 5692; 7053 6402.76; 206.229
3	0.0668	Error (Std) Min; Max \bar{n} ; Sd	0.06822 (0.003246723) 58; 116 80.664; 10.2337	0.0673 (0.002588731) 170; 332 237.479; 27.5531	0.06685 (0.002584759) 3583; 4887 4332.95; 206.855
4	0.0228	Error (Std) Min; Max \bar{n} ; Sd	0.02358 (0.001939936) 58; 89 65.255; 5.8563	0.02312 (0.001592048) 138; 229 168.922; 16.243	0.022905 (0.001521382) 1317; 2433 1917.24; 174.239

Changing the level of significance from $\alpha = 0.05$ to $\alpha = 0.01$, as provided in Table 3.5.4, has resulted in an increase in the average number of sequential steps required to successfully train the classifier, and for the specific scenarios where there is little separation between the underlying distributions the increases are rather significant. The average observed rate of misclassification is generally only slightly lower for $\alpha = 0.01$ than for $\alpha = 0.05$ as the classifier is trained to estimate the Bayes error better. The standard deviation of the observed rate of misclassification is also slightly lower than it is for $\alpha = 0.1$.

For h = 0.1 the maximum number of sequential steps previously imposed (M = 90) is not exceeded once for $\Delta = 4$, but the maximum is exceeded at least once for all other values of Δ tested. The average number of sequential steps required to successfully train



3.6. MICROARRAY SAMPLE DATA APPLICATION

the classifier decreases from 161.021 for $\Delta=1$ to 65.255 for $\Delta=4$. The standard deviation of the rate of misclassification decreases from 0.0058 for $\Delta=1$ to 0.0019 for $\Delta=4$.

For h=0.05 the maximum number of sequential steps previously imposed (M=90) is exceeded in all iterations for all Δ tested. For h=0.01 the maximum number of sequential steps previously imposed (M=90) is exceeded in all iterations for all values of Δ tested. In all scenarios the average rate of misclassification is again near the Bayes error, and as h decreases the standard deviation in the rate of misclassification decreases. Additionally, as h decreases from 0.1 to 0.01 the average number of sequential steps required to successfully train the classifier increases, with the most significant increase evident for $\Delta=1$.

In all of the scenarios tested, the proposed sequential procedure successfully trained the classifier to yield, with a high probability, a rate of misclassification within h of the Bayes error. The average number of sequential steps required to successfully train the classifier has increased significantly in some scenarios, while the corresponding average rate of misclassification has decreased only slightly. Therefore, it seems unnecessary to use a 1% level of significance as the improvement in the rate of misclassification is somewhat out-weighed by the increase in the required number of observations.

3.6 Microarray sample data application

The sequential procedure proposed is also applied to the Microarray dataset used by Van't Veer et al. (2002) and Van de Vijver et al. (2002). The proposed sequential approach will truly train the classifier to be as feasibly accurate as the researcher decides. The classifier will be trained sequentially until there is a high probability that the obtained classifier yields an error rate that is within a predetermined level of the minimum possible error.

To test the proposed sequential procedure's performance on the sample data, the same study design as noted previously was used. The only classification method tested was LDA and the results are provided in Table 3.6.1. The results presented in Table 3.6.1 are not directly comparable to those presented in Table 2.5.1 as the latter have an artificially imposed upper limit on the allowable number of observations to be sampled $(M \in \{50; 80\})$. The results presented in Table 3.6.1 should still display the proposed procedure's ability to optimally train the classifier using the least number of observations. As there are no artificial upper limits imposed on the allowable number of sequential steps, the procedure is allowed to train the classifier to estimate the Bayes error to within a certain level.



3.6. MICROARRAY SAMPLE DATA APPLICATION

TABLE 3.6.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier on the sample data. The initial sample sizes are provided. $\alpha = 0.05$ and the minimum, maximum, mean and standard deviation of the number of sequential steps required to train the LDA classifier on the 3 genes most highly correlated to the prognosis variable is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Initial Sample Sizes	h		$\alpha = 0.1$	$\alpha = 0.05$	$\alpha = 0.01$
(5,5)	0.1	Error (Std) Min; Max	0.23994 (0.02424) 30; 77	0.23694 (0.02541) 52; 104	0.23409 (0.03176) 105; 164
(5,5)	0.05	\bar{n} ; Sd Error (Std) Min; Max	63.331; 6.0271 0.23502 (0.05111) 175; 244	86.804; 7.1331 0.26718 (0.27862) 267; 295	141.414; 8.7104 . (.) 295; 295
(5.5)	0.01	\bar{n} ; Sd Error (Std)	219.452; 11.0024 . (.)	294.424; 3.1327 . (.)	295; 0 . (.)
		$\begin{array}{l} \text{Min; Max} \\ \bar{n}; \text{Sd} \end{array}$	295; 295 295; 0	295; 295 295; 0	295; 295 295; 0
(10.10)	0.1	Error (Std) Min; Max \bar{n} ; Sd	0.23842 (0.02422) 40; 78 62.743; 5.9115	0.23688 (0.0272) 52; 105 85.772; 7.6089	0.23427 (0.0332) 105; 164 140.482; 9.3986
(10.10)	0.05	Error (Std) Min; Max	0.23618 (0.0558) 170; 250	0.22959 (0.23132) 247; 295	. (.) 295; 295
(10.10)	0.01	\bar{n} ; Sd Error (Std) Min; Max \bar{n} ; Sd	218.457; 10.733 . (.) 295; 295 295; 0	294.814; 2.33728 . (.) 295; 295 295; 0	295; 0 . (.) 295; 295 295; 0

For the same h and α in Table 3.6.1, the average number of sequential steps required to successfully train the classifier does not seem to be influenced by the number of observations initially sampled. A similar result was evident in Table 2.5.1. As h decreases, for the same α , the average rate of misclassification also decreases - provided an iteration of the simulation did not use all observations available to try and train the classifier.

In the specific example where the initial number of observations sampled are (5, 5) and $\alpha = 0.05$, the sequential procedure reached the maximum number of observations available for training the classifier more than once during the simulation. Consequently - the classifiers were not successfully trained in these cases. Additionally - no observations remained to test against. It is also evident in scenarios where h = 0.01 that the sample was too small to successfully train any classifiers, irrespective of the initial samples selected or their respective sizes.



3.7. CONCLUSION

Comparing the results in Table 3.6.1 to Table 2.5.1, the average rate of misclassification is similar but the average number of sequential steps required to successfully train the classifier is significantly larger. This is due to the fact that no artificial upper limits were imposed on the allowable number of sampled observations.

In this particular scenario the proposed sequential procedure allows the researcher to optimally train the classifier based on the researcher's study design. It provides the researcher with control over how accurately the classifier should estimate the minimum feasible error. The proposed sequential procedure will also never continue to train the classifier indefinitely to try and obtain an unfeasibly low level of error.

3.7 Conclusion

In this chapter, a sequential procedure, developed to sample the minimum number of observations required to train a classifier that would yield an error rate comparable to the Bayes error, was proposed and discussed. The sequential procedure proposed by Fu et al. (2005) tries to train a classifier that yields a prespecified probability of misclassifying the next randomly sampled observation, while sampling only the minimum required number of observations. If the error rate specified is too low, as can easily be the case considering that the Bayes error is often not known, the sequential procedure proposed by Fu et al. (2005) will not stop. The sequential procedure proposed in this dissertation, however, trains the classifier to such an extent that the error rate obtained is within h of the minimum feasible error rate, i.e. the Bayes error, with a high probability. A series of binary observations are returned from each iteration of the sequential procedure and used to obtain the rate of misclassification - an estimate of the Bayes error. A variance adjusted confidence interval for the population rate of misclassification is obtained, and once the variance adjusted confidence interval is completely contained in a fixed width confidence interval for the rate of misclassification, the sequential procedure is stopped. Consequently, the researcher now has the ability to specify how accurate the classifier should be and the sequential procedure proposed can not train the classifier to yield an unfeasible rate of error.

Considering that the most frequently used level of significance is $\alpha=0.05$, it is interesting to note, from the simulation study, that a mere 8300 observations are on average necessary to train a LDA classifier that will yield a rate of misclassification within just 0.01 of the Bayes error. Usually researchers prefer to use as much data as they have available (costs and time already taken into account) and implicitly trust that using most of the data will yield the most accurate classifier - the researcher does not specify how accurate the classifier should be. This result, however, shows that large amounts of data



3.7. CONCLUSION

are not necessarily needed to obtain an accurate classifier, and using less data to derive a classifier that is as accurate as need be is of great value. Not only will using less data save processing time, but it could have a significant impact on the cost of the study. Additionally, if the cost of sampling more observations is not as important, the observations not used in classifier training can be used as testing data. One of the most important features of the proposed sequential procedure is the ability it provides to the researcher to specify his/her own acceptable level of accuracy, and it removes the possibility of choosing an unfeasibly low level of error.

The sequential procedure has multiple advantages: it evaluates the stopping criteria after each iteration, thereby ensuring the procedure will not sample observations unnecessarily once the stopping criteria have been met; it is not dependent on one method of classification, but rather depends only on a series of binary input variables, i.e. variables indicating whether a sampled observation was incorrectly (denoted 1) or correctly (denoted 0) classified; it recursively obtains a trained classifier that yields an optimised rate of misclassification with a high probability; it enables the researcher to dictate how accurately the Bayes error should be estimated.

The sequential procedure proposed does, however, have a few minor shortcomings. Due to the recursive nature of the process, computationally intensive classification methods like KNN take substantially longer to complete. This, however, is true of any sequential procedure and does not only apply to the proposed sequential procedure. Another shortcoming of the procedure currently is that the critical values α and a need to be specified beforehand. It is, however, possible to include the necessary steps to derive these values beforehand. This would enable the researcher to only specify the values of h and α .

The sequential procedure was proposed to aid in scenarios where data is not freely available, possibly due to high costs (in gathering data or the cost of a misclassification) or for some other reason, so that the classifier could be trained with the least amount of data to ensure, with a high enough probability of at least $100 (1 - \alpha)$ %, that after the classifier had been successfully trained the probability of the very next observation sampled being incorrectly classified is comparable to the minimum possible error, i.e. the Bayes error. The proposed sequential procedure addresses the most serious shortcoming of the sequential procedure proposed by Fu et al. (2005), and the proposed sequential procedure will never attempt to train the classifier to obtain an unfeasible rate of error. Therefore, the sequential procedure will always yield a result - provided h is large enough.



Chapter 4

General conclusion

Determining the correct sample size is of utmost importance, as samples that are too small will yield unreliable results. Samples that are very large will often yield parameters or estimates that have greater predictive ability. In scenarios where there is no or little cost involved, the researcher dictates to what level of accuracy he/she would like the parameter to be estimated. Numerous fixed sample size methods have been developed, like Stein's two stage sampling procedure, to aid in estimating the necessary sample size required to obtain the parameter estimate within a prespecified level of accuracy.

In scientific studies, for example, there are often limits imposed on the number of observations available to train a classifier or estimate an unknown parameter. These limits are usually determined by the financial cost involved in obtaining the necessary observations, as well as the time involved. In these scenarios the researcher may wish to still obtain an accurate estimate for the unknown parameter while minimising the number of observations required to obtain the estimate. This could ultimately save both time and money. There are numerous sequential procedures available that will seek the minimum number of observations required to meet some predetermined stopping criteria. One such an approach had previously been developed that would continually train and test a classifier until there was a large enough probability that the probability of the next observation sampled being classified incorrectly was acceptably small.

The sequential procedure could train a classifier until there was a high level of certainty that an additionally sampled observation would most likely not be misclassified. The procedure is independent of the method of classification used. Therefore any classification method could be used, provided a series of dichotomous observations could be obtained. Unfortunately the sequential procedure can not account for scenarios where the maximum allowable rate of error (as dictated by the researcher) is unfeasibly low (i.e. lower than the Bayes error), ultimately resulting in the sequential procedure processing ad infinitum. The procedure occasionally samples too many observations and trains the classifier to obtain a level of error smaller than the specified value. In specific scenarios where a large cost is involved in sampling or false-positives, the procedure provides unsatisfactory results.





An alternative sequential procedure is developed that trains the classifier to an optimal level. The classifier is trained until the observed rate of error has converged to the Bayes error - the theoretical minimum error rate. The proposed sequential procedure is independent of the method of classification used and depends only on a series of Bernoulli observations. The proposed sequential procedure will never train the classifier to obtain an unfeasibly low rate of error. This procedure provides the researcher with a feasible way to train the classifier, knowing that the classifier obtained will perform as well as is feasibly possible from the underlying data.

The application for large datasets is just as interesting. The proposed sequential procedure provides the researcher with a measure of how accurate the obtained classifier actually is. Although more data is usually preferable, it might no longer be necessary to use as much data. The researcher is able to dictate how accurately he/she wishes the classifier be trained, and the obtained classifier will always perform at an optimal level estimating the Bayes error.

Future work could comprise of including the necessary logic to automatically obtain the critical values α and a, as these values need to be specified currently. Additionally, the procedure could be tested on the other classification methods (QDA, KNN and LRIM) not tested here. A simulation could also be conducted using the sequential procedure proposed by Fu et al. (2005) to test the specific scenario where ε is marginally larger than the Bayes error. Currently, the artificial upper bounds imposed, both M and N_0 , inhibit the sequential procedure from successfully training the classifier to ensure, with a probability of at least $100 (1 - \alpha) \%$, that the probability of the next observation sampled being misclassified is at most ε . The actual unimpeded number of required observations should be compared to the number obtained from the newly proposed sequential procedure.



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Appendix A

Linear discriminant analysis (LDA)

A.1 Obtaining the linear discriminant function

From statistical decision theory, it is known that the optimal classification can be obtained if the class posteriors are known, i.e. if $P(class \ G|X=x)$ is known. If $f_k(x)$ is the class-conditional density of X for class G=k, the prior probability of class k is denoted by π_k and $\Sigma_{k=1}^K \pi_k = 1$, where K is the total number of classes, using the Bayes Theorem the class posterior for class k can be written as:

$$P(G = k|X = \underline{x}) = \frac{f_k(\underline{x})\pi_k}{\sum_{l=1}^K f_l(\underline{x})\pi_l}$$

If each class density is then modelled as a multivariate Gaussian, the density function of class k is given by:

$$f_k(\underline{x}) = \frac{1}{(2\pi)^{p/2} \left|\boldsymbol{\Sigma}_k\right|^{1/2}} e^{-\frac{1}{2} \left(\underline{x} - \underline{\mu}_k\right)^T \boldsymbol{\Sigma}_k^{-1} \left(\underline{x} - \underline{\mu}_k\right)}$$

where $\underline{\mu}_k$ is a $p \times 1$ matrix that denotes the population mean for class k, Σ_k is a $p \times p$ matrix denoting the population covariance matrix for class k, \underline{v}^T denotes the transpose of \underline{v} and \underline{x} is a p-dimensional row vector.

Consider now the specific case where all the classes have a common covariance matrix $\Sigma_k = \Sigma \forall k$.

Hastie, Tibshirani and Friedman (2001) notes that looking at the log ratio of the class posteriors is sufficient for comparing any two classes, k and l.



A.1. OBTAINING THE LINEAR DISCRIMINANT FUNCTION

Therefore the following holds:

$$\begin{split} \log \frac{P(G=k|X=\underline{x})}{P(G=l|X=\underline{x})} &= \log \frac{\sum_{j=1}^{f_k(\underline{x})\pi_k} \sum_{j=1}^{f_j(\underline{x})} j_j(\underline{x})\pi_j}{\int_{f_j(\underline{x})\pi_l} \sum_{j=1}^{f_j(\underline{x})} j_j(\underline{x})\pi_j} \\ &= \log \left(\frac{f_k(\underline{x})}{f_l(\underline{x})}\right) + \log \left(\frac{\pi_k}{\pi_l}\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) + \\ \log \left(\left(\frac{e^{-\frac{1}{2}\left(x-\mu_k\right)^T \mathbf{\Sigma}_k^{-1}\left(x-\mu_k\right)}}{(2\pi)^{p/2}|\mathbf{\Sigma}_k|^{1/2}}\right) / \left(\frac{e^{-\frac{1}{2}\left(x-\mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(x-\mu_l\right)}}{(2\pi)^{p/2}|\mathbf{\Sigma}_l|^{1/2}}\right)\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) + \log \left(\left(\frac{(2\pi)^{p/2}|\mathbf{\Sigma}_l|^{1/2}}{(2\pi)^{p/2}|\mathbf{\Sigma}_l|^{1/2}}\right) \left(\frac{e^{-\frac{1}{2}\left(x-\mu_k\right)^T \mathbf{\Sigma}_l^{-1}\left(x-\mu_k\right)}}{e^{-\frac{1}{2}\left(x-\mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(x-\mu_l\right)}}\right)\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) + \log \left(\left(\frac{(2\pi)^{p/2}|\mathbf{\Sigma}_l|^{1/2}}{(2\pi)^{p/2}|\mathbf{\Sigma}_l|^{1/2}}\right) \left(\frac{e^{-\frac{1}{2}\left(x-\mu_k\right)^T \mathbf{\Sigma}_l^{-1}\left(x-\mu_k\right)}}{e^{-\frac{1}{2}\left(x-\mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(x-\mu_l\right)}}\right)\right) \\ &= \operatorname{since} \Sigma_k = \Sigma \forall k \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) + \log \left(e^{-\frac{1}{2}\left(x-\mu_k\right)^T \mathbf{\Sigma}_l^{-1}\left(x-\mu_k\right) + \frac{1}{2}\left(x-\mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(x-\mu_l\right)}\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) - \frac{1}{2}\left(x-\mu_k\right)^T \mathbf{\Sigma}_l^{-1}\left(x-\mu_k\right) + \frac{1}{2}\left(x-\mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(x-\mu_l\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) - \frac{1}{2}\left(x^T \mathbf{\Sigma}_l^{-1} x - x^T \mathbf{\Sigma}_l^{-1} \mu_k - \mu_l^T \mathbf{\Sigma}_l^{-1} x + \mu_l^T \mathbf{\Sigma}_l^{-1} \mu_l\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) - \frac{1}{2}\left(\mu_k + \mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) + \frac{x}{2}^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) - \frac{1}{2}\left(\mu_k + \mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) + \frac{x}{2}^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) - \frac{1}{2}\left(\mu_k + \mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) + \frac{x}{2}^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) - \frac{1}{2}\left(\mu_k + \mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) + \frac{x}{2}^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) - \frac{1}{2}\left(\mu_k + \mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) + \frac{x}{2}^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) - \frac{1}{2}\left(\mu_k + \mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) + \frac{x}{2}^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) - \frac{1}{2}\left(\mu_k + \mu_l\right)^T \mathbf{\Sigma}_l^{-1}\left(\mu_k - \mu_l\right) + \frac{x}{2}^T \mathbf{\Sigma}_l^{-1}\left(\mu_k\right) + \frac{x}{2}^T$$

which is a linear equation in x. The linear discriminant functions can be defined as:

$$\delta_k (\underline{x}) = \underline{x}^T \mathbf{\Sigma}^{-1} \underline{\mu}_k - \frac{1}{2} \underline{\mu}_k^T \mathbf{\Sigma}^{-1} \underline{\mu}_k + \log \pi_k$$

If the parameters are not known, sample estimates for $\underline{\pi}_k$, $\underline{\mu}_k$ and Σ can be used. Therefore:

1.
$$\widehat{\pi}_k = \frac{N_k}{\sum_{l=1}^K N_l}$$

2.
$$\widehat{\mu}_k = \frac{\Sigma_{x \in k} \underline{x}}{N_k}$$

3.
$$\widehat{\Sigma} = \sum_{k=1}^K \sum_{x \in k} (\underline{x} - \widehat{\underline{\mu}}_k) (\underline{x} - \widehat{\underline{\mu}}_k)^T / (N - K)$$



A.2 Determining the decision boundary between class 1 and 2 using LDA

LDA assumes that $\Sigma_k = \Sigma \ \forall k$ where k are the classes. Assume there are two classes, denoted 1 and 2.

