



UNIVERSITEIT VAN PRETORIA
UNIVERSITY OF PRETORIA
YUNIBESITHI YA PRETORIA

Cellular Automata as an Approximate Method in Structural Analysis

Title: Cellular Automata as a Generalized Method in Structural Analysis
by Michael P. Hindley
Author: M. P. Hindley

A dissertation submitted in partial fulfillment
of the requirements for the degree of

Master of Engineering

in the Department of Mechanical and Aeronautical Engineering,
University of Pretoria

November 2001

Master's dissertation, to meet the requirements of the Faculty of Mechanical and
Aeronautical Engineering. Supervisor:
Prof. Albert A. Groenwold

and does not yet have a clear-cut solution. In this study, the underlying mathematics of CA is explored to determine how the method can be applied to structural mechanics. It is shown that distributed computing devices such as cellular automata can be used to solve structural analysis problems. The underlying mathematics of the CA simulation runs through the symmetry factor, which is proportional to the number of nodes in the mesh.

The distributed computing device itself is constructed by purchasing 12 cheap Pentium 4 computers. In terms of CPU performance the constructed distributed computing device is not the best, but it is constructed with no hardware costs and no software costs. The software used in simulating the model is in the public domain, and a genetic algorithm is used to determine optimum rules for the CA.

Title: Cellular Automata as an Approximate Method in Structural Analysis

Author: Michael Philip Hindley

Supervisor: Prof. A.A. Groenwold

Department: Department of Mechanical Engineering

Degree: Master of Engineering

Keywords: Cellular automata, structural analysis, finite difference method, finite element method, boundary element method

This thesis deals with the mathematical idealization denoted cellular automata (CA) and the applicability of this method to structural mechanics. When using CA, all aspects such as space and time are discrete. This discrete nature of CA allows for ease of interaction with digital computers, while physical phenomena which are essentially discrete in nature can be simulated in a realistic way. The application of such a novel numerical method opens up new possibilities in structural analysis.

In this study, the fundamentals of CA are studied to determine how the parameters of the method are to be evaluated and applied to the established field of structural analysis. Attention is given to the underlying mathematics of structural mechanics, as well as approximate methods currently used in structural analysis, e.g. the finite element method (FEM) and the boundary element method (BEM).

For structural simulations performed with the CA implemented in this study, machine learning based on a genetic algorithm (GA) is used to determine optimum rules for the CA, using finite element, boundary element and analytical approximations as the basis for machine learning.

Rather unconventionally, symmetric problems in structural analysis are analyzed using asymmetric rules in the machine learning process, where the symmetry of the solution found is used as a quantitative indication of the quality of the solution. It is demonstrated that the quality of the asymmetric rules is superior to the quality of symmetric rules, even for those

problems that are symmetric in nature.

Finally, exploiting the inherent parallelism of CA, it is shown that distributed computing can greatly improve the efficiency of the CA simulation, even though the speed-up factor is not necessarily proportional to the number of sub lattices used.

The distributed computing device itself is constructed by combining 18 obsolete Pentium computers in a single cluster. In terms of CPU performance the constructed distributed computer is not state-of-the-art, but it is constructed with no hardware costs whatsoever. In addition, the software used in assembling the cluster is in the public domain, and is also available free of charge. Such a parallel configuration is also known as the poor man's computer. However, faster and more modern machines can simply be added to the existing cluster as and when they become available.

While CA are recent additions to the ‘tools’ used in structural analysis, increased use of CA as distributed computing becomes more widely available is envisaged, even though the CA rules are at this stage not transferable between different problems or even between meshes of varying refinement for a given problem.

en die regte. Daar word aangegetoond dat die kwaliteit van onkonvensionele reëls beter is as die kwaliteit van simmetriese reëls, selfs vir die probleme wat inherint simmetriek is.

Desalniettemin, doen gevorderlik te moek van die huidige parallelisme van die SO, word aangegeven dat voorgedane benaderings nie effektiwiteit van SO-berekenings kan verhoog, aangesien die berekeningspunte nie noodwendig evenredig aan die aantal onderverdelings in die struktuur is.

Opsomming

In hierdie verhandeling is die gebruik van die Sellulêre Outomata (SO) om te bestudeer hoe die numeriese idealisering van struktuurmeganika kan word. Die SO is 'n metode waarin alle fisiese parameters soos tyd en ruimte met diskrete waardes benader word. Die diskrete aard van SO laat eenvoudige interaksies met rekenaars toe, terwyl fisiese verskynsels wat hoofsaaklik diskreet van aard is, op 'n realistiese wyse benader kan word.

Titel: Sellulêre Outomata as 'n Benaderingsmetode in Struktuuranalise

Outeur: Michael Philip Hindley

Leier: Prof. A.A. Groenwold

Departement: Departement van Meganiese Ingenieurswese

Graad: Meester van Ingenieurswese

Sleutelwoorde: Sellulêre outomata, struktuuranalise, eindige verskil metode, eindige element metode, rand element metode

Hierdie verhandeling is gemoeid met die numeriese idealisering met die SO. Die SO is 'n metode waarin alle fisiese parameters soos tyd en ruimte met diskrete waardes benader word. Die diskrete aard van SO laat eenvoudige interaksies met rekenaars toe, terwyl fisiese verskynsels wat hoofsaaklik diskreet van aard is, op 'n realistiese wyse benader kan word. Die toepassing van SO in struktuuranalise laat uiteraard nuwe moontlikhede toe.