The linear discriminant function for class 1 is given by:

$$\delta_1(\underline{x}) = \underline{x}^T \mathbf{\Sigma}^{-1} \underline{\mu}_1 - \frac{1}{2} \underline{\mu}_1^T \mathbf{\Sigma}^{-1} \underline{\mu}_1 + \log(\pi_1)$$

where $X \sim N(\underline{\mu}_1, \Sigma_1^2)$ and π_1 is the probability of selecting a random variable from class 1.

Similar for class 2 the linear discriminant function for class 2 is given by:

$$\delta_2(\underline{x}) = \underline{x}^T \mathbf{\Sigma}^{-1} \underline{\mu}_2 - \frac{1}{2} \underline{\mu}_2^T \mathbf{\Sigma}^{-1} \underline{\mu}_2 + \log(\pi_2)$$

where $X \sim N(\underline{\mu}_2, \Sigma_2^2)$ and π_2 is the probability of selecting a random variable from class 2.

For both class 1 and 2, assume the multidimensional space - R^p . Setting $\delta_1(\underline{x}) = \delta_2(\underline{x})$ the following holds:

$$\delta_{1}(\underline{x}) = \delta_{2}(\underline{x})$$

$$\underline{x}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{1} - \frac{1}{2} \underline{\mu}_{1} \mathbf{\Sigma}^{-1} \underline{\mu}_{1} + \log(\pi_{1}) = \underline{x}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{2} - \frac{1}{2} \underline{\mu}_{2}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{2} + \log(\pi_{2})$$

$$\underline{x}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{1} - \underline{x}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{2} = \log(\pi_{2}) - \log(\pi_{1}) + \frac{1}{2} \left(\underline{\mu}_{1}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{1} - \underline{\mu}_{2}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{2} \right)$$

$$\underline{x}^{T} \mathbf{\Sigma}^{-1} \left(\underline{\mu}_{1} - \underline{\mu}_{2} \right) = \log(\frac{\pi_{2}}{\pi_{1}}) + \frac{1}{2} \left(\underline{\mu}_{1}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{1} - \underline{\mu}_{2}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{2} \right)$$

where an observation is classified as coming from class 1 if

$$\underline{x}^T \mathbf{\Sigma}^{-1} \left(\underline{\mu}_1 - \underline{\mu}_2 \right) > \log(\frac{\pi_2}{\pi_1}) + \frac{1}{2} \left(\underline{\mu}_1^T \mathbf{\Sigma}^{-1} \underline{\mu}_1 - \underline{\mu}_2^T \mathbf{\Sigma}^{-1} \underline{\mu}_2 \right)$$

and from class 2 otherwise.

Alternatively, an observation is classified as coming from class 2 if

$$\underline{x}^{T} \mathbf{\Sigma}^{-1} \left(\underline{\mu}_{2} - \underline{\mu}_{1} \right) \geq \log(\frac{\pi_{1}}{\pi_{2}}) + \frac{1}{2} \left(\underline{\mu}_{2}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{2} - \underline{\mu}_{1}^{T} \mathbf{\Sigma}^{-1} \underline{\mu}_{1} \right)$$

and from class 1 otherwise.



A.2. DETERMINING THE DECISION BOUNDARY BETWEEN CLASS 1 AND 2 USING LDA

 π_1 can be estimated by $\widehat{p}_1 = \frac{n_1}{n_1 + n_2}$. Similarly π_2 can be estimated by $\widehat{p}_2 = \frac{n_2}{n_1 + n_2}$. $\underline{\mu}_1$ and $\underline{\mu}_2$ can be estimated from the sample means for class 1 and class 2 respectively, namely $\underline{\widehat{\mu}}_1$ and $\underline{\widehat{\mu}}_2$ respectively. Similarly $\widehat{\Sigma} = \sum_{k=1}^2 \sum_{x \in k} (\underline{x} - \underline{\widehat{\mu}}_k) (\underline{x} - \underline{\widehat{\mu}}_k)^T / (N-2)$.

This leads to the following:

Classify an observation as coming from class 2 if:

$$\underline{x}^{T}\widehat{\Sigma}^{-1}\left(\underline{\widehat{\mu}}_{2}-\underline{\widehat{\mu}}_{1}\right) \geq \log\left(\frac{\widehat{p}_{1}}{\widehat{p}_{2}}\right) + \frac{1}{2}\left(\underline{\widehat{\mu}}_{2}^{T}\widehat{\Sigma}^{-1}\underline{\widehat{\mu}}_{2}-\underline{\widehat{\mu}}_{1}^{T}\widehat{\Sigma}^{-1}\underline{\widehat{\mu}}_{1}\right)
x \geq \left(\log\left(\frac{\widehat{p}_{1}}{\widehat{p}_{2}}\right) + \frac{1}{2}\left(\underline{\widehat{\mu}}_{2}^{T}\widehat{\Sigma}^{-1}\underline{\widehat{\mu}}_{2}-\underline{\widehat{\mu}}_{1}^{T}\widehat{\Sigma}^{-1}\underline{\widehat{\mu}}_{1}\right)\right)\left(\widehat{\Sigma}^{-1}\left(\underline{\widehat{\mu}}_{2}-\underline{\widehat{\mu}}_{1}\right)\right)^{-1}
\text{provided } \widehat{\Sigma}^{-1}\left(\underline{\widehat{\mu}}_{2}-\underline{\widehat{\mu}}_{1}\right) \text{ is invertible}$$

and coming from class 1 otherwise.

In the case where the prior probabilities are known:

Let $\hat{p}_1 = \hat{p}_2 = 0.5$. Classify an observation as coming from class 2 if:

$$\begin{split} \underline{x}^T \widehat{\boldsymbol{\Sigma}}^{-1} \left(\widehat{\underline{\mu}}_2 - \widehat{\underline{\mu}}_1 \right) & \geq & \log \left(\frac{\widehat{p}_1}{\widehat{p}_2} \right) + \frac{1}{2} \left(\widehat{\underline{\mu}}_2^T \widehat{\boldsymbol{\Sigma}}^{-1} \widehat{\underline{\mu}}_2 - \widehat{\underline{\mu}}_1^T \widehat{\boldsymbol{\Sigma}}^{-1} \widehat{\underline{\mu}}_1 \right) \\ & = & \log \left(1 \right) + \frac{1}{2} \left(\widehat{\underline{\mu}}_2^T \widehat{\boldsymbol{\Sigma}}^{-1} \widehat{\underline{\mu}}_2 - \widehat{\underline{\mu}}_1^T \widehat{\boldsymbol{\Sigma}}^{-1} \widehat{\underline{\mu}}_1 \right) \\ & = & \frac{1}{2} \left(\widehat{\underline{\mu}}_2^T \widehat{\boldsymbol{\Sigma}}^{-1} \widehat{\underline{\mu}}_2 - \widehat{\underline{\mu}}_1^T \widehat{\boldsymbol{\Sigma}}^{-1} \widehat{\underline{\mu}}_1 \right) \end{split}$$

Consider now the case where p = 1. For ease of use $\widehat{\Sigma}$ can be written as $\widehat{\sigma}^2$. Classify an observation as coming from class 2 if:

$$x \geq \frac{\left(\widehat{\mu}_{2}^{2}\left(\widehat{\sigma^{2}}\right)^{-1} - \widehat{\mu}_{1}^{2}\left(\widehat{\sigma^{2}}\right)^{-1}\right)}{2\left(\widehat{\sigma^{2}}\right)^{-1}\left(\widehat{\mu}_{2} - \widehat{\mu}_{1}\right)}$$

$$= \frac{\left(\widehat{\mu}_{2}^{2} - \widehat{\mu}_{1}^{2}\right)}{2\left(\widehat{\mu}_{2} - \widehat{\mu}_{1}\right)}$$

$$= \widehat{\lambda}$$



Appendix B

Quadratic discriminant analysis (QDA)

B.1 Obtaining the quadratic discriminant function

$$\begin{split} \log \frac{P\left(G = k | X = \underline{x}\right)}{P\left(G = l | X = \underline{x}\right)} &= \log \frac{f_k(\underline{x})\pi_k}{f_l(\underline{x})\pi_l} \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) + \log \left(\left(\frac{(2\pi)^{p/2} | \Sigma_l|^{1/2}}{(2\pi)^{p/2} | \Sigma_k|^{1/2}}\right) \left(\frac{e^{-\frac{1}{2}\left(\underline{x} - \underline{\mu}_k\right)^T \Sigma_k^{-1}\left(\underline{x} - \underline{\mu}_k\right)}}{e^{-\frac{1}{2}\left(\underline{x} - \underline{\mu}_l\right)^T \Sigma_l^{-1}\left(\underline{x} - \underline{\mu}_l\right)}}\right) \right) \\ &= \log \left(\frac{\pi_k}{\pi_l}\right) + \log \left(\frac{(2\pi)^{p/2} | \Sigma_l|^{1/2}}{(2\pi)^{p/2} | \Sigma_k|^{1/2}}\right) + \log \left(\frac{e^{-\frac{1}{2}\left(\underline{x} - \underline{\mu}_l\right)^T \Sigma_l^{-1}\left(\underline{x} - \underline{\mu}_l\right)}}{e^{-\frac{1}{2}\left(\underline{x} - \underline{\mu}_l\right)^T \Sigma_l^{-1}\left(\underline{x} - \underline{\mu}_l\right)}}\right) \\ &= \log \pi_k - \log \pi_l + \log \left(\frac{|\Sigma_l|^{1/2}}{|\Sigma_k|^{1/2}}\right) + \log \left(e^{-\frac{1}{2}\left(\underline{x} - \underline{\mu}_k\right)^T \Sigma_l^{-1}\left(\underline{x} - \underline{\mu}_k\right)}\right) \\ &- \log \left(e^{-\frac{1}{2}\left(\underline{x} - \underline{\mu}_l\right)^T \Sigma_l^{-1}\left(\underline{x} - \underline{\mu}_l\right)}\right) \\ &= \log \pi_k - \log \pi_l + \frac{1}{2}\log |\Sigma_l| - \frac{1}{2}\log |\Sigma_k| - \frac{1}{2}\left(\underline{x} - \underline{\mu}_l\right)^T \Sigma_l^{-1}\left(\underline{x} - \underline{\mu}_l\right) \\ &= \left(\log \pi_k - \frac{1}{2}\log |\Sigma_k| - \frac{1}{2}\left(\underline{x} - \underline{\mu}_k\right)^T \Sigma_k^{-1}\left(\underline{x} - \underline{\mu}_k\right)\right) \\ &- \left(\log \pi_l - \frac{1}{2}\log |\Sigma_l| - \frac{1}{2}\left(\underline{x} - \underline{\mu}_l\right)^T \Sigma_l^{-1}\left(\underline{x} - \underline{\mu}_l\right)\right) \end{split}$$

leading to the quadratic discriminant functions:

$$\delta_k(\underline{x}) = \log \pi_k - \frac{1}{2} \log |\mathbf{\Sigma}_k| - \frac{1}{2} \left(\underline{x} - \underline{\mu}_k\right)^T \mathbf{\Sigma}_k^{-1} \left(\underline{x} - \underline{\mu}_k\right)$$

If the number of dimensions p in R^p is large the number of parameters can increase substantially. If the necessary parameters are not known, sample estimates for π_k , $\underline{\mu}_k$ and Σ_k can again be used.



B.2 Determining the decision boundary between class1 and 2 using QDA

QDA does not have the assumption that $\Sigma_k = \Sigma \ \forall k$, as LDA does. Assume there are two classes, denoted 1 and 2.

The linear discriminant function for class 1 is given by:

$$\delta_{1}\left(\underline{x}\right) = \log \pi_{1} - \frac{1}{2}\log |\mathbf{\Sigma}_{1}| - \frac{1}{2}\left(\underline{x} - \underline{\mu}_{1}\right)^{T}\mathbf{\Sigma}_{1}^{-1}\left(\underline{x} - \underline{\mu}_{1}\right)$$

where $X \sim N(\underline{\mu}_1, \Sigma_1^2)$ and π_1 is the probability of selecting a random variable from class 1.

Similar for class 2 the linear discriminant function for class 2 is given by:

$$\delta_{2}\left(\underline{x}\right) = \log \pi_{2} - \frac{1}{2}\log |\mathbf{\Sigma}_{2}| - \frac{1}{2}\left(\underline{x} - \underline{\mu}_{2}\right)^{T}\mathbf{\Sigma}_{2}^{-1}\left(\underline{x} - \underline{\mu}_{2}\right)$$

where $X \sim N(\underline{\mu}_2, \Sigma_2^2)$ and π_2 is the probability of selecting a random variable from class 2.

For both class 1 and 2, assume the multidimensional space - \mathbb{R}^p .

Setting $\delta_1(\underline{x}) = \delta_2(\underline{x})$ the following holds:

$$\begin{split} &\delta_1(x) = \delta_2(x) \\ &\log \pi_1 - \frac{1}{2} \log |\mathbf{\Sigma}_1| - \frac{1}{2} \left(\underline{x} - \underline{\mu}_1\right)^T \mathbf{\Sigma}_1^{-1} \left(\underline{x} - \underline{\mu}_1\right) = \log \pi_2 - \frac{1}{2} \log |\mathbf{\Sigma}_2| - \frac{1}{2} \left(\underline{x} - \underline{\mu}_2\right)^T \mathbf{\Sigma}_2^{-1} \left(\underline{x} - \underline{\mu}_2\right) \\ &\frac{1}{2} \left[\left(\underline{x} - \underline{\mu}_2\right)^T \mathbf{\Sigma}_2^{-1} \left(\underline{x} - \underline{\mu}_2\right) - \left(\underline{x} - \underline{\mu}_1\right)^T \mathbf{\Sigma}_1^{-1} \left(\underline{x} - \underline{\mu}_1\right) \right] = \log \pi_2 - \frac{1}{2} \log |\mathbf{\Sigma}_2| - \log \pi_1 + \frac{1}{2} \log |\mathbf{\Sigma}_1| \end{split}$$

where an observation is classified as coming from class 1 if

$$\frac{1}{2}\left[\left(\underline{x}-\underline{\mu}_{2}\right)^{T}\boldsymbol{\Sigma}_{2}^{-1}\left(\underline{x}-\underline{\mu}_{2}\right)-\left(\underline{x}-\underline{\mu}_{1}\right)^{T}\boldsymbol{\Sigma}_{1}^{-1}\left(\underline{x}-\underline{\mu}_{1}\right)\right]>\log\pi_{2}-\frac{1}{2}\log|\boldsymbol{\Sigma}_{2}|-\log\pi_{1}+\frac{1}{2}\log|\boldsymbol{\Sigma}_{1}|$$

and from class 2 otherwise.

Alternatively, an observation is classified as coming from class 2 if

$$\frac{1}{2}\left[\left(\underline{x}-\underline{\mu}_1\right)^T\boldsymbol{\Sigma}_1^{-1}\left(\underline{x}-\underline{\mu}_1\right)-\left(\underline{x}-\underline{\mu}_2\right)^T\boldsymbol{\Sigma}_2^{-1}\left(\underline{x}-\underline{\mu}_2\right)\right]\geq \log\frac{\pi_1}{\pi_2}-\frac{1}{2}\log|\boldsymbol{\Sigma}_1|+\frac{1}{2}\log|\boldsymbol{\Sigma}_2|$$

, and from class 1 otherwise.



B.2. DETERMINING THE DECISION BOUNDARY BETWEEN CLASS 1 AND 2 USING QDA

 π_1 can be estimated by $\widehat{p}_1 = \frac{n_1}{n_1 + n_2}$. Similarly π_2 can be estimated by $\widehat{p}_2 = \frac{n_2}{n_1 + n_2}$. $\underline{\mu}_1$ and $\underline{\mu}_2$ can be estimated from the sample means for class 1 and class 2 respectively, namely $\underline{\widehat{\mu}}_1$ and $\underline{\widehat{\mu}}_2$ respectively. Similarly Σ_1 and Σ_2 can be estimated from the sample covariance matrices for class 1 and class 2 respectively, namely $\widehat{\Sigma}_1$ and $\widehat{\Sigma}_2$ respectively.

This leads to the following:

Classify an observation as coming from class 2 if:

$$\frac{1}{2}\left[\left(\underline{x}-\widehat{\underline{\mu}}_1\right)^T\widehat{\boldsymbol{\Sigma}}_1^{-1}\left(\underline{x}-\widehat{\underline{\mu}}_1\right)-\left(\underline{x}-\widehat{\underline{\mu}}_2\right)^T\widehat{\boldsymbol{\Sigma}}_2^{-1}\left(\underline{x}-\widehat{\underline{\mu}}_2\right)\right]\geq \log\frac{\widehat{p}_1}{\widehat{p}_2}-\frac{1}{2}\log\left|\widehat{\boldsymbol{\Sigma}}_1\right|+\frac{1}{2}\log\left|\widehat{\boldsymbol{\Sigma}}_2\right|$$

and coming from class 1 otherwise.

In the case where the prior probabilities are known:

Let $\hat{p}_1 = \hat{p}_2 = 0.5$. Classify an observation as coming from class 2 if:

$$\begin{split} \frac{1}{2} \left[\left(\underline{x} - \widehat{\underline{\mu}}_1 \right)^T \widehat{\Sigma}_1^{-1} \left(\underline{x} - \widehat{\underline{\mu}}_1 \right) - \left(\underline{x} - \widehat{\underline{\mu}}_2 \right)^T \widehat{\Sigma}_2^{-1} \left(\underline{x} - \widehat{\underline{\mu}}_1 \right) \right] & \geq & \log \frac{\widehat{p}_1}{\widehat{p}_2} - \frac{1}{2} \log \left| \widehat{\Sigma}_1 \right| + \frac{1}{2} \log \left| \widehat{\Sigma}_2 \right| \\ & = & \log \left(1 \right) - \frac{1}{2} \log \left| \widehat{\Sigma}_1 \right| + \frac{1}{2} \log \left| \widehat{\Sigma}_2 \right| \\ & = & \frac{1}{2} \left(\log \left| \widehat{\Sigma}_2 \right| - \log \left| \widehat{\Sigma}_1 \right| \right) \end{split}$$

Consider now the case where p = 1. For ease of use $\widehat{\Sigma}_1$ can be written as s_1^2 , and $\widehat{\Sigma}_2$ can be written as s_2^2 .

Classify an observation as coming from class 2 if:

$$\frac{1}{2}\left[\left(\underline{x}-\widehat{\underline{\mu}}_{1}\right)^{T}\left(s_{1}^{2}\right)^{-1}\left(\underline{x}-\widehat{\underline{\mu}}_{1}\right)-\left(\underline{x}-\widehat{\underline{\mu}}_{2}\right)^{T}\left(s_{2}^{2}\right)^{-1}\left(\underline{x}-\widehat{\underline{\mu}}_{2}\right)\right]\geq\frac{1}{2}\left(\log\left|s_{2}^{2}\right|-\log\left|s_{1}^{2}\right|\right)$$

Since the underlying distributions are Gaussian and the parameters are known, the optimal classifier for use in the Bayes error calculation can be determined using the equations derived above, and the optimal classifier in the single dimension case with different sample variances is then given by:

$$\frac{1}{2} \left[(\lambda - \mu_1)^T \sigma_1^{-2} (\lambda - \mu_1) - (\lambda - \mu_2) \sigma_2^{-2} (\lambda - \mu_2) \right] = \log \frac{\pi_1}{\pi_2} - \frac{1}{2} \log \left(\sigma_1^2 \right) + \frac{1}{2} \log \left(\sigma_2^2 \right)$$

therefore

$$\begin{split} \left(\lambda^2 - 2\lambda\mu_1 + \mu_1^2\right)\left(\sigma_1^2\right)^{-1} - \left(\lambda^2 - 2\lambda\mu_2 + \mu_2^2\right)\left(\sigma_2^2\right)^{-1} - 2\log\left(\frac{\pi_1}{\pi_2}\right) + \log\left(\frac{\sigma_1^2}{\sigma_2^2}\right) = 0 \\ \left(\frac{1}{\sigma_1^2} - \frac{1}{\sigma_2^2}\right)\lambda^2 - 2\left(\frac{\mu_1}{\sigma_1^2} - \frac{\mu_2}{\sigma_2^2}\right)\lambda + \left(-2\log\left(\frac{\pi_1}{\pi_2}\right) + \log\left(\frac{\sigma_1^2}{\sigma_2^2}\right) + \frac{\mu_1^2}{\sigma_1^2} - \frac{\mu_2^2}{\sigma_2^2}\right) = 0 \end{split}$$



B.2. DETERMINING THE DECISION BOUNDARY BETWEEN CLASS 1 AND 2 USING QDA

which is a quadratic function of λ . Lambda can be solved as follows:

$$\lambda = \frac{2\left(\frac{\mu_1}{\sigma_1^2} - \frac{\mu_2}{\sigma_2^2}\right) \pm \sqrt[2]{4\left(\frac{\mu_1}{\sigma_1^2} - \frac{\mu_2}{\sigma_2^2}\right)^2 - 4\left(\frac{1}{\sigma_1^2} - \frac{1}{\sigma_2^2}\right)\left(-2\log\left(\frac{\pi_1}{\pi_2}\right) + \log\left(\frac{\sigma_1^2}{\sigma_2^2}\right) + \frac{\mu_1^2}{\sigma_1^2} - \frac{\mu_2^2}{\sigma_2^2}\right)}{2\left(\frac{1}{\sigma_1^2} - \frac{1}{\sigma_2^2}\right)}$$

resulting in two different roots for λ .

Define

$$L\left(\lambda\right) = \left(\frac{1}{\sigma_1^2} - \frac{1}{\sigma_2^2}\right)\lambda^2 - 2\left(\frac{\mu_1}{\sigma_1^2} - \frac{\mu_2}{\sigma_2^2}\right)\lambda + \left(-2\log\left(\frac{\pi_1}{\pi_2}\right) + \log\left(\frac{\sigma_1^2}{\sigma_2^2}\right) + \frac{\mu_1^2}{\sigma_1^2} - \frac{\mu_2^2}{\sigma_2^2}\right)$$

The first derivative of $L(\lambda)$ with regards to λ in the respective roots will show whether a particular root is a local minimum or maximum. By choosing the root that maximises $\frac{\partial L}{\partial \lambda}$ the optimal classifier is chosen.



Appendix C

Linear regression of an indicator matrix (LRIM)

Consider the case where $\underline{\beta} = \{\beta_0, \beta_1, ..., \beta_p\}$, and let **X** be a $n \times (p+1)$ matrix with the first column populated with 1's, and the remaining columns populated with the p-dimensions of the x values. For row i, the following holds:

$$e_i = y_i - \underline{x_i}\beta$$

or in matrix notation

$$\underline{e} = y - \mathbf{X}\beta$$

Define $O = \sum_{i=1}^{n} e_i^2 = \sum_{i=1}^{n} (y_i - \beta_0 - x_{i1}\beta_1 - \dots - x_{ip}\beta_p)^2 = (\underline{y} - \mathbf{X}\underline{\beta})^T (\underline{y} - \mathbf{X}\underline{\beta})$, the objective function that needs to be minimised. Taking the derivative with respect to β , setting the resulting equation equal to 0 and solving the equation, will yield the parameter estimate. This is done by using the product-rule, as follows:

$$\frac{\partial O}{\partial \underline{\beta}} = -\mathbf{X}^{T} (\underline{y} - \mathbf{X}\underline{\beta}) - (\underline{y} - \mathbf{X}\underline{\beta})^{T} \mathbf{X}$$
Therefore
$$0 = -\mathbf{X}^{T} (\underline{y} - \mathbf{X}\underline{\hat{\beta}}) - (\underline{y} - \mathbf{X}\underline{\hat{\beta}})^{T} \mathbf{X}$$

$$= -2\mathbf{X}^{T} (\underline{y} - \mathbf{X}\underline{\hat{\beta}})$$

$$= \mathbf{X}^{T} \underline{y} - \mathbf{X}^{T} \mathbf{X}\underline{\hat{\beta}}$$

$$\mathbf{X}^{T} \mathbf{X}\underline{\hat{\beta}} = \mathbf{X}^{T} \underline{y}$$

$$\underline{\hat{\beta}} = (\mathbf{X}^{T} \mathbf{X})^{-1} \mathbf{X}^{T} \underline{y}$$

provided $\mathbf{X}^T\mathbf{X}$ is invertible. This is the case as there can be no linear dependence in the regressors, i.e. $rank(\mathbf{X}) = n$.





Appendix D

Sequential procedure results and critical values

D.1 LDA results

TABLE D.1.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.34213 (0.018359) 90; 90 90; 0	0.34146 (0.017922) 11; 90 88.065; 12.0943	0.34237 (0.020012) 8; 90 79.852; 26.6529	0.34359 (0.023878) 6; 90 69.485; 34.5361
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.29478 (0.012652) 25; 90 89.935; 2.0555	0.29545 (0.013126) 11; 90 84.691; 19.415	0.2968 (0.017072) 8; 90 75.823; 30.1001	0.29883 (0.022177) 6; 90 58.663; 37.9973
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.26723 (0.011468) 22; 90 89.67; 4.6599	0.26682 (0.011181) 11; 90 83.559; 21.2761	0.2675 (0.013486) 8; 90 71.541; 32.6515	0.27079 (0.01965) 6; 90 52.911; 37.982
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.20239 (0.00682) 21; 90 88.825; 8.6931	0.20339 (0.009471) 11; 90 74.512; 30.34	0.20579 (0.011638) 8; 90 53.219; 37.756	0.20703 (0.014133) 6; 90 34.685; 33.5103
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.16973 (0.005759) 21; 90 86.523; 14.6285	0.17095 (0.008537) 11; 90 65.512; 34.6576	0.17382 (0.012125) 8; 90 43.868; 35.9818	0.17512 (0.013123) 6; 90 25.023; 26.3481
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.14973 (0.005744) 21; 90 84.669; 17.7922	0.15168 (0.008366) 11; 90 60.158; 35.4467	0.15395 (0.011929) 8; 90 36.04; 33.052	0.15577 (0.017156) 6; 90 19.885; 20.9906
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.10818 (0.006095) 21; 90 77.831; 24.7271	0.1112 (0.010245) 11; 90 46.582; 34.4316	0.11307 (0.011942) 8; 90 24; 22.423	0.11391 (0.013291) 6; 90 13.482; 10.1931
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05335 (0.006692) 21; 90 54.778; 28.6004	0.05432 (0.0084) 11; 90 25.465; 15.8907	0.05543 (0.010144) 8; 69 15.564; 6.133	0.05622 (0.0104) 6; 33 11.724; 3.5686





TABLE D.1.2 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max	0.3575 (0.031626)	0.35978 (0.034427) 11; 90	0.35908 (0.03513) 8; 90	0.35816 (0.032694) 6; 90
		\bar{n} ; Sd	90; 0	88.376; 11.0963	81.886; 24.1202	73.101; 32.1264
1.3	0.29473	Error (Std) Min; Max	0.31238 (0.022352) 21; 90	0.3133 (0.022889) 11; 90	0.31356 (0.026254) 8; 90	0.31514 (0.030256) 6; 90
		\bar{n} ; Sd	89.931; 2.182	86.873; 15.1419	$78.263;\ 28.0213$	$65.061;\ 36.33$
1.5	0.27214	Error (Std) Min; Max	0.28638 (0.018654) 22; 90	0.28628 (0.018269) 11; 90	0.28731 (0.02077) 8: 90	0.28934 (0.024393) 6: 90
		\bar{n} ; Sd	89.804; 3.5789	84.235; 20.2695	74.882; 31.0399	57.445; 37.9089
2	0.21843	Error (Std) Min; Max	0.22441 (0.009906) 22; 90	0.22574 (0.011788) 11; 90	0.22694 (0.015744) 8; 90	0.22883 (0.017745) 6; 90
		\bar{n} ; Sd	89.532; 5.5771	$77.057;\ 28.5359$	$59.896;\ 36.852$	$40.789;\ 36.0522$
2.3	0.18885	Error (Std) Min; Max \bar{n} ; Sd	0.19281 (0.00739) 21; 90 88.89; 8.4582	0.19435 (0.009445) 11; 90 73.926; 30.5681	0.19709 (0.013318) 8; 90 49.805; 37.529	0.19923 (0.020051) 6; 90 30.576; 30.9091
		n, sa	00.03, 0.4002	75.520, 50.5001	49.000, 37.029	50.570, 50.5051
2.5	0.17042	Error (Std) Min; Max	0.17433 (0.006829) 21; 90	0.17553 (0.010075) 11; 90	0.17857 (0.015888) 8; 90	0.18002 (0.015846) 6; 90
		\bar{n} ; Sd	86.659; 14.3207	69.083; 33.1024	44.7; 36.3731	26.969; 28.3265
3	0.12928	Error (Std) Min; Max	0.13314 (0.006612) 21; 90	0.13567 (0.010111) 11; 90	0.13703 (0.011958) 8; 90	0.13918 (0.013587) 6; 90
		\bar{n} ; Sd	82.949; 20.0131	57.069; 35.7983	$31.257;\ 29.5961$	$17.554;\ 17.9315$
4	0.06833	Error (Std) Min; Max	0.0767 (0.009122) 21: 90	0.07919 (0.012792) 11: 90	0.08035 (0.013991) 8: 90	0.08032 (0.014431) 6; 56
		\bar{n} ; Sd	64.857; 29.661	30.366; 24.0243	16.694; 11.2796	12.117; 5.8521



TABLE D.1.3 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.36906 (0.044901) 90; 90 90: 0	0.36699 (0.040876) 11; 90 88.612; 10.262	0.36692 (0.043322) 8; 90 82.951; 22.5522	0.36877 (0.047113) 6; 90 71.266; 33.7254
		n; so	90; 0	88.012; 10.202	82.951; 22.5522	71.200; 55.7254
1.3	0.29754	Error (Std) Min; Max	0.32529 (0.032975) 22; 90	0.32646 (0.034348) 11; 90	0.32706 (0.035409) 8; 90	0.324 (0.033601) 6; 90
		\bar{n} ; Sd	89.932; 2.1503	86.374; 16.3413	$78.833;\ 27.5635$	$66.075;\ 35.9166$
1.5	0.27772	Error (Std) Min; Max	0.29935 (0.027887) 23; 90	0.29891 (0.026571) 11; 90	0.29959 (0.028251) 8; 90	0.30143 (0.033257) 6; 90
		\bar{n} ; Sd	89.815; 3.3853	$84.331;\ 20.0784$	76.066; 29.853	$60.788;\ 37.3334$
2	0.22973	Error (Std) Min; Max	0.24053 (0.017303) 21; 90	0.24005 (0.015219) 11; 90	0.2423 (0.01997) 8; 90	0.24436 (0.02434) 6; 90
		\bar{n} ; Sd	89.673; 4.6184	79.781; 25.7797	65.799; 35.3784	46.477; 37.3938
2.3	0.20265	Error (Std) Min; Max	0.20917 (0.010605) 21; 90	0.21092 (0.015785) 11; 90	0.21206 (0.016624) 8; 90	0.21454 (0.020225) 6; 90
		\bar{n} ; Sd	88.721; 9.0039	76.887; 28.4162	$56.575;\ 37.4452$	37.992; 34.6864
2.5	0.18551	Error (Std) Min; Max	0.19031 (0.008284) 21; 90	0.19219 (0.010959) 11; 90	0.19466 (0.014394) 8; 90	0.1976 (0.021479) 6; 90
		\bar{n} ; Sd	88.467; 10.0035	$71.239;\ 32.3081$	52.018; 37.6832	$31.561;\ 31.6372$
3	0.14628	Error (Std) Min; Max	0.15051 (0.006941) 21; 90	0.15321 (0.011234) 11; 90	0.15525 (0.013058) 8; 90	0.15703 (0.015483) 6: 90
		$\bar{n}; \mathrm{Sd}$	85.513; 16.5186	62.028; 35.2244	35.803; 32.8645	21.802; 22.2585
4	0.08473	Error (Std) Min; Max	0.09431 (0.011011) 21; 90	0.09689 (0.013444) 11; 90	0.09875 (0.016726) 8; 90	0.09912 (0.015896) 6; 68
		$ar{n}; \operatorname{Sd}$	72.975; 27.7846	38.084; 30.4163	19.609; 16.7255	11.863; 6.2081



TABLE D.1.4 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.34668 (0.027005) 40; 40 40: 0	0.35077 (0.033684) 11; 40 39.186; 4.641	0.3492 (0.031919) 8; 40 36.04; 10.2068	0.35045 (0.034353) 6; 40 32.841; 13.1466
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.29933 (0.019455) 22; 40 39.982; 0.5692	0.30037 (0.019765) 11; 40 38.563; 6.0639	0.30102 (0.023275) 8; 40 34.311; 11.7361	0.30178 (0.027489) 6; 40 29.316; 14.6251
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.27008 (0.015047) 21; 40 39.919; 1.1721	0.2706 (0.017171) 11; 40 37.25; 8.1275	0.27307 (0.019948) 8; 40 33.354; 12.3946	0.27189 (0.019654) 6; 40 27.261; 15.0468
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.20522 (0.011071) 21; 40 39.708; 2.1595	0.20636 (0.012408) 11; 40 34.726; 10.5284	0.20729 (0.016768) 8; 40 28.298; 14.1609	0.20814 (0.014681) 6; 40 21.607; 14.5378
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.17228 (0.009381) 21; 40 39.231; 3.492	0.17356 (0.011724) 11; 40 32.783; 11.5275	0.17482 (0.013791) 8; 40 24.962; 13.9632	0.17557 (0.014464) 6; 40 18.184; 13.2302
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.15185 (0.00769) 21; 40 38.891; 3.9561	0.1527 (0.009323) 11; 40 31.212; 11.983	0.15455 (0.012507) 8; 40 23.078; 13.5826	0.15628 (0.013643) 6; 40 16.391; 11.7048
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.10945 (0.007478) 21; 40 37.43; 5.7397	0.1113 (0.00974) 11; 40 27.163; 12.1542	0.11323 (0.01263) 8; 40 18.011; 10.868	0.11367 (0.012913) 6; 40 13.961; 8.8593
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05316 (0.006441) 21; 40 34.237; 7.1215	0.05492 (0.008822) 11; 40 22.638; 8.8796	0.05571 (0.009841) 8; 40 15.803; 5.9511	0.05556 (0.009773) 6; 39 11.886; 3.9054



TABLE D.1.5 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} ; Sd	0.36347 (0.042796) 40; 40 40; 0	0.36595 (0.04442) 11; 40 39.265; 4.4266	0.36462 (0.043172) 8; 40 37.095; 8.9149	0.36615 (0.045298) 6; 40 33.274; 13.026
1.3	0.29473	Error (Std) Min; Max \bar{n} ; Sd	0.32022 (0.036081) 22; 40 39.982; 0.5692	0.3199 (0.036628) 11; 40 38.449; 6.2792	0.32355 (0.039007) 8; 40 35.805; 10.3589	0.32116 (0.039056) 6; 40 31.699; 13.8307
1.5	0.27214	Error (Std) Min; Max \bar{n} ; Sd	0.29092 (0.028227) 40; 40 40; 0	0.29279 (0.031916) 11; 40 38.164; 6.791	0.29236 (0.031114) 8; 40 33.523; 12.298	0.29068 (0.027591) 6; 40 29.064; 14.7981
2	0.21843	Error (Std) Min; Max \bar{n} ; Sd	0.23049 (0.019357) 21; 40 39.632; 2.4377	0.22993 (0.01717) 11; 40 36.118; 9.4156	0.23017 (0.018992) 8; 40 29.814; 13.7881	0.23103 (0.019863) 6; 40 24.411; 15.1074
2.3	0.18885	Error (Std) Min; Max \bar{n} ; Sd	0.19685 (0.014729) 21; 40 39.641; 2.3937	0.19655 (0.011935) 11; 40 34.542; 10.5863	0.19861 (0.014529) 8; 40 27.333; 14.2596	0.20049 (0.019473) 6; 40 21.007; 14.3842
2.5	0.17042	Error (Std) Min; Max \bar{n} ; Sd	0.17667 (0.011154) 21; 40 39.287; 3.296	0.17812 (0.012498) 11; 40 33.543; 11.1652	0.17974 (0.015986) 8; 40 25.882; 14.2651	0.18051 (0.015711) 6; 40 18.933; 13.4643
3	0.12928	Error (Std) Min; Max \bar{n} ; Sd	0.135 (0.008405) 21; 40 38.622; 4.4286	0.13672 (0.01133) 11; 40 29.693; 12.0907	0.13888 (0.013959) 8; 40 20.715; 12.7546	0.13987 (0.015023) 6; 40 14.629; 10.0176
4	0.06833	Error (Std) Min; Max \bar{n} ; Sd	0.07707 (0.010142) 21; 40 34.977; 7.0508	0.0787 (0.011643) 11; 40 23.532; 10.5689	0.07958 (0.013122) 8; 40 15.872; 7.9147	0.08039 (0.014611) 6; 40 11.853; 5.0538



TABLE D.1.6 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.37961 (0.055843) 40; 40 40; 0	0.37962 (0.055753) 11; 40 39.331; 4.2189	0.37982 (0.055878) 8; 40 37.564; 8.2501	0.37635 (0.05814) 6; 40 33.642; 12.6193
1.3	0.29754	Error (Std) Min; Max \bar{n} ; Sd	0.33395 (0.047255) 21; 40 39.966; 0.7651	0.33545 (0.047369) 11; 40 38.833; 5.4861	0.3343 (0.047524) 8; 40 35.864; 10.2969	0.33577 (0.04843) 6; 40 31.716; 13.8854
1.5	0.27772	Error (Std) Min; Max \bar{n} ; Sd	0.30925 (0.043605) 40; 40 40; 0	0.30712 (0.040461) 11; 40 38.737; 5.6712	0.30917 (0.044479) 8; 40 34.278; 11.7532	0.30666 (0.04258) 6; 40 30.519; 14.235
2	0.22973	Error (Std) Min; Max \bar{n} ; Sd	0.24539 (0.025884) 21; 40 39.838; 1.6341	0.2473 (0.031235) 11; 40 36.621; 8.8369	0.24705 (0.027879) 8; 40 31.893; 13.0557	0.24782 (0.029647) 6; 40 25.837; 15.2271
2.3	0.20265	Error (Std) Min; Max \bar{n} ; Sd	0.21385 (0.020064) 21; 40 39.787; 1.7666	0.21488 (0.019533) 11; 40 35.114; 10.1687	0.2158 (0.022856) 8; 40 28.508; 14.1268	0.21744 (0.022402) 6; 40 22.066; 14.7935
2.5	0.18551	Error (Std) Min; Max \bar{n} ; Sd	0.19453 (0.016391) 21; 40 39.712; 2.21	0.19464 (0.015508) 11; 40 34.485; 10.7583	0.1974 (0.019603) 8; 40 28.002; 14.1218	0.19828 (0.021302) 6; 40 20.542; 14.3107
3	0.14628	Error (Std) Min; Max \bar{n} ; Sd	0.15296 (0.009778) 21; 40 38.96; 3.9958	0.15514 (0.013816) 11; 40 31.415; 11.9876	0.15706 (0.016693) 8; 40 23.304; 13.7932	0.15724 (0.016253) 6; 40 16.33; 11.8058
4	0.08473	Error (Std) Min; Max \bar{n} ; Sd	0.09429 (0.010871) 21; 40 36.634; 6.3081	0.09719 (0.013907) 11; 40 25.539; 11.7311	0.09805 (0.015412) 8; 40 16.641; 9.4992	0.0991 (0.016281) 6; 40 12.537; 6.8928