In hierdie studie word die fundamentele werking van die SO bestudeer om te bepaal hoe die parameters van die metode benader kan word, om dan ook toegepas te kan word op die gevestigde gebied van struktuuranalise. Aandag word verder ook gegee aan die onderliggende wiskundige begrippe van struktuurmeganika, asook benaderingsmetodes wat reeds gevestig is in struktuuranalise, soos byvoorbeeld die eindige element metode (EEM) en die rand element metode (REM).

In struktursimulasies met behulp van die SO wat ontwikkel is, word masjien-onderrig met behulp van 'n genetiese algoritme (GA) gebruik om die optimale reëls vir die SO te bepaal. Die basis vir die leerproses is eindige element modelle, rand element modelle, asook analitiese benaderings.

Simmetriese probleme in struktuuranalise word op 'n onkonvensionele manier geanaliseer met behulp van onsimmetriese reëls in die masjienonderrig proses, terwyl die simmetrie van die voor spelde oplossings gebruik word as 'n kwalitatiewe aanduiding van die gesiktheid

van die reëls. Daar word aangetoon dat die kwaliteit van onsimmetriese reëls beter is as die kwaliteit van simmetriese reëls, selfs vir die probleme wat inherent simmetries is.

Laastens, deur gebruik te maak van die inherente parallelisme van die SO, word aangetoon dat verspreide berekenings die effektiwiteit van SO-berekenings kan verhoog, alhoewel die versnellingsfaktor nie noodwendig eweredig aan die aantal onderverdelings in die struktuur is nie.

Die verspreide rekenaar is saamgestel deur 18 verouerde Pentium-rekenaars in 'n enkele berekeningsgroep saam te stel. In terme van SVE-prestasie is die verspreide rekenaar nie op die voorgrond van tegnologie nie, maar is saamgestel sonder enige hardware koste. Die sagteware wat gebruik is om die berekeningsgroep saam te stel is in die publieke domein, en is ook kosteloos beskikbaar. So 'n parallele rekenaar staan ook bekend as die "arm man se parallelleretekaar". Vinniger en beter rekenaars kan egter eenvoudig tot die berekeningsgroep toegevoeg word wanneer hulle beskikbaar is.

Terwyl SO 'n onlangse stuk 'gereedskap' is wat in struktuuranalise gebruik word, word verwag dat SO toenemend gebruik sal word soos verspreide berekenings meer algemeen beskikbaar raak, nieteenstaande die feit dat die reëls op hierdie stadium nie oordraagbaar is tussen verskillende probleme nie, en ook nie vir verskillende grade van maasverfyning vir 'n bepaalde probleem nie.

Acknowledgments

I would like to express my sincere gratitude towards the following persons:

- Prof. Albert A. Groenwold, my supervisor, for his guidance and support throughout this study.
- To both my parents for their support, and for granting me the opportunity to study. I would also like to thank them for their financial backing.
- To my fellow students for turning a hard working environment into a pleasurable social experience.
- To every person involved with development of GNU (GPL) software. All the work performed in this thesis, including programming, editing and writing of this thesis, was accomplished using free software granted under the GNU public license.

I would like to dedicate this thesis to Laura Vatta.

Introduction to cellular automata

2.1. General theory

2.1.1. Basic concepts

2.2. Formal definition

2.2.1. Neighborhood and local rule

2.2.2. Boundary conditions

2.2.3. Initialization of the automaton

2.2.4. Evolution of the automaton

2.2.4.1. One-dimensional

2.2.4.2. Two-dimensional

2.2.4.3. Three-dimensional

2.2.5. Cell state and function

2.8	Cell rule and neighborhood	15
2.9	Cellular automata classification	16
2.10	Summary of neighborhood possibilities	16
2.11	Partial differential equations, continuous systems and cellular automata	17

Contents

	2.12	Cellular automata in structural analysis	18
	2.13	Introduction	19
	2.14	2.13.1 CA parameters in structural analysis	20
	2.15	2.13.2 CA implementation	21
Abstract			ii
Opsomming			iv
Acknowledgments			vi
List of Figures			xiv
List of Tables			xv
List of Abbreviations			xvi
1	Introduction		1
1.1	Motivation	1	
1.2	Objectives	3	
1.3	Approach	4	
2	Introduction to cellular automata		5
2.1	Informal definition	5	
2.1.1	Simple example	6	
2.2	Formal definition	6	
2.3	Neighborhood definition and size in 2-D	7	
2.4	Boundary conditions	8	
2.5	Initial conditions	9	
2.6	Geometry	9	
2.6.1	One dimension	10	
2.6.2	Two dimensions	10	
2.6.3	Three dimensions	14	
2.7	Cell state and precision	14	