D.2 QDA results

TABLE D.2.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the QDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.33453 (0.010855) 23; 90 89.933; 2.1187	0.33455 (0.01186) 11; 90 88.304; 11.3182	0.33681 (0.01559) 8; 90 82.844; 22.6474	0.33862 (0.019479) 6; 90 71.278; 33.1351
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.29188 (0.009462) 23; 90 89.801; 3.63	0.29342 (0.012437) 11; 90 86.067; 16.8015	0.29442 (0.015079) 8; 90 75.378; 30.4173	0.29806 (0.022251) 6; 90 62.159; 37.1646
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.26488 (0.008434) 21; 90 89.598; 5.1781	0.26491 (0.008664) 11; 90 84.505; 19.7587	0.26679 (0.013398) 8; 90 73.873; 31.1175	0.27122 (0.023493) 6; 90 57.044; 37.3739
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.20203 (0.005463) 21; 90 88.699; 9.1262	0.20344 (0.010275) 11; 90 75.652; 29.3991	0.20689 (0.01701) 8; 90 57.469; 36.8005	0.21075 (0.021042) 6; 90 35.941; 33.7879
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.16959 (0.005793) 21; 90 86.683; 14.2895	0.17142 (0.011234) 11; 90 69.512; 32.9141	0.17592 (0.017874) 8; 90 45.823; 36.2616	0.17802 (0.019448) 6; 90 27.626; 28.0359
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.14999 (0.005355) 21; 90 85.16; 16.9747	0.15227 (0.011003) 11; 90 63.892; 34.664	0.15657 (0.018465) 8; 90 37.951; 33.4661	0.15899 (0.020766) 6; 90 21; 22.041
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.10736 (0.00493) 21; 90 79.473; 23.4577	0.11119 (0.011602) 11; 90 47.392; 34.3341	0.11377 (0.015354) 8; 90 24.845; 22.9883	0.11788 (0.019991) 6; 90 14.533; 12.6255
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05163 (0.006898) 21; 90 55.933; 28.5638	0.05419 (0.011979) 11; 90 25.996; 16.4854	0.05747 (0.017973) 8; 90 16.351; 8.2681	0.05945 (0.020641) 6; 44 11.91; 4.1595



TABLE D.2.2 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the QDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} ; Sd	0.32764 (0.009462) 24; 90 89.934; 2.0871	0.32816 (0.010577) 11; 90 87.219; 14.4033	0.32921 (0.01703) 8; 90 82.343; 23.4365	0.33253 (0.019323) 6; 90 69.098; 34.5981
1.3	0.29473	Error (Std) Min; Max \bar{n} ; Sd	0.29676 (0.007636) 27; 90 89.874; 2.816	0.29746 (0.009432) 11; 90 86.76; 15.4976	0.29941 (0.013281) 8; 90 76.916; 29.3799	0.30245 (0.017837) 6; 90 64.179; 36.5078
1.5	0.27214	Error (Std) Min; Max \bar{n} ; Sd	0.27585 (0.008488) 22; 90 89.932; 2.1503	0.27585 (0.009083) 11; 90 84.977; 18.9702	0.27855 (0.016207) 8; 90 74.636; 30.9374	0.28206 (0.019422) 6; 90 59.878; 37.0008
2	0.21843	Error (Std) Min; Max \bar{n} ; Sd	0.22193 (0.007074) 21; 90 88.669; 9.3272	0.224 (0.011136) 11; 90 79.322; 26.3339	0.22675 (0.017317) 8; 90 64.513; 35.4401	0.22963 (0.021516) 6; 90 44.142; 36.5686
2.3	0.18885	Error (Std) Min; Max \bar{n} ; Sd	0.1923 (0.005892) 21; 90 88.063; 11.0399	0.19418 (0.010661) 11; 90 74.885; 29.8532	0.19699 (0.017032) 8; 90 53.278; 37.3805	0.20051 (0.021067) 6; 90 35.911; 33.016
2.5	0.17042	Error (Std) Min; Max \bar{n} ; Sd	0.17332 (0.005243) 21; 90 87.535; 12.4624	0.17554 (0.010344) 11; 90 70.781; 32.1873	0.1795 (0.018371) 8; 90 46.983; 36.3242	0.18286 (0.01963) 6; 90 27.771; 27.8828
3	0.12928	Error (Std) Min; Max \bar{n} ; Sd	0.13181 (0.005755) 21; 90 83.751; 18.8746	0.13636 (0.015396) 11; 90 57.975; 34.9321	0.13883 (0.016785) 8; 90 32.89; 30.3712	0.14269 (0.023183) 6; 90 18.943; 18.9039
4	0.06833	Error (Std) Min; Max \bar{n} ; Sd	0.07154 (0.005797) 21; 90 67.111; 29.1485	0.07574 (0.014191) 11; 90 31.531; 24.5383	0.07833 (0.0168) 8; 90 17.177; 11.2866	0.08116 (0.023903) 6; 61 12.464; 6.6285



TABLE D.2.3 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the QDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.31194 (0.009211) 21; 90 89.931; 2.182	0.31351 (0.012472) 11; 90 87.213; 14.4318	0.31472 (0.013347) 8; 90 80.795; 25.2825	0.31751 (0.018714) 6; 90 67.589; 34.9202
		n; so	09.931; 2.102	67.215; 14.4516	80.795; 25.2825	07.569; 54.9202
1.3	0.29754	Error (Std) Min; Max	0.29097 (0.008797) 21; 90	0.29172 (0.010829) 11; 90	0.29352 (0.013153) 8; 90	0.29601 (0.019326) 6; 90
		\bar{n} ; Sd	89.798; 3.6849	$86.525;\ 16.0217$	$77.346;\ 28.7818$	$66.091;\ 35.3665$
1.5	0.27772	Error (Std) Min; Max	0.27437 (0.007577) 21; 90	0.27525 (0.009885) 11; 90	0.27769 (0.013128) 8; 90	0.28134 (0.020095) 6; 90
		\bar{n} ; Sd	89.865; 3.0179	$85.202;\ 18.5662$	75.042; 30.4093	58.975; 37.6196
2	0.22973	Error (Std) Min; Max	0.23128 (0.006429) 21; 90	0.23307 (0.013839) 11; 90	0.23592 (0.016343) 8; 90	0.24065 (0.021995) 6; 90
		\bar{n} ; Sd	89.484; 5.7615	81.416; 23.9031	$65.031;\ 35.8512$	$46.577;\ 37.1275$
2.3	0.20265	Error (Std) Min; Max \bar{n} ; Sd	0.20506 (0.006029) 21; 90 89.28; 6.857	0.20694 (0.011691) 11; 90 76.736; 28.5393	0.2101 (0.015902) 8; 90 57.56; 37.2625	0.21485 (0.021891) 6; 90 37.639; 34.6961
		,	,	,	,	,
2.5	0.18551	Error (Std) Min; Max	0.18879 (0.006833) 21; 90	0.19065 (0.011716) 11; 90	0.19476 (0.01737) 8; 90	0.19906 (0.024365) 6; 90
		\bar{n} ; Sd	88.304; 10.4046	$74.005;\ 30.7121$	51.44; 37.0648	$32.878;\ 31.7466$
3	0.14628	Error (Std) Min; Max	0.14897 (0.00507) 21; 90	0.15211 (0.012537) 11; 90	0.15642 (0.018796) 8; 90	0.15984 (0.021086) 6; 90
		\bar{n} ; Sd	86.046; 15.4518	64.316; 34.8455	38.914; 33.5584	21.24; 22.2746
4	0.08473	Error (Std) Min; Max	0.08819 (0.007174) 21; 90	0.09268 (0.015164) 11; 90	0.09662 (0.021407) 8; 90	0.09879 (0.021733) 6; 90
		\bar{n} ; Sd	70.009; 29.1724	37.571; 29.7439	19.75; 16.3559	12.986; 9.0941



TABLE D.2.4 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the QDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.34402 (0.024489) 22; 40 39.965; 0.7826	0.34335 (0.023477) 11; 40 39.484; 3.6572	0.34481 (0.027123) 8; 40 37.088; 9.0111	0.34619 (0.027567) 6; 40 33.896; 12.4706
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.29798 (0.01879) 22; 40 39.966; 0.7612	0.29788 (0.018208) 11; 40 38.711; 5.7165	0.30063 (0.022539) 8; 40 35.446; 10.715	0.30206 (0.025902) 6; 40 31.266; 13.9251
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.2691 (0.013152) 25; 40 39.985; 0.4743	0.27011 (0.01624) 11; 40 37.895; 7.1985	0.27246 (0.022644) 8; 40 33.882; 11.9993	0.27541 (0.025552) 6; 40 28.955; 14.716
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.20551 (0.010035) 21; 40 39.703; 2.1807	0.20696 (0.014277) 11; 40 35.39; 9.9803	0.2084 (0.016667) 8; 40 28.892; 14.1344	0.2111 (0.01978) 6; 40 22.829; 14.7719
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.17185 (0.008289) 21; 40 39.361; 3.0955	0.17352 (0.012181) 11; 40 32.856; 11.3877	0.17627 (0.015844) 8; 40 27.017; 14.0226	0.17884 (0.019759) 6; 40 19.274; 13.4279
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.15206 (0.008458) 21; 40 39.115; 3.6638	0.15377 (0.011507) 11; 40 32.078; 11.6256	0.15615 (0.016615) 8; 40 23.892; 13.639	0.15899 (0.020624) 6; 40 17.387; 12.2986
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.10908 (0.007011) 21; 40 37.575; 5.6198	0.11152 (0.011836) 11; 40 28.033; 12.0646	0.11432 (0.015096) 8; 40 19.585; 11.5574	0.11756 (0.020324) 6; 40 13.126; 8.0256
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05225 (0.006968) 21; 40 34.409; 7.1468	0.05454 (0.013103) 11; 40 22.902; 9.6333	0.05711 (0.016361) 8; 40 15.759; 6.2103	0.05952 (0.01899) 6; 40 11.706; 3.9287



TABLE D.2.5 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the QDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} ; Sd	0.33538 (0.023581) 21; 40 39.981; 0.6008	0.33543 (0.022999) 11; 40 39.276; 4.3645	0.33566 (0.021343) 8; 40 37.091; 8.9518	0.33842 (0.024084) 6; 40 33.019; 13.1015
1.3	0.29473	Error (Std) Min; Max \bar{n} ; Sd	0.30355 (0.01708) 21; 40 39.965; 0.7851	0.30394 (0.01652) 11; 40 39.05; 4.9374	0.30501 (0.019857) 8; 40 36.239; 9.9186	0.30708 (0.021311) 6; 40 30.788; 14.2028
1.5	0.27214	Error (Std) Min; Max \bar{n} ; Sd	0.2819 (0.017886) 22; 40 39.965; 0.7826	0.28342 (0.019388) 11; 40 38.09; 6.9014	0.28439 (0.020174) 8; 40 34.274; 11.7731	0.28555 (0.022249) 6; 40 28.494; 15.048
2	0.21843	Error (Std) Min; Max \bar{n} ; Sd	0.22646 (0.012718) 21; 40 39.878; 1.4564	0.22694 (0.012924) 11; 40 36.442; 8.9565	0.23002 (0.01779) 8; 40 30.377; 13.5813	0.23351 (0.023268) 6; 40 24.149; 15.0411
2.3	0.18885	Error (Std) Min; Max \bar{n} ; Sd	0.1964 (0.011725) 21; 40 39.597; 2.5681	0.19719 (0.013034) 11; 40 35.118; 10.0921	0.19871 (0.016607) 8; 40 28.726; 14.0559	0.20334 (0.024273) 6; 40 21.506; 14.4718
2.5	0.17042	Error (Std) Min; Max \bar{n} ; Sd	0.17652 (0.008564) 21; 40 39.385; 3.0887	0.17823 (0.012688) 11; 40 33.949; 10.8101	0.18117 (0.016814) 8; 40 26.258; 14.1655	0.1834 (0.019881) 6; 40 20.236; 13.9321
3	0.12928	Error (Std) Min; Max \bar{n} ; Sd	0.13454 (0.007787) 21; 40 38.847; 4.0289	0.13646 (0.011883) 11; 40 30.24; 12.1003	0.1398 (0.01715) 8; 40 22.794; 13.3659	0.1434 (0.024023) 6; 40 15.879; 11.2038
4	0.06833	Error (Std) Min; Max \bar{n} ; Sd	0.07294 (0.008035) 21; 40 35.521; 6.7656	0.07663 (0.014831) 11; 40 23.765; 10.7928	0.07925 (0.020909) 8; 40 16.345; 8.7334	0.08023 (0.019564) 6; 40 12.256; 5.7692



TABLE D.2.6 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the QDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.32001 (0.019228) 21; 40 39.981; 0.6008	0.32056 (0.020111) 11; 40 38.941; 5.2735	0.32124 (0.020435) 8; 40 35.852; 10.3742	0.32316 (0.023011) 6; 40 32.677; 13.2864
1.3	0.29754	Error (Std) Min; Max \bar{n} ; Sd	0.29729 (0.015866) 23; 40 39.968; 0.7166	0.29809 (0.016015) 11; 40 38.571; 6.0244	0.29983 (0.020057) 8; 40 35.268; 10.8468	0.30113 (0.021798) 6; 40 30.506; 14.3292
1.5	0.27772	Error (Std) Min; Max \bar{n} ; Sd	0.28097 (0.015925) 21; 40 39.875; 1.4925	0.28139 (0.014609) 11; 40 38.492; 6.2252	0.2812 (0.015791) 8; 40 35.101; 11.0691	0.28544 (0.020793) 6; 40 29.244; 14.703
2	0.22973	Error (Std) Min; Max \bar{n} ; Sd	0.23642 (0.011852) 21; 40 39.877; 1.4056	0.23643 (0.01321) 11; 40 36.822; 8.5655	0.23891 (0.01649) 8; 40 31.948; 12.986	0.2404 (0.019565) 6; 40 25.23; 15.1764
2.3	0.20265	Error (Std) Min; Max \bar{n} ; Sd	0.20924 (0.011097) 21; 40 39.698; 2.2144	0.21074 (0.013255) 11; 40 35.632; 9.7616	0.21249 (0.01795) 8; 40 29.268; 13.8959	0.21752 (0.025535) 6; 40 22.533; 14.7411
2.5	0.18551	Error (Std) Min; Max \bar{n} ; Sd	0.19239 (0.01123) 21; 40 39.553; 2.6691	0.19443 (0.014678) 11; 40 34.95; 10.2862	0.19643 (0.017698) 8; 40 27.53; 14.1318	0.2009 (0.024818) 6; 40 20.33; 14.2799
3	0.14628	Error (Std) Min; Max \bar{n} ; Sd	0.15208 (0.008508) 21; 40 38.918; 4.0241	0.15372 (0.011267) 11; 40 32.025; 11.82	0.15867 (0.02362) 8; 40 24.056; 13.8729	0.16087 (0.022908) 6; 40 17.429; 12.5729
4	0.08473	Error (Std) Min; Max \bar{n} ; Sd	0.08961 (0.008093) 21; 40 36.579; 6.3049	0.09234 (0.012821) 11; 40 25.509; 11.6262	0.09673 (0.021061) 8; 40 17.781; 10.1072	0.09817 (0.022029) 6; 40 12.794; 7.1701



D.3 5-nn results

TABLE D.3.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.38008 (0.025224) 21; 90 89.931; 2.182	0.37782 (0.023774) 11; 90 88.851; 9.3293	0.3775 (0.025864) 8; 90 82.897; 22.6492	0.37529 (0.031878) 6; 90 72.182; 33.1842
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.33257 (0.024872) 21; 90 89.862; 3.0842	0.33011 (0.025554) 11; 90 86.021; 17.0056	0.32924 (0.026277) 8; 90 78.332; 27.8111	0.32685 (0.030739) 6; 90 63.626; 37.0076
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.29941 (0.023229) 22; 90 89.805; 3.562	0.2992 (0.025167) 11; 90 84.344; 19.9144	0.29817 (0.029154) 8; 90 73.039; 32.1075	0.29498 (0.030096) 6; 90 59.407; 37.7755
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.22692 (0.020414) 22; 90 89.016; 7.9808	0.22641 (0.020916) 11; 90 76.429; 28.8554	0.22293 (0.022254) 8; 90 57.455; 37.6951	0.22535 (0.027977) 6; 90 43.159; 36.8851
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.18932 (0.018129) 21; 90 87.115; 13.5024	0.18923 (0.020346) 11; 90 70.683; 32.3577	0.18821 (0.02428) 8; 90 49.054; 37.2711	0.18671 (0.024048) 6; 90 29.153; 30.5044
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.16607 (0.017434) 21; 90 85.545; 16.42	0.16534 (0.019292) 11; 90 64.066; 34.6543	0.16676 (0.022461) 8; 90 41.983; 35.286	0.16557 (0.024204) 6; 90 23.275; 24.9212
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.11877 (0.014383) 21; 90 78.822; 24.1662	0.11894 (0.017221) 11; 90 47.099; 34.7159	0.11921 (0.018859) 8; 90 26.649; 25.962	0.12051 (0.020939) 6; 90 15.509; 14.692
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05409 (0.008925) 21; 90 54.246; 28.3958	0.0557 (0.010886) 11; 90 26.587; 18.3184	0.05709 (0.012795) 8; 90 15.796; 8.0502	0.058 (0.013084) 6; 50 11.831; 4.7725



D.3. 5-NN RESULTS

TABLE D.3.2 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} ; Sd	0.47587 (0.01054) 90; 90 90; 0	0.47513 (0.01494) 11; 90 88.091; 11.9448	0.47062 (0.02676) 8; 90 83.647; 21.7113	0.46195 (0.03812) 6; 90 73.297; 32.5036
1.3	0.29473	Error (Std) Min; Max \bar{n} ; Sd	0.47972 (0.00999) 22; 90 89.866; 2.9952	0.47592 (0.01956) 11; 90 86.687; 15.5768	0.46784 (0.03513) 8; 90 79.254; 26.9635	0.45932 (0.04452) 6; 90 69.231; 34.3071
1.5	0.27214	Error (Std) Min; Max \bar{n} ; Sd	0.47992 (0.01139) 22; 90 89.865; 3.0173	0.47696 (0.02061) 11; 90 85.419; 18.1154	0.46777 (0.04024) 8; 90 76.477; 29.7417	0.45094 (0.05541) 6; 90 60.786; 37.6795
2	0.21843	Error (Std) Min; Max \bar{n} ; Sd	0.48434 (0.01254) 23; 90 89.606; 5.0755	0.47435 (0.03545) 11; 90 79.444; 26.1593	0.45828 (0.05652) 8; 90 66.452; 35.2402	0.4392 (0.0738) 6; 90 48.224; 38.0001
2.3	0.18885	Error (Std) Min; Max \bar{n} ; Sd	0.48528 (0.0141) 21; 90 88.364; 10.2347	0.47143 (0.04425) 11; 90 75.016; 29.7408	0.44422 (0.07311) 8; 90 55.085; 37.4359	0.42356 (0.08473) 6; 90 35.673; 34.1691
2.5	0.17042	Error (Std) Min; Max \bar{n} ; Sd	0.48412 (0.01743) 21; 90 86.437; 14.8029	0.46722 (0.05426) 11; 90 71.31; 32.039	0.44301 (0.08157) 8; 90 51.163; 37.037	0.41683 (0.08968) 6; 90 33.553; 32.7304
3	0.12928	Error (Std) Min; Max \bar{n} ; Sd	0.48497 (0.02165) 21; 90 83.998; 18.7398	0.45434 (0.06958) 11; 90 58.425; 35.4486	0.41211 (0.09612) 8; 90 35.113; 32.5414	0.38423 (0.10764) 6; 90 19.104; 20.3698
4	0.06833	Error (Std) Min; Max \bar{n} ; Sd	0.46801 (0.04596) 21; 90 65.277; 29.7882	0.4081 (0.09942) 11; 90 32.148; 25.5308	0.36813 (0.11527) 8; 90 17.353; 12.5453	0.34372 (0.12761) 6; 66 12.093; 6.095



D.3. 5-NN RESULTS

TABLE D.3.3 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.46677 (0.01336) 90; 90 90; 0	0.46384 (0.01958) 11; 90 88.295; 11.3756	0.45815 (0.03408) 8; 90 83.282; 22.2223	0.4502 (0.04189) 6; 90 75.013; 30.679
1.3	0.29754	Error (Std) Min; Max \bar{n} ; Sd	0.46895 (0.01362) 22; 90 89.932; 2.1503	0.46594 (0.02476) 11; 90 87.013; 14.9119	0.45617 (0.04483) 8; 90 79.906; 26.2451	0.44428 (0.05355) 6; 90 70.299; 33.992
1.5	0.27772	Error (Std) Min; Max \bar{n} ; Sd	0.46993 (0.01429) 23; 90 89.809; 3.4907	0.46644 (0.02439) 11; 90 86.082; 16.812	0.45356 (0.04642) 8; 90 75.642; 30.2631	0.4389 (0.06025) 6; 90 64.773; 36.3862
2	0.22973	Error (Std) Min; Max \bar{n} ; Sd	0.47528 (0.01395) 22; 90 89.47; 5.9064	0.46588 (0.03776) 11; 90 82.296; 22.912	0.44306 (0.06716) 8; 90 68.042; 34.8597	0.42257 (0.0754) 6; 90 50.959; 38.0277
2.3	0.20265	Error (Std) Min; Max \bar{n} ; Sd	0.47643 (0.01755) 21; 90 89.151; 7.411	0.45974 (0.05047) 11; 90 77.475; 28.1124	0.43481 (0.07291) 8; 90 60.241; 37.0223	0.40605 (0.08976) 6; 90 42.559; 36.6259
2.5	0.18551	Error (Std) Min; Max \bar{n} ; Sd	0.47694 (0.01953) 21; 90 88.105; 10.9917	0.4587 (0.05668) 11; 90 74.328; 30.3255	0.42913 (0.08143) 8; 90 56.29; 37.323	0.39585 (0.09029) 6; 90 35.026; 34.1627
3	0.14628	Error (Std) Min; Max \bar{n} ; Sd	0.47805 (0.0223) 21; 90 85.761; 16.039	0.44268 (0.07541) 11; 90 64.17; 34.8395	0.40243 (0.09674) 8; 90 42.109; 35.2254	0.36727 (0.10308) 6; 90 25.141; 27.0931
4	0.08473	Error (Std) Min; Max \bar{n} ; Sd	0.46472 (0.05164) 21; 90 73.297; 27.426	0.39132 (0.10606) 11; 90 39.006; 31.2692	0.35029 (0.1123) 8; 90 22.003; 20.4566	0.31949 (0.12178) 6; 90 13.955; 10.9875



D.3. 5-NN RESULTS

TABLE D.3.4 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.37937 (0.033388) 22; 40 39.982; 0.5692	0.38009 (0.035261) 11; 40 39.305; 4.273	0.37747 (0.03465) 8; 40 36.999; 9.0736	0.37769 (0.037315) 6; 40 34.121; 12.2671
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.3331 (0.034691) 23; 40 39.936; 1.0114	0.33426 (0.034905) 11; 40 38.892; 5.3223	0.33273 (0.037773) 8; 40 35.167; 11.012	0.33041 (0.037796) 6; 40 31.211; 13.9482
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.29947 (0.033142) 21; 40 39.894; 1.2745	0.30006 (0.033847) 11; 40 38.413; 6.2464	0.2973 (0.034383) 8; 40 34.239; 11.7336	0.30011 (0.037935) 6; 40 29.71; 14.4815
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.22881 (0.028436) 21; 40 39.765; 1.927	0.22996 (0.032241) 11; 40 35.43; 9.9185	0.22858 (0.032494) 8; 40 29.545; 13.92	0.22709 (0.032091) 6; 40 23.909; 15.0414
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.18955 (0.025204) 21; 40 39.335; 3.2045	0.18946 (0.025547) 11; 40 33.928; 10.8236	0.18865 (0.026054) 8; 40 25.813; 14.1121	0.18918 (0.027498) 6; 40 19.703; 14.0017
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.16784 (0.022451) 21; 40 39.043; 3.7123	0.16671 (0.022231) 11; 40 31.529; 11.9305	0.1672 (0.025731) 8; 40 24.184; 13.8285	0.16683 (0.025506) 6; 40 18.496; 13.0681
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.11877 (0.018617) 21; 40 37.882; 5.2509	0.11882 (0.018709) 11; 40 27.719; 12.1494	0.12072 (0.02103) 8; 40 19.444; 11.74	0.11992 (0.020296) 6; 40 13.782; 9.1602
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05562 (0.011459) 21; 40 34.214; 7.0592	0.05636 (0.013687) 11; 40 22.49; 9.0293	0.05636 (0.011894) 8; 40 15.627; 6.3773	0.05801 (0.014381) 6; 40 11.861; 4.1772



D.3. 5-NN RESULTS

TABLE D.3.5 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} ; Sd	0.37644 (0.032149) 23; 40 39.983; 0.5376	0.37585 (0.032117) 11; 40 39.457; 3.8117	0.37614 (0.033723) 8; 40 37.255; 8.727	0.37456 (0.036759) 6; 40 34.329; 12.1091
1.3	0.29473	Error (Std) Min; Max \bar{n} ; Sd	0.34094 (0.032699) 22; 40 39.966; 0.7612	0.34243 (0.032815) 11; 40 38.873; 5.4119	0.34167 (0.035179) 8; 40 36.278; 9.8639	0.33937 (0.036404) 6; 40 31.736; 13.8738
1.5	0.27214	Error (Std) Min; Max \bar{n} ; Sd	0.31754 (0.033909) 21; 40 39.962; 0.8493	0.31711 (0.035132) 11; 40 38.692; 5.788	0.31837 (0.036265) 8; 40 35.116; 11.0317	0.31349 (0.039845) 6; 40 30.463; 14.339
2	0.21843	Error (Std) Min; Max \bar{n} ; Sd	0.25273 (0.030605) 21; 40 39.882; 1.4114	0.25228 (0.031475) 11; 40 36.67; 8.8435	0.25142 (0.032935) 8; 40 31.019; 13.4416	0.25082 (0.034571) 6; 40 25.723; 15.1465
2.3	0.18885	Error (Std) Min; Max \bar{n} ; Sd	0.21691 (0.028628) 21; 40 39.671; 2.3057	0.21703 (0.028561) 11; 40 35.198; 10.0886	0.21627 (0.029775) 8; 40 29.093; 13.7923	0.21587 (0.033217) 6; 40 22.178; 14.5761
2.5	0.17042	Error (Std) Min; Max \bar{n} ; Sd	0.19614 (0.026441) 21; 40 39.414; 2.9886	0.19179 (0.025208) 11; 40 33.763; 10.9945	0.19589 (0.03094) 8; 40 27.49; 14.0977	0.19456 (0.029315) 6; 40 19.776; 13.8594
3	0.12928	Error (Std) Min; Max \bar{n} ; Sd	0.1467 (0.022029) 21; 40 38.745; 4.2023	0.14643 (0.021026) 11; 40 30.257; 12.1217	0.14742 (0.024216) 8; 40 22.267; 13.4266	0.14763 (0.025942) 6; 40 15.459; 11.3411
4	0.06833	Error (Std) Min; Max \bar{n} ; Sd	0.07777 (0.013909) 21; 40 35.826; 6.677	0.07991 (0.016911) 11; 40 24.268; 10.9084	0.08 (0.016163) 8; 40 16.39; 8.6732	0.08121 (0.017996) 6; 40 12.318; 6.1575



D.3. 5-NN RESULTS

TABLE D.3.6 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 5-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.43061 (0.02548) 22; 40 39.982; 0.5692	0.4287 (0.02762) 11; 40 39.178; 4.6832	0.42395 (0.0321) 8; 40 37.306; 8.6756	0.42021 (0.03881) 6; 40 34.631; 11.8441
1.3	0.29754	Error (Std) Min; Max \bar{n} ; Sd	0.43251 (0.02921) 26; 40 39.986; 0.4427	0.43013 (0.0326) 11; 40 38.671; 5.8315	0.42692 (0.03658) 8; 40 36.393; 9.7504	0.41576 (0.04795) 6; 40 32.002; 13.582
1.5	0.27772	Error (Std) Min; Max \bar{n} ; Sd	0.43316 (0.03236) 21; 40 39.966; 0.7651	0.43418 (0.03322) 11; 40 38.583; 5.9881	0.42523 (0.04502) 8; 40 35.235; 11.0008	0.41317 (0.05415) 6; 40 31.031; 14.0708
2	0.22973	Error (Std) Min; Max \bar{n} ; Sd	0.44114 (0.03536) 21; 40 39.899; 1.3132	0.43581 (0.04063) 11; 40 37.365; 7.95	0.42276 (0.05574) 8; 40 33.076; 12.3897	0.39974 (0.07036) 6; 40 26.443; 15.159
2.3	0.20265	Error (Std) Min; Max \bar{n} ; Sd	0.44547 (0.03575) 21; 40 39.718; 2.1576	0.43284 (0.05082) 11; 40 35.764; 9.6803	0.41326 (0.069) 8; 40 29.79; 13.8388	0.39206 (0.07984) 6; 40 24.042; 15.0507
2.5	0.18551	Error (Std) Min; Max \bar{n} ; Sd	0.4445 (0.03635) 21; 40 39.517; 2.817	0.43124 (0.0547) 11; 40 35.169; 10.1494	0.41066 (0.07183) 8; 40 28.785; 13.9364	0.38618 (0.08564) 6; 40 22.239; 14.7034
3	0.14628	Error (Std) Min; Max \bar{n} ; Sd	0.44587 (0.04192) 21; 40 38.772; 4.2734	0.42105 (0.06971) 11; 40 32.333; 11.6052	0.38981 (0.08847) 8; 40 24.683; 13.9553	0.35973 (0.10269) 6; 40 17.695; 12.8894
4	0.08473	Error (Std) Min; Max \bar{n} ; Sd	0.44185 (0.05049) 21; 40 36.536; 6.4154	0.38467 (0.09713) 11; 40 26.051; 11.8011	0.34131 (0.11291) 8; 40 17.571; 10.3112	0.30578 (0.11667) 6; 40 12.605; 7.2595

D.4 3-nn results

D.4. 3-NN RESULTS

TABLE D.4.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 3-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.39172 (0.021777) 21; 90 89.931; 2.182	0.39169 (0.024267) 11; 90 87.6; 13.4286	0.38762 (0.025446) 8; 90 82.728; 22.9411	0.38796 (0.028179) 6; 90 76.368; 29.9515
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.34796 (0.024607) 24; 90 89.934; 2.0871	0.34575 (0.025236) 11; 90 86.918; 15.1119	0.34443 (0.027725) 8; 90 79.217; 27.135	0.34231 (0.029582 6; 90 69.703; 34.441
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.31676 (0.023472) 22; 90 89.864; 3.0395	0.31505 (0.026178) 11; 90 84.498; 19.7321	0.31335 (0.029644) 8; 90 74.399; 31.3084	0.31021 (0.033922 6; 90 60.673; 37.9134
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.24221 (0.022653) 21; 90 89.398; 6.3215	0.23806 (0.02362) 11; 90 77.97; 27.7126	0.23559 (0.028605) 8; 90 59.113; 37.4405	0.23479 (0.033729 6; 90 42.66; 37.1164
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.20237 (0.02125) 21; 90 87.966; 11.392	0.19944 (0.023581) 11; 90 71.578; 32.0532	0.19665 (0.026826) 8; 90 51.285; 37.6364	0.19744 (0.031488 6; 90 32.203; 33.0427
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.17892 (0.020614) 21; 90 86.164; 15.3737	0.17421 (0.022943) 11; 90 64.973; 34.8347	0.17474 (0.027917) 8; 90 45.633; 36.5035	0.17512 (0.03249) 6; 90 25.717; 28.0994
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.12603 (0.017224) 21; 90 79.008; 24.0248	0.12541 (0.020215) 11; 90 52.368; 35.4262	0.1253 (0.025664) 8; 90 27.356; 27.3635	0.12615 (0.029248 6; 90 16.819; 16.5841
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05692 (0.011568) 21; 90 56.826; 28.6241	0.05799 (0.014494) 11; 90 26.455; 18.4834	0.05796 (0.013016) 8; 90 16.274; 8.6034	0.05927 (0.017202 6; 90 11.959; 5.7582



TABLE D.4.2 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 3-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} : Sd	0.48528 (0.007337) 23; 90 89.933; 2.1187	0.48362 (0.010941) 11; 90 88.386; 11.0293	0.48044 (0.019645) 8; 90 83.952; 21.1633	0.47661 (0.026224) 6; 90 76.894; 29.5135
		n, su	09.935, 2.1167	00.300, 11.0233	03.932, 21.1033	70.034, 23.3133
1.3	0.29473	Error (Std) Min; Max	0.48639 (0.00822) 25; 90	0.48538 (0.012964) 11; 90	0.48107 (0.021532) 8; 90	0.47229 (0.032846) 6: 90
		\bar{n} ; Sd	89.935; 2.0555	87.079; 14.7172	80.53; 25.7445	68.481; 35.4979
1.5	0.27214	Error (Std) Min; Max	0.48747 (0.008276) 22: 90	0.48572 (0.013954) 11; 90	0.48219 (0.02224) 8; 90	0.46952 (0.038827) 6: 90
		\bar{n} ; Sd	89.803; 3.5949	85.404; 18.216	79.694; 26.3809	62.52; 37.3572
2	0.21843	Error (Std) Min; Max	0.49035 (0.008122) 21; 90	0.48592 (0.021276) 11; 90	0.47284 (0.039867) 8; 90	0.46383 (0.046541) 6; 90
		\bar{n} ; Sd	89.206; 7.2129	80.889; 24.5866	65.505; 35.9409	51.704; 38.417
2.3	0.18885	Error (Std) Min; Max	0.49054 (0.008725) 21; 90	0.4844 (0.025918) 11; 90	0.47296 (0.041601) 8; 90	0.45503 (0.057508) 6; 90
		\bar{n} ; Sd	88.394; 10.086	$75.594;\ 29.5917$	$59.964;\ 36.8411$	$39.528;\ 36.1869$
2.5	0.17042	Error (Std) Min; Max	0.49101 (0.010228) 21; 90	0.48299 (0.029293) 11; 90	0.47083 (0.045376) 8; 90	0.45375 (0.060451) 6; 90
		\bar{n} ; Sd	88.106; 10.9909	71.809; 31.9027	54.078; 37.3575	34.558; 33.551
3	0.12928	Error (Std) Min; Max	0.49088 (0.014025) 21; 90	0.47427 (0.042024) 11; 90	0.46031 (0.059006) 8; 90	0.43874 (0.070531) 6; 90
		\bar{n} ; Sd	83.388; 19.4522	$59.041;\ 35.9602$	$36.726;\ 33.3188$	$22.431;\ 24.0352$
4	0.06833	Error (Std) Min; Max	0.48428 (0.027055) 21; 90	0.45844 (0.05882) 11; 90	0.43228 (0.073295) 8; 90	0.40747 (0.084775) 6; 90
		\bar{n} ; Sd	66.744; 29.5869	33.402; 27.5377	20.097; 17.7052	$12.572;\ 8.4013$



TABLE D.4.3 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 3-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max	0.37104 (0.023112) 29; 90	0.37128 (0.022905) 11; 90	0.36882 (0.025041) 8; 90	0.36838 (0.0282) 6; 90
		\bar{n} ; Sd	89.939; 1.929	88.627; 10.1606	82.244; 23.5661	72.579; 32.7042
1.3	0.29754	Error (Std)	0.34917 (0.022847)	0.34747 (0.023812)	0.34667 (0.027186)	0.34416 (0.028594)
		Min; Max	21; 90	11; 90	8; 90	6; 90
		\bar{n} ; Sd	89.931; 2.182	87.995; 12.2813	79.485; 26.8133	$71.16;\ 33.5598$
1.5	0.27772	Error (Std)	0.3318 (0.023383)	0.33036 (0.025457)	0.32886 (0.027332)	0.32872 (0.032012)
		Min; Max	23; 90	11: 90	8: 90	6: 90
		\bar{n} ; Sd	89.933; 2.1187	86.116; 16.7781	77.527; 28.866	66.362; 35.9851
2	0.22973	Error (Std)	0.28136 (0.023891)	0.28021 (0.026451)	0.27769 (0.029602)	0.27483 (0.033094)
		Min; Max	21: 90	11: 90	8: 90	6: 90
		\bar{n} ; Sd	89.33; 6.6728	$82.726;\ 22.3923$	$70.154;\ 33.7939$	$54.911;\ 38.3179$
2.3	0.20265	Error (Std)	0.25019 (0.023997)	0.24798 (0.026197)	0.24489 (0.029991)	0.24242 (0.03448)
		Min; Max	21; 90	11; 90	8; 90	6; 90
		\bar{n} ; Sd	88.998; 8.1249	$79.548;\ 26.0293$	$62.698;\ 36.6844$	$45.874;\ 37.8914$
2.5	0.18551	Error (Std)	0.22905 (0.023946)	0.22632 (0.026271)	0.22568 (0.029665)	0.22535 (0.036741)
		Min; Max	21; 90	11; 90	8; 90	6; 90
		\bar{n} ; Sd	88.442; 9.9594	$75.041;\ 29.9259$	$59.3;\ 37.0329$	$41.091;\ 36.7081$
3	0.14628	Error (Std)	0.17764 (0.021018)	0.17732 (0.02539)	0.17298 (0.026092)	0.17516 (0.032837)
		Min; Max	21; 90	11; 90	8; 90	6; 90
		\bar{n} ; Sd	85.705; 16.1086	66.665; 34.1264	42.895; 35.9381	$27.317;\ 29.0824$
4	0.08473	Error (Std)	0.1002 (0.015097)	0.10134 (0.018631)	0.10226 (0.024309)	0.10397 (0.02713)
-		Min; Max	21; 90	11; 90	8; 90	6; 90
		\bar{n} ; Sd	73.88; 26.8382	41.797; 32.7118	22.025; 21.3859	14.032; 11.2883



TABLE D.4.4 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 3-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.39357 (0.030982) 23; 40 39.967; 0.7379	0.39229 (0.033702) 11; 40 39.376; 4.0283	0.39001 (0.034) 8; 40 37.407; 8.5079	0.38943 (0.035035) 6; 40 35.084; 11.5109
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.34834 (0.033819) 22; 40 39.965; 0.7826	0.34452 (0.034354) 11; 40 39.039; 4.9906	0.34499 (0.03632) 8; 40 36.17; 10.0255	0.34323 (0.037422) 6; 40 32.261; 13.4693
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.31688 (0.034872) 21; 40 39.956; 0.8347	0.31684 (0.034608) 11; 40 38.282; 6.5621	0.31374 (0.036979) 8; 40 34.306; 11.6334	0.31362 (0.038973) 6; 40 30.181; 14.4227
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.24196 (0.03162) 21; 40 39.659; 2.3884	0.2431 (0.033311) 11; 40 36.286; 9.1102	0.23916 (0.034535) 8; 40 30.285; 13.7033	0.23905 (0.038948) 6; 40 23.736; 15.2432
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.2028 (0.02945) 21; 40 39.353; 3.1674	0.20044 (0.02798) 11; 40 34.106; 10.8102	0.19877 (0.031281) 8; 40 26.472; 14.176	0.19884 (0.035) 6; 40 20.795; 14.271
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.17946 (0.026675) 21; 40 39.15; 3.602	0.17703 (0.029052) 11; 40 32.204; 11.6193	0.17668 (0.030434) 8; 40 25.105; 13.9992	0.17494 (0.033741) 6; 40 18.158; 13.1286
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.12847 (0.023725) 21; 40 37.868; 5.2353	0.12477 (0.022838) 11; 40 27.57; 12.1852	0.12534 (0.024392) 8; 40 20.376; 12.4737	0.12495 (0.02676) 6; 40 14.251; 9.9921
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05772 (0.013146) 21; 40 34.511; 7.0599	0.05817 (0.014663) 11; 40 22.615; 9.3544	0.05918 (0.017306) 8; 40 15.898; 6.4988	0.05959 (0.017662) 6; 40 12.002; 4.4748



TABLE D.4.5 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 3-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} ; Sd	0.3856 (0.03063) 22; 40 39.982; 0.5692	0.38742 (0.031068) 11; 40 39.482; 3.7285	0.38814 (0.032929) 8; 40 37.573; 8.2635	0.38625 (0.033353) 6; 40 34.482; 11.9649
1.3	0.29473	Error (Std) Min; Max \bar{n} ; Sd	0.35426 (0.032155) 25; 40 39.985; 0.4743	0.35381 (0.032967) 11; 40 38.851; 5.5088	0.35383 (0.0335) 8; 40 36.37; 9.7653	0.35228 (0.03661) 6; 40 32.744; 13.1969
1.5	0.27214	Error (Std) Min; Max \bar{n} ; Sd	0.33157 (0.034664) 28; 40 39.988; 0.3795	0.33036 (0.03324) 11; 40 38.625; 5.9109	0.32887 (0.034763) 8; 40 35.41; 10.7379	0.32719 (0.038121) 6; 40 31.604; 13.8305
2	0.21843	Error (Std) Min; Max \bar{n} ; Sd	0.26974 (0.032535) 21; 40 39.863; 1.4575	0.26896 (0.035273) 11; 40 37.12; 8.2175	0.2649 (0.035132) 8; 40 31.875; 13.1544	0.26448 (0.038265) 6; 40 26.512; 15.1299
2.3	0.18885	Error (Std) Min; Max \bar{n} ; Sd	0.23353 (0.033054) 21; 40 39.646; 2.4513	0.23046 (0.033772) 11; 40 34.968; 10.2919	0.22794 (0.033376) 8; 40 29.273; 13.9224	0.22628 (0.035137) 6; 40 23.802; 14.9461
2.5	0.17042	Error (Std) Min; Max \bar{n} ; Sd	0.2078 (0.029908) 21; 40 39.326; 3.1862	0.2064 (0.031027) 11; 40 34.319; 10.6794	0.20676 (0.032965) 8; 40 27.703; 14.2385	0.20371 (0.034122) 6; 40 21.691; 14.6322
3	0.12928	Error (Std) Min; Max \bar{n} ; Sd	0.15767 (0.026345) 21; 40 38.678; 4.3191	0.1553 (0.025536) 11; 40 30.529; 12.2089	0.15605 (0.030945) 8; 40 22.919; 13.4354	0.15538 (0.030674) 6; 40 16.831; 12.1695
4	0.06833	Error (Std) Min; Max \bar{n} ; Sd	0.08346 (0.018727) 21; 40 35.748; 6.752	0.08136 (0.016796) 11; 40 24.919; 11.0562	0.08394 (0.022692) 8; 40 17.074; 9.2116	0.08251 (0.020032) 6; 40 12.474; 6.1762



TABLE D.4.6 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the 3-nn classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.4552 (0.02009) 21; 40 39.981; 0.6008	0.45499 (0.021269) 11; 40 39.504; 3.6171	0.45036 (0.025856) 8; 40 37.306; 8.6513	0.44514 (0.032981) 6; 40 33.968; 12.317
1.3	0.29754	Error (Std) Min; Max \bar{n} ; Sd	0.45876 (0.0206) 24; 40 39.984; 0.506	0.45734 (0.023308) 11; 40 39.081; 4.8565	0.45348 (0.027979) 8; 40 37.012; 8.998	0.44465 (0.037658) 6; 40 32.378; 13.552
1.5	0.27772	Error (Std) Min; Max \bar{n} ; Sd	0.46003 (0.021726) 21; 40 39.948; 0.953	0.45849 (0.024087) 11; 40 38.919; 5.3121	0.4532 (0.031151) 8; 40 36.149; 10.0247	0.44398 (0.039247) 6; 40 31.415; 14.0089
2	0.22973	Error (Std) Min; Max \bar{n} ; Sd	0.46513 (0.023061) 21; 40 39.885; 1.3826	0.46055 (0.029709) 11; 40 37.35; 7.9882	0.45166 (0.043546) 8; 40 32.264; 12.9896	0.43854 (0.053676) 6; 40 27.46; 15.0951
2.3	0.20265	Error (Std) Min; Max \bar{n} ; Sd	0.46842 (0.023388) 21; 40 39.649; 2.4265	0.46261 (0.031914) 11; 40 36.214; 9.2082	0.45155 (0.045113) 8; 40 30.723; 13.5376	0.4353 (0.058335) 6; 40 25.297; 15.1314
2.5	0.18551	Error (Std) Min; Max \bar{n} ; Sd	0.46842 (0.024383) 21; 40 39.573; 2.643	0.46326 (0.034579) 11; 40 35.982; 9.3953	0.44478 (0.053689) 8; 40 28.896; 14.1434	0.43143 (0.061907) 6; 40 23.317; 14.8676
3	0.14628	Error (Std) Min; Max \bar{n} ; Sd	0.4715 (0.023959) 21; 40 39.135; 3.5586	0.45867 (0.044452) 11; 40 32.694; 11.3888	0.43695 (0.063977) 8; 40 25.324; 13.8616	0.4187 (0.071335) 6; 40 18.742; 13.3721
4	0.08473	Error (Std) Min; Max \bar{n} ; Sd	0.47105 (0.030817) 21; 40 36.855; 6.2197	0.44462 (0.061241) 11; 40 26.324; 11.5999	0.41695 (0.079434) 8; 40 19.081; 11.0799	0.38996 (0.086296) 6; 40 13.219; 8.1392



D.5 LRIM results

TABLE D.5.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LRIM classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.34321 (0.022092) 23; 90 89.933; 2.1187	0.34223 (0.020212) 11; 90 87.448; 13.8267	0.34343 (0.022548) 8; 90 81.771; 24.1033	0.34312 (0.022382) 6; 90 71.967; 32.626
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.29573 (0.013159) 21; 90 89.662; 4.7714	0.29548 (0.013211) 11; 90 84.825; 19.1871	0.29678 (0.013767) 8; 90 74.848; 30.8957	0.29688 (0.017492) 6; 90 60.863; 37.6043
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.26723 (0.011193) 22; 90 89.676; 4.5863	0.2675 (0.011418) 11; 90 82.879; 22.1823	0.26852 (0.014951) 8; 90 71.839; 32.8119	0.27016 (0.01764) 6; 90 54.38; 37.9256
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.20222 (0.006478) 21; 90 88.797; 8.707	0.2037 (0.008973) 11; 90 75.59; 29.418	0.2051 (0.01155) 8; 90 54.502; 37.4299	0.20814 (0.015034) 6; 90 33.652; 32.6839
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.16987 (0.006159) 21; 90 86.37; 14.9604	0.17127 (0.010333) 11; 90 66.835; 33.9901	0.17347 (0.012298) 8; 90 42.949; 35.6598	0.17531 (0.014156) 6; 90 25.233; 27.0529
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.1498 (0.005169) 21; 90 85.36; 16.7214	0.15172 (0.009265) 11; 90 58.711; 35.7186	0.15429 (0.01389) 8; 90 35.966; 33.0031	0.15598 (0.013704) 6; 90 19.354; 20.1823
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.10817 (0.006161) 21; 90 76.273; 26.1044	0.11106 (0.010497) 11; 90 43.937; 33.4581	0.11279 (0.012403) 8; 90 23.224; 21.5337	0.11357 (0.0129) 6; 90 13.882; 10.9684
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05298 (0.006028) 21; 90 54.574; 28.6094	0.05453 (0.008534) 11; 90 24.486; 15.3112	0.05532 (0.009749) 8; 82 15.28; 5.9858	0.05627 (0.010761) 6; 55 11.683; 3.8193



TABLE D.5.2 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LRIM classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} ; Sd	0.35661 (0.030651) 21; 90 89.931; 2.182	0.35656 (0.031817) 11; 90 87.905; 12.5848	0.35683 (0.032831) 8; 90 83.609; 21.6526	0.35921 (0.034343) 6; 90 73.933; 31.811
1.3	0.29473	Error (Std) Min; Max \bar{n} ; Sd	0.31405 (0.023897) 23; 90 89.87; 2.9068	0.31532 (0.024884) 11; 90 87.556; 13.4558	0.31332 (0.024811) 8; 90 77.992; 28.0492	0.31461 (0.028482) 6; 90 65.171; 35.9034
1.5	0.27214	Error (Std) Min; Max \bar{n} ; Sd	0.28594 (0.019476) 22; 90 89.932; 2.1503	0.28673 (0.020435) 11; 90 84.294; 20.137	0.28742 (0.023892) 8; 90 74.373; 31.1169	0.28861 (0.025745) 6; 90 57.543; 38.3332
2	0.21843	Error (Std) Min; Max \bar{n} ; Sd	0.22492 (0.011295) 21; 90 89.35; 6.4818	0.22623 (0.013054) 11; 90 77.99; 27.5135	0.22799 (0.014911) 8; 90 60.576; 36.7273	0.22929 (0.018452) 6; 90 41.619; 36.5687
2.3	0.18885	Error (Std) Min; Max \bar{n} ; Sd	0.19343 (0.00794) 21; 90 88.211; 10.7548	0.19505 (0.011899) 11; 90 71.905; 32.006	0.19659 (0.014635) 8; 90 52.084; 37.2906	0.199 (0.016005) 6; 90 33.635; 32.7116
2.5	0.17042	Error (Std) Min; Max \bar{n} ; Sd	0.17438 (0.00704) 21; 90 86.931; 13.7569	0.17647 (0.011585) 11; 90 68.128; 33.6102	0.1782 (0.013331) 8; 90 44.84; 36.412	0.18146 (0.020007) 6; 90 26.713; 28.6331
3	0.12928	Error (Std) Min; Max \bar{n} ; Sd	0.13312 (0.006529) 21; 90 82.257; 20.9007	0.13523 (0.010408) 11; 90 55.383; 35.5615	0.13774 (0.012981) 8; 90 32.69; 30.1293	0.13961 (0.014768) 6; 90 17.48; 18.3451
4	0.06833	Error (Std) Min; Max \bar{n} ; Sd	0.07607 (0.008425) 21; 90 66.061; 29.8858	0.07861 (0.01159) 11; 90 31.88; 25.8305	0.08006 (0.014317) 8; 90 16.782; 10.7704	0.08009 (0.013937) 6; 83 12.004; 5.7697



TABLE D.5.3 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LRIM classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.37024 (0.044895) 90; 90 90; 0	0.36938 (0.043749) 11; 90 88.382; 11.0571	0.36871 (0.045063) 8; 90 82.384; 23.3289	0.37281 (0.049199) 6; 90 74.246; 31.5387
1.3	0.29754	Error (Std) Min; Max \bar{n} ; Sd	0.32656 (0.034877) 24; 90 89.803; 3.5932	0.32566 (0.03293) 11; 90 87.5; 13.6963	0.32463 (0.033979) 8; 90 78.952; 27.3065	0.3248 (0.03642) 6; 90 65.851; 36.073
1.5	0.27772	Error (Std) Min; Max \bar{n} ; Sd	0.29889 (0.025596) 22; 90 89.867; 2.9732	0.29903 (0.028859) 11; 90 85.849; 17.3942	0.29869 (0.028373) 8; 90 74.992; 30.7914	0.30133 (0.032515) 6; 90 64.231; 36.3779
2	0.22973	Error (Std) Min; Max \bar{n} ; Sd	0.23999 (0.015894) 21; 90 89.388; 6.4263	0.24013 (0.016679) 11; 90 80.116; 25.4999	0.24261 (0.019197) 8; 90 66.034; 35.6971	0.24385 (0.027122) 6; 90 46.182; 38.0856
2.3	0.20265	Error (Std) Min; Max \bar{n} ; Sd	0.2096 (0.012568) 21; 90 89.145; 7.4573	0.21081 (0.014377) 11; 90 75.566; 29.3639	0.21258 (0.015641) 8; 90 55.684; 37.5297	0.21536 (0.02424) 6; 90 39.249; 35.1915
2.5	0.18551	Error (Std) Min; Max \bar{n} ; Sd	0.19023 (0.008723) 21; 90 88.2; 10.6457	0.19226 (0.011123) 11; 90 71.959; 31.9092	0.19512 (0.015605) 8; 90 49.833; 37.5697	0.19693 (0.018229) 6; 90 31.577; 32.4725
3	0.14628	Error (Std) Min; Max \bar{n} ; Sd	0.15015 (0.006662) 21; 90 85.434; 16.6738	0.15326 (0.011835) 11; 90 62.348; 35.2392	0.15528 (0.01336) 8; 90 36.581; 32.5813	0.15821 (0.018936) 6; 90 20.405; 22.0441
4	0.08473	Error (Std) Min; Max \bar{n} ; Sd	0.09352 (0.009206) 21; 90 73.71; 27.2572	0.09682 (0.013424) 11; 90 39.688; 31.0294	0.09807 (0.01515) 8; 90 19.908; 17.3107	0.09903 (0.016667) 6; 90 12.483; 8.0551



TABLE D.5.4 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LRIM classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,2)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32771	Error (Std) Min; Max \bar{n} ; Sd	0.34926 (0.031343) 21; 40 39.981; 0.6008	0.34995 (0.03346) 11; 40 39.315; 4.294	0.34864 (0.030902) 8; 40 36.799; 9.3066	0.35134 (0.037352) 6; 40 33.275; 12.9652
1.3	0.28633	Error (Std) Min; Max \bar{n} ; Sd	0.30048 (0.021323) 23; 40 39.968; 0.7166	0.30008 (0.023404) 11; 40 38.282; 6.5579	0.30229 (0.025664) 8; 40 35.204; 10.9594	0.30179 (0.024801) 6; 40 31.122; 14.0018
1.5	0.25982	Error (Std) Min; Max \bar{n} ; Sd	0.26974 (0.01678) 21; 40 39.946; 0.988	0.27184 (0.019493) 11; 40 38.168; 6.7469	0.27175 (0.019917) 8; 40 33.612; 12.0751	0.27299 (0.021182) 6; 40 28.231; 14.9074
2	0.19885	Error (Std) Min; Max \bar{n} ; Sd	0.2054 (0.011534) 21; 40 39.699; 2.1788	0.2062 (0.013043) 11; 40 34.172; 10.8557	0.20711 (0.013785) 8; 40 28.005; 14.1075	0.20922 (0.0177) 6; 40 21.27; 14.6065
2.3	0.16656	Error (Std) Min; Max \bar{n} ; Sd	0.17233 (0.009645) 21; 40 39.188; 3.4838	0.1729 (0.010467) 11; 40 32.768; 11.4942	0.17462 (0.012467) 8; 40 25.281; 14.1195	0.17587 (0.01415) 6; 40 18.613; 13.2493
2.5	0.14697	Error (Std) Min; Max \bar{n} ; Sd	0.15189 (0.007591) 21; 40 38.872; 4.1159	0.15368 (0.009851) 11; 40 30.632; 12.2539	0.15464 (0.010937) 8; 40 22.367; 13.4611	0.15593 (0.015927) 6; 40 16.473; 11.5894
3	0.10485	Error (Std) Min; Max \bar{n} ; Sd	0.10996 (0.00776) 21; 40 37.51; 5.6498	0.11176 (0.010843) 11; 40 26.758; 12.2308	0.11289 (0.012427) 8; 40 18.532; 11.1349	0.11422 (0.014432) 6; 40 13.495; 8.4692
4	0.04789	Error (Std) Min; Max \bar{n} ; Sd	0.05363 (0.007139) 21; 40 34; 7.2119	0.05461 (0.008654) 11; 40 22.768; 9.3724	0.05591 (0.010262) 8; 40 15.386; 5.9315	0.05632 (0.011065) 6; 40 11.882; 3.9045



TABLE D.5.5 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LRIM classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,3)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.32919	Error (Std) Min; Max \bar{n} : Sd	0.36683 (0.047542) 22; 40 39.982; 0.5692	0.36676 (0.04473) 11; 40 39.063; 5.003	0.36648 (0.044871) 8; 40 37.187; 8.7945	0.37004 (0.051158) 6; 40 34.336; 12.0658
1.3	0.29473	Error (Std) Min; Max \bar{n} ; Sd	0.31878 (0.033682) 23; 40 39.966; 0.7599	0.31923 (0.034966) 11; 40 39.011; 5.0749	0.32145 (0.036532) 8; 40 35.92; 10.3288	0.32056 (0.036299) 6; 40 31.495; 14.0346
1.5	0.27214	Error (Std) Min; Max \bar{n} ; Sd	0.29198 (0.029549) 21; 40 39.963; 0.8272	0.29198 (0.029839) 11; 40 37.966; 7.1369	0.29228 (0.032058) 8; 40 33.98; 11.9482	0.29378 (0.034066) 6; 40 28.825; 14.8945
2	0.21843	Error (Std) Min; Max \bar{n} ; Sd	0.22826 (0.016839) 23; 40 39.911; 1.1526	0.22962 (0.01913) 11; 40 36.262; 9.2036	0.23188 (0.02394) 8; 40 30.955; 13.4049	0.23149 (0.021645) 6; 40 24.329; 15.1144
2.3	0.18885	Error (Std) Min; Max \bar{n} ; Sd	0.19624 (0.013342) 21; 40 39.494; 2.7389	0.19763 (0.01436) 11; 40 34.401; 10.6692	0.19961 (0.018911) 8; 40 27.404; 14.1794	0.20138 (0.021371) 6; 40 21.352; 14.4776
2.5	0.17042	Error (Std) Min; Max \bar{n} ; Sd	0.17732 (0.011333) 21; 40 39.29; 3.3537	0.17932 (0.015112) 11; 40 32.707; 11.6783	0.17985 (0.014651) 8; 40 25.826; 14.2547	0.17981 (0.014612) 6; 40 19.037; 13.5243
3	0.12928	Error (Std) Min; Max \bar{n} ; Sd	0.13528 (0.008498) 21; 40 38.368; 4.8231	0.13693 (0.011078) 11; 40 29.463; 12.3366	0.13807 (0.013833) 8; 40 21.095; 12.9532	0.14033 (0.015943) 6; 40 14.702; 10.3468
4	0.06833	Error (Std) Min; Max \bar{n} ; Sd	0.07664 (0.009478) 21; 40 35.534; 6.9528	0.07855 (0.012151) 11; 40 24.048; 10.7124	0.07976 (0.013665) 8; 40 16.153; 7.853	0.07989 (0.013984) 6; 40 11.746; 5.0888



TABLE D.5.6 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LRIM classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated a $N(\Delta,4)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 40 (i.e. M=40). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$ $0.38172 \ (0.060556)$ $6; \ 40$ $34.975; \ 11.5586$	
1	0.32743	Error (Std) Min; Max \bar{n} ; Sd	0.38395 (0.060374) 27; 40 39.987; 0.4111	0.38187 (0.059518) 11; 40 39.274; 4.385	0.37992 (0.058269) 8; 40 37.513; 8.2841		
1.3	0.29754	Error (Std) Min; Max \bar{n} ; Sd	0.33832 (0.052738) 22; 40 39.947; 0.967	0.33416 (0.048372) 11; 40 39.027; 5.0529	0.33413 (0.04926) 8; 40 35.563; 10.6616	0.33375 (0.050707) 6; 40 31.621; 13.7554	
1.5	0.27772	Error (Std) Min; Max \bar{n} ; Sd	0.30961 (0.042489) 21; 40 39.936; 1.0349	0.30894 (0.044759) 11; 40 38.247; 6.6437	0.30816 (0.044169) 8; 40 35.085; 11.0313	0.30793 (0.044131) 6; 40 30.391; 14.3168	
2	0.22973	Error (Std) Min; Max \bar{n} ; Sd	0.24422 (0.025062) 21; 40 39.777; 1.895	0.24554 (0.026011) 11; 40 37.101; 8.2092	0.24643 (0.027813) 8; 40 31.542; 13.2497	0.24794 (0.0289) 6; 40 25.166; 15.1485	
2.3	0.20265	Error (Std) Min; Max \bar{n} ; Sd	0.21418 (0.021255) 21; 40 39.687; 2.3204	0.21625 (0.024131) 11; 40 34.825; 10.4703	0.21723 (0.025172) 8; 40 29.418; 13.8575	0.21893 (0.031311) 6; 40 23.051; 14.8569	
2.5	0.18551	Error (Std) Min; Max \bar{n} ; Sd	0.1955 (0.017943) 21; 40 39.478; 2.8649	0.19607 (0.018171) 11; 40 34.792; 10.3935	0.19785 (0.020131) 8; 40 27.458; 14.1972	0.19799 (0.019091) 6; 40 20.901; 14.3016	
3	0.14628	Error (Std) Min; Max \bar{n} ; Sd	0.15359 (0.013717) 21; 40 38.738; 4.2689	0.15492 (0.01322) 11; 40 30.814; 12.2029	0.15661 (0.016054) 8; 40 22.413; 13.5995	0.15783 (0.016823) 6; 40 16.735; 11.9037	
4	0.08473	Error (Std) Min; Max \bar{n} ; Sd	0.09469 (0.010962) 21; 40 36.484; 6.4957	0.09657 (0.013524) 11; 40 25.826; 11.6396	0.09893 (0.017288) 8; 40 17.75; 10.1283	0.09866 (0.015547) 6; 40 12.431; 7.0953	



D.6. CHANGES TO SAMPLING PROBABILITIES

D.6 Changes to sampling probabilities

TABLE D.6.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 9 initial observations were generated from a N(0,1) distribution and 1 observation was generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$	
1	0.098664	Error (Std) Min; Max \bar{n} ; Sd	0.10225 (0.026447) 21; 90 77.817; 24.843	0.10498 (0.044611) 11; 90 50.492; 33.7206	0.1116 (0.0762) 8; 90 30.509; 27.1625	0.11494 (0.084567) 6; 90 20.11; 18.897	
1.3	0.093761	Error (Std) Min; Max \bar{n} ; Sd	0.0967 (0.005075) 21; 90 78.008; 24.7133	0.10131 (0.045158) 11; 90 46.024; 33.2122	0.10192 (0.038002) 8; 90 25.781; 22.798	0.10877 (0.072855) 6; 90 16.554; 14.7071	
1.5	0.088312	Error (Std) Min; Max \bar{n} ; Sd	0.09194 (0.004915) 21; 90 73.131; 27.6366	0.09506 (0.027302) 11; 90 41.933; 31.8929	0.09823 (0.04567) 8; 90 24.459; 22.2731	0.10089 (0.052934) 6; 90 14.842; 12.4204	
2	0.070061	Error (Std) Min; Max \bar{n} ; Sd	0.07461 (0.007512) 21; 90 66.587; 29.5584	0.07742 (0.010173) 11; 90 33.837; 26.648	0.08094 (0.038682) 8; 90 18.163; 14.0808	0.08338 (0.040373) 6; 90 13.117; 8.5015	
2.3	0.058151	Error (Std) Min; Max \bar{n} ; Sd	0.06263 (0.007725) 21; 90 58.837; 29.5645	0.06622 (0.011103) 11; 90 27.295; 20.5604	0.06844 (0.029516) 8; 90 16.491; 9.7223	0.06997 (0.030014) 6; 66 12.308; 5.8753	
2.5	0.050496	Error (Std) Min; Max \bar{n} ; Sd	0.05473 (0.007316) 21; 90 56.338; 29.2241	0.05878 (0.028859) 11; 90 26.389; 17.4138	0.05979 (0.012412) 8; 77 16.319; 8.1052	0.06143 (0.029758) 6; 59 11.828; 4.7258	
3	0.033651	Error (Std) Min; Max \bar{n} ; Sd	0.03774 (0.007368) 21; 90 48.116; 23.9813	0.03963 (0.0091) 11; 90 23.523; 11.2685	0.04057 (0.010352) 8; 52 16.096; 5.2633	0.04133 (0.011524) 6; 43 12.258; 3.4154	
4	0.0122	Error (Std) Min; Max \bar{n} ; Sd	0.01401 (0.003331) 21; 90 45.553; 16.197	0.01557 (0.005611) 11; 53 24.749; 6.5831	0.01611 (0.005976) 8; 29 17.061; 3.6073	0.01687 (0.007458 6; 22 12.993; 2.3118	



D.6. CHANGES TO SAMPLING PROBABILITIES

TABLE D.6.2 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 8 initial observations were generated from a N(0,1) distribution and 2 observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon=0.15$	$\epsilon=0.20$
1	0.18616	Error (Std) Min; Max \bar{n} ; Sd	0.19046 (0.005939) 21; 90 87.171; 13.3666	0.19257 (0.028325) 11; 90 75.465; 29.5437	0.19392 (0.022398) 8; 90 54.239; 37.0799	0.19765 (0.031246) 6; 90 36.393; 33.727
1.3	0.16672	Error (Std) Min; Max \bar{n} ; Sd	0.17098 (0.006678) 21; 90 87.121; 13.3035	0.17344 (0.011299) 11; 90 70.53; 32.3272	0.17502 (0.012073) 8; 90 47.176; 36.4995	0.18088 (0.042394) 6; 90 27.27; 28.5264
1.5	0.15147	Error (Std) Min; Max \bar{n} ; Sd	0.15578 (0.007262) 21; 90 85.861; 15.7832	0.15833 (0.011653) 11; 90 62.164; 35.1934	0.16137 (0.02448) 8; 90 39.594; 34.6786	0.16308 (0.015486) 6; 90 22.963; 23.8766
2	0.11207	Error (Std) Min; Max \bar{n} ; Sd	0.11584 (0.007707) 21; 90 80.838; 22.2787	0.11839 (0.01179) 11; 90 48.292; 34.6782	0.12085 (0.013284) 8; 90 26.975; 26.3049	0.1229 (0.016186) 6; 90 15.261; 13.1234
2.3	0.09028	Error (Std) Min; Max \bar{n} ; Sd	0.09353 (0.006207) 21; 90 72.473; 27.9107	0.0966 (0.01102) 11; 90 41.437; 31.8886	0.09941 (0.013595) 8; 90 20.288; 18.0169	0.1014 (0.016833) 6; 90 12.927; 8.7389
2.5	0.07714	Error (Std) Min; Max \bar{n} ; Sd	0.08055 (0.006219) 21; 90 67.642; 29.4206	0.08315 (0.009691) 11; 90 35.615; 27.6538	0.08484 (0.011095) 8; 90 17.884; 12.8587	0.08725 (0.01588) 6; 61 12.42; 6.6786
3	0.04983	Error (Std) Min; Max \bar{n} ; Sd	0.05273 (0.005114) 21; 90 53.821; 27.9111	0.05481 (0.008117) 11; 90 26.066; 17.2744	0.05636 (0.009283) 8; 74 16.259; 8.002	0.05747 (0.01037) 6; 56 12.067; 4.3932
4	0.0174	Error (Std) Min; Max \bar{n} ; Sd	0.01921 (0.003242) 21; 90 45.062; 17.9185	0.02002 (0.004331) 11; 76 24.328; 7.5398	0.02074 (0.005767) 8; 29 16.861; 3.7659	0.02099 (0.005194) 6; 21 12.821; 2.4118



D.6. CHANGES TO SAMPLING PROBABILITIES

TABLE D.6.3 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 6 initial observations were generated from a N(0,1) distribution and 4 observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 90 (i.e. M=90). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.2945	Error (Std) Min; Max \bar{n} ; Sd	0.29926 (0.008016) 21; 90 89.865; 3.0179	0.29977 (0.01028) 11; 90 86.391; 16.2662	0.30086 (0.012626) 8; 90 77.098; 28.9675	0.30301 (0.015594) 6; 90 61.648; 37.5361
1.3	0.24789	Error (Std) Min; Max \bar{n} ; Sd	0.2515 (0.006611) 21; 90 89.535; 5.545	0.25206 (0.007578) 11; 90 81.815; 23.6122	0.2536 (0.011309) 8; 90 69.696; 33.9644	0.25615 (0.016119) 6; 90 49.839; 37.889
1.5	0.21856	Error (Std) Min; Max \bar{n} ; Sd	0.22171 (0.006204) 21; 90 89.129; 7.5979	0.2228 (0.009954) 11; 90 77.902; 27.6509	0.22447 (0.010955) 8; 90 60.662; 37.2291	0.22697 (0.01647) 6; 90 40.918; 36.1438
2	0.15378	Error (Std) Min; Max \bar{n} ; Sd	0.15639 (0.005393) 21; 90 85.66; 16.2358	0.15825 (0.007623) 11; 90 61.804; 35.3964	0.16005 (0.011232) 8; 90 39.059; 33.7807	0.16171 (0.012494) 6; 90 21.264; 22.7407
2.3	0.12146	Error (Std) Min; Max \bar{n} ; Sd	0.12398 (0.005067) 21; 90 81.153; 21.9087	0.12579 (0.008092) 11; 90 52.55; 35.5923	0.12841 (0.010793) 8; 90 27.428; 26.6925	0.12993 (0.012452) 6; 90 16.293; 15.6695
2.5	0.1027	Error (Std) Min; Max \bar{n} ; Sd	0.1048 (0.004987) 21; 90 76.55; 25.5821	0.10741 (0.00841) 11; 90 44.975; 33.4877	0.10908 (0.010715) 8; 90 21.759; 20.0345	0.11024 (0.01161) 6; 90 13.658; 10.3907
3	0.06507	Error (Std) Min; Max \bar{n} ; Sd	0.06744 (0.004433) 21; 90 60.75; 29.9426	0.06926 (0.007111) 11; 90 29.427; 22.5406	0.07065 (0.009354) 8; 90 16.495; 9.8049	0.07173 (0.009869) 6; 72 11.795; 5.0299
4	0.02221	Error (Std) Min; Max \bar{n} ; Sd	0.02375 (0.002975) 21; 90 44.116; 18.3193	0.02448 (0.003917) 11; 65 23.78; 7.5385	0.02497 (0.004302) 8; 35 16.347; 4.0987	0.02511 (0.004673) 6; 33 12.624; 2.6829



D.7. CHANGING MAXIMUM NUMBER OF SEQUENTIAL STEPS

D.7 Changing maximum number of sequential steps

TABLE D.7.1 - The average and standard deviation of the misclassification rate (denoted Error and Std respectively) in training the LDA classifier is given below. 5 initial observations were generated from a N(0,1) distribution and 5 additional observations were generated from a $N(\Delta,1)$ distribution, $\alpha=0.05$ and the maximum number of sequential steps is 300 (i.e. M=300). The minimum, maximum, mean and standard deviation of the number of sequential steps required to train the classifier is also provided (denoted Min, Max, \bar{n} and Sd respectively).

Δ	Bayes error		$\epsilon = 0.05$	$\epsilon = 0.10$	$\epsilon = 0.15$	$\epsilon = 0.20$
1	0.30854	Error (Std) 0.3116 (0.006455508) Min; Max 23; 300 \bar{n} ; Sd 299.723; 8.75951		0.31243 (0.010963) 11; 300 290.47; 51.196	0.31551 (0.019036) 8; 300 247.571; 107.621	0.31926 (0.025056) 6; 300 183.643; 128.818
1.3	0.25785	Error (Std) Min; Max \bar{n} ; Sd	0.261 (0.006524) 21; 300 298.342; 21.352	0.26293 (0.013892) 11; 300 276.46; 77.858	0.26774 (0.02549) 8; 300 214.121; 122.996	0.27162 (0.027994) 6; 300 128.188; 119.637
1.5	0.22663	Error (Std) Min; Max \bar{n} ; Sd	0.23009 (0.00736) 21; 300 297.238; 27.496	0.2329 (0.01807) 11; 300 263.568; 93.408	0.24028 (0.029012) 8; 300 180.131; 128.659	0.24709 (0.036581) 6; 300 90.52; 103.66
2	0.15866	Error (Std) Min; Max \bar{n} ; Sd	0.16332 (0.011152) 21; 300 288.726; 54.556	0.17098 (0.029493) 11; 300 209.605; 122.798	0.1807 (0.040026) 8; 300 84.253; 96.374	0.18882 (0.045265) 6; 300 31.797; 43.806
2.3	0.12507	Error (Std) Min; Max \bar{n} ; Sd	0.13109 (0.01504) 21; 300 278.697; 72.449	0.144 (0.039547) 11; 300 151.871; 125.587	0.15594 (0.050247) 8; 300 47.81; 65.011	0.16581 (0.061292) 6; 210 20.547; 25.992
2.5	0.10565	Error (Std) Min; Max \bar{n} ; Sd	0.11282 (0.016814) 21; 300 263.073; 92.03	0.12694 (0.043258) 11; 300 111.339; 112.812	0.13572 (0.048943) 8; 300 35.646; 45.936	0.14534 (0.059173) 6; 234 16.752; 17.778
3	0.06681	Error (Std) Min; Max \bar{n} ; Sd	0.0775 (0.021215) 21; 300 210.269; 120.207	0.09704 (0.049834) 11; 300 50.234; 62.692	0.10324 (0.06012) 8; 228 20.858; 22.037	0.11316 (0.066498) 6; 87 11.982; 7.006
4	0.02275	Error (Std) Min; Max \bar{n} ; Sd	0.04087 (0.03075) 21; 300 72.33; 69.521	0.05803 (0.060197) 11; 300 24.957; 18.653	0.06842 (0.074307) 8; 98 15.298; 7.001	0.06586 (0.071539) 6; 62 11.773; 3.702



D.8. CRITICAL VALUES FOR PRESCRIBED COVERAGE PROBABILITY

D.8 Critical values for prescribed coverage probability

TABLE D.8.1 - The parameter values for a and γ as determined by Frey (2010), used to determine a fixed-width interval for a proportion p. The half-width of the interval is denoted by h.

	$\alpha = 0.$		α	= 0.05	α	= 0.01
Half-width h	α	γ	$ \alpha$	γ	$\parallel \alpha$	γ
0.1 0.05 0.01	4 4 8	0.0754 0.0859 0.0972	4 6 10	0.0356 0.0433 0.0487	6 8 14	0.0068 0.0083 0.0097



Appendix E

SAS Code

```
options compress = Y minoperator cpucount = actual threads;
   %macro determine sample size(StopRule, sample sz1, sample sz2, mu1, mu2, sig1, sig2,
                                 eps,alpha,h,repititions,max sample,lambda method,
                                 Nearest Neighbours, two normal out m);
   %if &StopRule. = 'NEW' %then %do;
       \%let eps loop = 0.2;
       \%let epsloop = 20;
   \%end;
   proc iml;
   start LDA two normal distributions (StopRule, sample sz1, sample sz2, mu1, mu2, sig1,
                                     sig2,eps,alpha,h,repititions,max sample,lambda method,
                                     KNN Neighbours, two normal out m);
   /*StopRule - NEW indicates proposed method, OLD indicates current methodology*/
   /*sample sz1 = the number of observations to generate from sample1;*/
   /*sample sz2 = the number of observations to generate from sample2;*/
   /*mu1 = mean value for generating sample1 observations;*/
   /*mu2 = mean value for generating sample2 observations;*/
   /*sig1 = variance for generating sample1 observations;*/
   /*sig2 = variance for generating sample2 observations;*/
   /*eps = epsilon;*/
   /*a = alpha significance level;*/
   /*h = halfwidth of confidence interval for proposed approach*/
   /*repititions = number of repititions that the recursive method should be iterated;*/
   /*max sample = maximum number of trails allowed;*/
   /*lambda method = LDA, QDA, KNN, REG variable to select whether lambda is
   calculated using K-Nearest, LDA, QDA or Regression of Indicator Matrix*/
   /*KNN Neighbours = K-Nearest Neighbours if LAMBDA METHOD = KNN*/
```





```
/*two normal out m = Output matrix for two normal distribution inputs*/
sampsize1 = sample sz1;
sampsize2 = sample sz2;
epsilon = eps;
mean1 = mu1;
             **** changes with delta;
mean2 = mu2;
var1 = sig1;
var2 = sig2;
sample ratio = sample sz1/(sample sz1 + sample sz2);
if KNN Neighbours > 0 then KNN Number = KNN Neighbours;
if strip(upcase(StopRule)) = 'NEW' then max sample = 50000;
N_{Zero} = \log(alpha)/(\log(1-epsilon));
do rep1 = 1 to repititions;
   sample = (randnormal(sampsize1,mean1,var1)||J(sampsize1,1,0))//
   (randnormal(sampsize2,mean2,var2)||J(sampsize2,1,1));
   ******* Determining the initial Classifier - LDA ********;
   if upcase(lambda method) = 'LDA' then do;
       lambda use in = sample;
       call lambda calc LDA(lambda use in,lambda use);
   end;
   if upcase(lambda method) = 'QDA' then do;
       lambda use in = sample;
       call lambda calc QDA(lambda use in,lambda use,qda mean 0,
                            qda mean 1,qda var 0,qda var 1);
   end;
   if upcase(lambda method) = 'REG' then do;
       lambda use in = sample;
       call lambda calc REG(lambda use in,lambda use);
   end;
   ****** Set up initial variables ******;
   Perfect Class Counter = 0;
   Missclass Matrix = J(1,1,0);
```



```
******* Recursive run to reach stopping critria ********
do i3 = 1 to max sample;
    ****** Randomly Sampling Record *******;
    u = ranuni(0);
    val chosen = randnormal(1, mean1, var1)||0;
    if u >= sample ratio then val chosen = randnormal(1,mean2,var2)||1;
    sample = sample/val chosen;
    ****** Reclassifying Lambda - KNN *******;
    if upcase(lambda method) = 'KNN' then do;
         call lambda calc KNN(sample,KNN Number,lambda use);
    end;
    ******* Classify Sampled Record ********;
    if upcase(lambda method) = 'LDA' then do;
        if (val chosen[,2] = 0 \& val chosen[,1] < lambda use)
         (\text{val chosen}[,2] = 1 \& \text{val chosen}[,1] >= \text{lambda use}) \text{ then do};
             Missclass Matrix = Missclass Matrix//0;
             Perfect Class Counter = Perfect Class Counter + 1;
        end:
        else do;
             Missclass Matrix = Missclass Matrix//1;
             Perfect Class Counter = 0;
        end;
    end:
    if upcase(lambda method) = 'QDA' then do;
        if (val chosen[,2] = 0 \& 0.5*((\text{val chosen}[,1]-\text{qda mean }0)^*
        inv(qda \ var \ 0)*(val \ chosen[,1]-qda \ mean \ 0) -
         (val chosen[,1]-qda mean 1)*inv(qda var 1)*
         (val chosen[,1]-qda mean 1)) < lambda use)
         (\text{val chosen}[,2] = 1 \& 0.5*((\text{val chosen}[,1]-\text{qda mean }0)^*
        inv(qda \ var \ 0)*(val \ chosen[,1]-qda \ mean \ 0) -
         (val chosen[,1]-qda mean 1)'*inv(qda var 1)*
         (val chosen[,1]-qda mean 1)) >= lambda use) then do;
             Perfect Class Counter = Perfect Class Counter + 1;
             Missclass Matrix = Missclass Matrix//0;
        end;
        else do;
             Missclass Matrix = Missclass Matrix//1;
```



```
Perfect Class Counter = 0;
    end;
end;
if upcase(lambda method) = 'KNN' then do;
    if val chosen[,2] = lambda use then do;
        Perfect Class Counter = Perfect Class Counter + 1;
        Missclass Matrix = Missclass Matrix//0;
    end;
    else do;
        Missclass Matrix = Missclass Matrix//1;
        Perfect Class Counter = 0;
    end:
end;
if upcase(lambda method) = 'REG' then do;
    if (val chosen[,2] = 0 \& \max((1||val chosen[,1])*lambda use) =
    ((1||val chosen[,1])*lambda use)[,1]) |
    (\text{val chosen}[,2] = 1 \& \max((1||\text{val chosen}[,1])*|\text{lambda use}) =
    ((1||val chosen[,1])*lambda use)[,2]) then do;
        Perfect Class Counter = Perfect Class Counter + 1;
        Missclass Matrix = Missclass Matrix//0;
    end;
    else do;
        Missclass Matrix = Missclass Matrix//1;
        Perfect Class Counter = 0;
    end;
end;
if i3 = 1 then Missclass Matrix = Missclass Matrix[2,];
Q = Missclass Matrix[,1];
****** Stopping Criteria *******;
accept ind = 0;
if strip(upcase(StopRule)) = 'OLD' then do;
    pie i = J(i3,1,0);
    do i4 = 1 to i3;
        pie i[i4,1] = (1/i4)*(Q[1:i4,])*J(i4,1,1);
    end;
    Kappa N = (1/i3)^*((pie\ i\#(1-pie\ i))^*J(nrow(pie\ i),1,1));
    param1 = inv(i3)*(Q[1:i3]^*J(i3,1,1));
```



```
if param1 < epsilon && Kappa N > 0 && param1 > 0 then do;
        crit1 = ( (probit(1-alpha)*kappa_n)/(epsilon - param1) )**2;
        if i3 >= crit1 \mid perfect \ class \ Counter >= N \ Zero
        then accept ind = 1;
    end;
    else do;
        if perfect\_class\_Counter >= N\_Zero then
        accept ind = 1;
    end;
end;
/****************** New Rules *************/
if strip(upcase(StopRule)) = 'NEW' then do;
    if alpha = 0.1 then do;
        if h = 0.1 then do;
             a = 4;
                       gamma = 0.0754;
        end;
        if h = 0.05 then do;
             a = 4;
                       gamma = 0.0859;
        end;
        if h = 0.03 then do;
             a = 6;
                       gamma = 0.0916;
        end;
        if h = 0.02 then do;
             a = 6;
                       gamma = 0.0945;
        end;
        if h = 0.01 then do;
                       gamma = 0.0972;
             a = 6;
        end;
    end;
    if alpha = 0.05 then do;
        if h = 0.1 then do;
             a = 4;
                       gamma = 0.0356;
        end;
        if h = 0.05 then do;
             a = 6;
                       gamma = 0.0433;
        end:
        if h = 0.03 then do;
```



```
a = 6;
                           gamma = 0.0455;
          end;
          if h = 0.02 then do;
               a = 8;
                           gamma = 0.0472;
          end;
          if h = 0.01 then do;
               a = 10;
                            gamma = 0.0487;
          end;
     end;
     if alpha = 0.01 then do;
          if h = 0.1 then do;
               a = 6;
                           gamma = 0.0068;
          end;
          if h = 0.05 then do;
               a = 8;
                           gamma = 0.0083;
          end;
          if h = 0.03 then do;
               a = 12;
                            gamma = 0.0092;
          end;
          if h = 0.02 then do;
               a = 14;
                            gamma = 0.0095;
          end;
          if h = 0.01 then do;
               a = 14;
                            gamma = 0.0097;
          end:
     end;
                 = (Q[+,1])/(nrow(Q));
     p hat adj = (Q[+,1] + a)/(nrow(Q) + 2*a);
     interval upper = p hat + probit(1 - gamma/2)*
     \operatorname{sqrt}(p \text{ hat } \operatorname{adj}^*(1 - p \text{ hat } \operatorname{adj})/\operatorname{nrow}(Q));
     interval lower = p hat - probit(1 - gamma/2)*
     \operatorname{sqrt}(p \text{ hat } \operatorname{adj}^*(1 - p \text{ hat } \operatorname{adj})/\operatorname{nrow}(Q));
     if interval lower >= (p hat - h) & interval lower <= (p hat + h) &
     interval upper >= (p hat - h) & interval upper <= (p hat + h)
     then accept_ind = 1;
end;
/****** Calculate Misclassification Rate ******/
if accept_ind = 1 then do;
```



```
if strip(upcase(lambda method)) = 'LDA' then do;
        call Error calc lda(lambda use,missclass rate,mu1,mu2,sig1,sig2,
                             10000, sample sz1, sample sz2);
    end;
    if upcase(lambda method) = 'QDA' then do;
        call Error calc qda(lambda use,missclass rate,mu1,mu2,sig1,sig2,
                             10000,sample sz1,sample sz2,qda mean 0,
                             qda mean 1,qda var 0,qda var 1);
    end;
    if upcase(lambda method) = 'KNN' then do;
        call Error calc knn(sample,KNN Number,missclass rate,mu1,mu2,
                             sig1,sig2,10000,sample sz1,sample sz2);
    end;
    if upcase(lambda method) = 'REG' then do;
        call Error calc reg(lambda use,missclass rate,mu1,mu2,sig1,sig2,
                             10000, sample sz1, sample sz2);
    end;
    call Error calc theoret(sample sz1,sample sz2,mu1,
                             mu2,sig1,sig2,Bayes Error);
    Two Normal Out M = Two Normal Out M//
                             (mu1||mu2||eps||alpha||h||i3||
    missclass rate||Bayes_Error);
    i3 = \max \text{ Sample};
end;
else if accept ind = 0 \& i3 = \max sample then do;
    if upcase(lambda method) = 'LDA' then do;
        call Error calc lda(lambda use,missclass rate,mu1,mu2,sig1,
                             sig2,10000,sample sz1,sample sz2);
    end;
    if upcase(lambda method) = 'QDA' then do;
        call Error calc qda(lambda use,missclass rate,mu1,mu2,sig1,
                             sig2,10000,sample sz1,sample sz2,
                             qda mean 0,qda mean 1,
                             qda var 0, qda var 1);
    end;
    if upcase(lambda method) = 'KNN' then do;
        call Error calc knn(sample,KNN Number,missclass rate,mu1,mu2,
                             sig1,sig2,10000,sample sz1,sample sz2);
    end;
```



```
if upcase(lambda method) = 'REG' then do;
                call Error calc reg(lambda use,missclass rate,mu1,mu2,sig1,sig2,
                                     10000, sample sz1, sample sz2);
            end;
            call Error calc theoret(sample sz1,sample sz2,mu1,mu2,
                                     sig1,sig2,Bayes Error);
            Two Normal Out M = Two Normal Out M//
                                     (mu1||mu2||eps||alpha||h||i3||
            missclass rate||Bayes Error);
        end;
        ****** Reclassifying Lambda - LDA *******;
        if accept ind = 0 \& i3 < max sample then do;
            lambda use in = sample;
            if upcase(lambda method) = 'LDA' then do;
                call lambda calc LDA(lambda use in,lambda use);
            end;
            if upcase(lambda method) = 'QDA' then do;
                call lambda calc QDA(lambda use in,lambda use,qda mean 0,
                                         qda mean 1,qda var 0,qda var 1);
            end;
            if upcase(lambda method) = 'REG' then do;
                call lambda calc REG(lambda use in,lambda use);
            end;
        end;
    end;
end:
varnames = 'mu1'||'mu2'||'eps'||'alpha'||'h'||'sequential steps'||
            'missclass rate'||'Bayes Error';
create Two Normal Out D from Two Normal Out M [colname = varnames];
append from Two Normal Out M;
finish LDA two normal distributions;
******* Calculating lambda practically - LDA ********;
start lambda calc LDA(input matrix,output matrix);
    mean\_matrix = input\_matrix[loc(input\_matrix[,ncol(input\_matrix)] = 0),1][:]||
                    input matrix[loc(input matrix[,ncol(input matrix)] = 1),1][:];
    var matrix = (input matrix[loc(input matrix[,ncol(input matrix)] = 0),1] -
                mean matrix[,1])[\#\#,] +
                (input matrix[loc(input matrix[,ncol(input matrix)] = 1),1]
```



```
- mean matrix[,2])[\#\#,];
    var matrix = var matrix/nrow(input matrix - 2);
    var matrix = var matrix||var matrix;
    output matrix = (\log(\text{input matrix}[+,2]/(\text{nrow}(\text{input matrix})-\text{input matrix}[+,2]))
    + ((\text{mean matrix}[1,1]^{**2})/(\text{var matrix}[1,1]) - (\text{mean matrix}[1,2]^{**2})/
    (\text{var matrix}[1,2])/2)/(\text{mean matrix}[1,1]/
    var matrix[1,1] - mean matrix[1,2]/var matrix[1,2];
finish lambda calc LDA;
******* Calculating lambda practically - QDA ********;
start lambda calc QDA(input matrix,output matrix,mean matrix 0,
                          mean matrix 1, var matrix 0, var matrix 1);
         qda train 0 = \text{input matrix}[\text{loc(input matrix}[,\text{ncol(input matrix})] = 0),];
         qda train 1 = input matrix[loc(input matrix[,ncol(input matrix)] = 1),];
         mean matrix 0 = \text{qda} train 0[:,1:(\text{ncol}(\text{qda} \text{ train } 0)-1)];
         mean matrix 1 = qda train 1[:,1:(ncol(qda train 1)-1)];
         var matrix 0 = (qda train 0, 1:(ncol(qda train 0)-1)]-mean matrix 0)
                          (qda train 0,1:(ncol(qda train 0)-1)]-mean matrix 0)/
                          (nrow(qda train 0)-1);
         var matrix 1 = (qda train 1[,1:(ncol(qda train 1)-1)]-mean matrix 1)
                          (qda train 1,1:(ncol(qda train 1)-1)]-mean matrix 1)/
                          (nrow(qda train 1)-1);
         output matrix = \log(nrow(qda train 0)/nrow(qda train 1)) -
                              0.5*\log(\det(\text{var matrix }0)) +
                              0.5*\log(\det(\text{var matrix }1));
finish lambda calc QDA;
******* Calculating lambda practically - Regression ********;
start lambda calc REG(input matrix,output matrix);
        X Matrix = J(nrow(input matrix),1,1)||input matrix[,1];
         Y Matrix = (1-input matrix[,2])||input matrix[,2];
         output matrix = (inv(X Matrix'*X Matrix))*X Matrix'*Y Matrix;
finish lambda calc REG;
******* Calculating lambda practically - KNN *********;
start lambda calc KNN(input matrix,KNN,Output value);
        KNN sample = input matrix[1:nrow(input matrix)-1,]]
                          abs(input matrix[1:nrow(input matrix)-1,]-
                          input matrix[nrow(input matrix),1]);
        ndx = 0;
```



```
call sortndx(ndx,KNN sample,3,);
        new index = ndx[1:KNN,];
        KNN Sample KNN = J(1,ncol(KNN Sample),987);
        do knn cnt = 1 to KNN;
            Knn val idx = new index[knn cnt, 1];
            KNN Sample KNN = KNN Sample KNN//
                                    KNN Sample[Knn val idx,];
        end;
        KNN Sample KNN = KNN Sample KNN[2:nrow(KNN Sample KNN),];
        if (KNN Sample KNN[,2][+])/KNN < 0.5 then Output Value = 0;
        else Output Value = 1;
finish lambda calc KNN;
******* Calculating error LDA ********;
start Error calc lda(input val,output val,mean val1,mean val2,var val1,
                    var val2, holdout sample size, sample1, sample2);
    output val = 0;
    rat = sample1/(sample1 + sample2);
    output val = ncol(loc(randnormal(holdout sample size*
                    rat,mean val1,var val1) > input val));
    output val = output val + ncol(loc(randnormal(holdout sample size*)
                                (1-rat), mean val2, var val2) \leq input val);
    output val = output val/holdout sample size;
finish Error calc lda;
start Error calc knn(training, KNN, output val, mean val1, mean val2, var val1,
                var val2, holdout sample size, sample1, sample2);
    output val = 0;
    rat = sample1/(sample1 + sample2);
    input matrix = (randnormal(holdout sample size*rat,mean val1,var val1)
                    ||J(holdout sample size*rat,1,0))//
                    (randnormal(holdout sample size*(1-rat),mean val2,var val2)
                    ||J(holdout sample size*(1-rat),1,1));
    do iii = 1 to nrow(input matrix);
        value = ((training[,1:ncol(training)-1]-
                input matrix[iii,1:ncol(input matrix)-1])##2)
                *J(ncol(input matrix)-1,1,1);
        KNN sample = training||value;
        ndx = 0;
```



```
call sortndx(ndx,KNN sample,ncol(KNN sample),);
        new index = ndx[1:KNN,];
        KNN Sample KNN = J(1,ncol(KNN Sample),9876);
        do knn cnt = 1 to KNN;
            Knn val idx = new index[knn cnt, 1];
            KNN Sample KNN = KNN Sample KNN//
                                     KNN Sample[Knn val idx,];
        end;
        KNN Sample KNN = KNN Sample KNN[2:nrow(KNN Sample KNN)];
        if (KNN Sample KNN, \frac{1}{1}, \frac{1}{1})/KNN < 0.5
        then knn class = 0;
        else knn class = 1;
        if knn class ^= input matrix[iii,ncol(training)] then
        output val = output val + 1;
    end:
    output val = output val/nrow(input matrix);
finish Error calc knn;
******* Calculating error QDA ********;
start Error calc qda(input val,output val,mean val1,mean val2,var val1,var val2,
                         holdout sample size, sample 1, sample 2, mean matrix 0,
                         mean matrix 1, var matrix 0, var matrix 1);
    rat = sample1/(sample1 + sample2);
    x0 = \text{randnormal(holdout sample size*rat,mean val1,var val1)};
    x1 = \text{randnormal(holdout sample size}^*(1-\text{rat}), \text{mean val2, var val2)};
    x0 = 0.5*((x0\text{-mean matrix }0)\#\text{inv}(\text{var matrix }0)\#(x0\text{-mean matrix }0)
        (x0-mean matrix 1)\#inv(var matrix 1)\#(x0-mean matrix 1));
    x1 = 0.5*((x1-mean matrix 0)\#inv(var matrix 0)\#(x1-mean matrix 0) -
        (x1-mean matrix 1)\#inv(var matrix 1)\#(x1-mean matrix 1));
    output val = (ncol(loc(x0 > input val)) + ncol(loc(x1 <= input val)))
                     /holdout sample size;
finish Error calc qda;
******* Calculating error Regression *********;
start Error calc reg(input val,output val,mean val1,mean val2,var val1,var val2,
                     holdout sample size, sample1, sample2);
    rat = sample1/(sample1 + sample2);
    x0 = \text{randnormal(holdout sample size*rat,mean val1,var val1)};
    x1 = randnormal(holdout sample size*(1-rat), mean val2, var val2);
    output val = 0;
```



```
do ii1 = 1 to nrow(x0);
         if \max((1||x0||i1,|))*input val) = ((1||x0||i1,|))*input val)[,2] then
                                             output val = output val + 1;
    end;
    do ii2 = 1 to nrow(x1);
         if \max((1||x1||i2,|))*input val) = ((1||x1||i2,|))*input val)[,1] then
                                             output val = output val + 1;
    end;
    output val = output val/holdout sample size;
finish Error calc reg;
******* Calculating error theoretically i.e. Bayes error ********;
start Error calc theoret(sampsize1,sampsize2,mean1,mean2,sigma1,sigma2,output val);
    rat = sampsize1/(sampsize1 + sampsize2);
    if sigma1 = sigma2 then do;
         sigma \ overall = (sigma1*(sampsize1 - 1) + sigma2*(sampsize2 - 1))/
                           (sampsize1 + sampsize2 - 2);
         lambda bayes = (\log(\text{sampsize1/sampsize2}) + 0.5*(\text{mean2*inv}(\text{sigma overall})*)
                               mean2 - mean1*inv(sigma overall)*mean1))/
                               (inv(sigma \ overall)*(mean2 - mean1));
         output val = rat*(1 - probnorm((lambda bayes - mean1)/sqrt(sigma1)))
                      +(1 - rat)*probnorm((lambda bayes - mean2)/
                      sqrt(sigma2));
    end;
    else do;
         lambda bayes1 = (2*(mean1/sigma1 - mean2/sigma2) +
                               sqrt(4*(mean1/sigma1 - mean2/sigma2)**2
                                -4*(1/sigma1 - 1/sigma2)*(-2*log(sampsize1/sampsize2)
                               + \log(\text{sigma1/sigma2}) + \text{mean1*mean1/sigma1} -
                               mean2*mean2/sigma2))) / (2*(1/sigma1 - 1/sigma2));
         lambda bayes2 = (2*(mean1/sigma1 - mean2/sigma2) -
                               sqrt(4*(mean1/sigma1 - mean2/sigma2)**2
                               - 4*(1/\text{sigma1} - 1/\text{sigma2})*(-2*\log(\text{sampsize1/sampsize2})
                               + \log(\text{sigma1/sigma2}) + \text{mean1*mean1/sigma1} -
                               mean2*mean2/sigma2))) / (2*(1/sigma1 - 1/sigma2));
         if lambda bayes1 > lambda bayes2 then lambda bayes = lambda bayes1;
         else lambda bayes = lambda bayes 2;
         output val = rat*(1 - probnorm((lambda bayes - mean1)/sqrt(sigma1)))
                      + (1 - rat)*probnorm((lambda bayes - mean2)/
```



```
sqrt(sigma2));
    end;
finish Error calc theoret;
call LDA two normal distributions (&StopRule., &sample sz1., &sample sz2., &mul.,
                                      &mu2.,&sig1.,&sig2.,&eps.,&alpha.,&h.,
                                      &repititions.,&max sample.,&lambda method.,
                                      &Nearest Neighbours., &two normal out m.);
                     *** Parameter order ****;
/*StopRule - NEW indicates proposed method, OLD indicates current methodology*/
/*sample sz1 = the number of observations to generate from sample1;*/
/*sample sz2 = the number of observations to generate from sample2;*/
/*mu1 = mean value for generating sample1 observations;*/
/*mu2 = mean value for generating sample2 observations;*/
/*sig1 = variance for generating sample1 observations;*/
/*sig2 = variance for generating sample2 observations;*/
/*eps = epsilon;*/
/*a = alpha significance level;*/
/*h = halfwidth of confidence interval for proposed approach*/
/*repititions = number of repititions that the recursive method should be iterated;*/
/*max sample = maximum number of trails allowed;*/
/*lambda method = LDA, QDA, KNN, REG variable to select whether lambda
is calculated using K-Nearest, LDA, QDA or Regression of Indicator Matrix*/
/*KNN Neighbours = K-Nearest Neighbours if LAMBDA METHOD = KNN*/
/*two normal out m = Output matrix for two normal distribution inputs*/
quit;
data null;
    delta = transtrn(input(\&mu2. - \&mu1.,\$12.),'.',(' '));
    epsname = transtrn(input(\&eps.,\$12.),'.',');
    call symput('delta',compress(delta));
    call symput('epsname',compress(epsname));
run;
proc means data = Two normal out d noprint;
var sequential steps missclass rate Bayes Error;
output out = output &delta. &epsname. metric (keep = mean missclass
std missclass min seq max seq mean seq std seq mean Bayes)
min = min seq min missclass min Bayes max = max seq max missclass
```



```
max Bayes mean = mean seq mean missclass mean Bayes std = std seq
                      std missclass std Bayes;
quit;
data output &delta. &epsname. metric;
set output &delta. &epsname. metric;
delta = transtrn("\&delta."," ",".");
{\it epsilon} = {\it transtrn}("\&epsname.", "\_", ".");
run;
%if %sysfunc(EXIST(final output)) ^= 1 %then %do;
data final output;
    set\ Output\_1\_0\_05\_metric;
run;
%end;
%else %do;
    data final output;
         set final output output &delta. &epsname. metric;
    run;
%end;
%mend determine sample size;
%macro all delta;
    \%do epsloop = \%sysevalf(0.05*100) \%to \%sysevalf(0.2*100) \%by \%sysevalf(0.05*100);
         \%let eps loop = \%sysevalf(&epsloop./100);
         \%loop(\%str(1, 1.3, 1.5, 2, 2.3, 2.5, 3, 4));
/*This is the list of all delta values you want to loop through*/
    %end;
%mend all delta;
%macro loop(values);
/* Count the number of values in the string */
%let count=%sysfunc(countw(&values,','));
/* Loop through the total number of values */
\%do i = 1 \%to &count;
%let delta loop=%gscan(&values,&i,%str(,));
    %determine sample size('OLD',5,5,0,&delta loop.,1,1,&eps loop.,0.05,0.1,1000
                                    ,90,'LDA',3,Output);
%end;
%mend;
```



****** Now running the program ******; %all_delta;