2.8	Cell rule	15
2.9	Cellular automata classification	16
2.10	CA internal representation possibilities	18
2.11	Partial differential equations, continuous systems and cellular automata	19
3	Cellular automata in structural analysis	22
3.1	Introduction	22
3.1.1	CA parameters in structural analysis	23
3.1.2	CA implementation	25
3.2	Problem formulation	25
3.2.1	Problem descriptions	25
3.2.2	Neighborhood descriptions	26
3.2.3	Analysis criteria	27
3.3	Determination of the optimum cell rule	30
3.3.1	Motivation	30
3.3.2	Cell rule comparison definition	31
3.4	Problem analysis and results	32
3.4.1	Extended neighborhood	32
3.4.2	Moore neighborhood	37
3.5	Cellular automata computational conclusions	52
4	Parallel processing implementation	53
4.1	Introduction	53
4.1.1	Parallel computing concepts	53
4.1.2	Technology	54
4.1.3	Classification of parallel machines	54
4.1.4	Interconnecting structures and graphs	55
4.1.5	Parallel computing models and complexity measures	55
4.2	Parallel virtual machine, linux xpvm	56
4.2.1	Linux	56
4.2.2	Parallel virtual machine	57
4.2.3	Xpvm	59
4.3	Parallelization of cellular automata	62
4.3.1	Parallelization method	62
4.3.2	Sequential sub-lattice update method	64
4.3.3	Parallel lattice computation	66

4.4	Parallelization of a genetic algorithm	70
4.4.1	Introduction	70
4.4.2	Implementation method	70
4.5	Computational conclusions	72
5	Concluding Remarks	73
5.1	Summary of contributions	73
5.2	Conclusions	74
5.3	Directions for future work	74
A	Established structural approximation methods	80
A.1	Governing equations	80
A.1.1	One dimension	82
A.1.2	Two dimensions	82
A.1.3	Mechanics of the boundary value problem	82
A.2	Finite difference method	86
A.2.1	Introduction	86
A.2.2	Methodology	86
A.2.3	Methods of successive approximations	89
A.2.4	Practicality for structural analysis	91
A.3	Finite element method	93
A.3.1	Introduction	93
A.3.2	Methodology	94
A.3.3	Implementation	101
A.4	Boundary element method	102
A.4.1	Introduction	102
A.4.2	Basic principles	103
A.4.3	Fundamental solution	105
A.4.4	Boundary integral formulation	106
A.4.5	Boundary element formulation	108
A.4.6	Implementation	109
A.5	Finite element method and boundary element method comparison	115
B	Numerical optimization	117
B.1	Optimization formulation	117
B.1.1	Mathematical definition	117

B.1.2	Solution methodology	117
B.2	Genetic algorithm	118
B.2.1	Introduction	118
B.2.2	Solution representation	118
B.2.3	Selection function	118
B.2.4	Genetic operators	120
B.2.5	Initialization function	121
B.2.6	Termination criteria	122
B.2.7	Objective function	122
C	Flow diagrams for selected programs	123
2.6	Mapping of the present neighbour to a solution approach	17
2.6	Mapping of the present neighbour to the update factor	18
2.7	Mapping of the present neighbour to a solution approach	19
2.8	Mapping of the present neighbour to the update factor	20
3.1	One-dimensional problems	23
3.2	One-dimensional dispersed local optimisation	24
3.3	Formulation of CA problem 1 problem 2	25
3.4	Formulation of CA problem 2 problem 1	26
3.5	Formulation of CA problem 3	27
3.6	Extended neighborhood local optimisation	28
3.7	Mean neighborhood local optimisation	29
3.8	Extended neighborhood local optimisation	30
3.9	Extended neighborhood KNN local optimisation	31
3.10	Extended neighborhood extended neighborhood local optimisation	32
3.11	Problem 1 FEM 4 x 8 stress plot	33
3.12	Problem 1 CA optimised 12 cell state stress plot	34
3.13	Problem 1 FEM 4 neighbours stress plot	35
3.14	Problem 1 CA optimised 1201 cell states stress plot	36
3.15	Problem 1 CA optimised 976 cell states stress plot	37
3.16	Problem 1 Extended FEM stress plot	38
3.17	Cell state accuracy threshold generation	39
3.18	Problem 1 FEM 10 x 10 stress plot	40
3.19	Problem 1 FEM 8 x 8 stress plot	41

3.20 Problem 1 CA optimized 32 cell states stress plot	39
3.21 Problem 1 CA optimized 512 cell states stress plot	39
3.22 Problem 1 CA optimized 1024 cell states stress plot	39
3.23 Problem 1 CA optimized 32768 cell states stress plot	39

List of Figures

2.1 Various CA neighborhood definitions	8
2.2 Shear mapping of the hexagonal lattice to the square lattice	11
2.3 Mapping of the nearest neighbor in the shear mapping	11
2.4 Shift mapping of the hexagonal lattice to the square lattice	11
2.5 Mapping of the nearest neighbors in the shift mapping	12
2.6 Mapping of the triangular lattice to the square lattice	13
2.7 Mapping of the nearest neighbors in the triangular mapping	13
2.8 Mapping of two triangular cells into one square cell	13
3.1 One-dimensional bar problem	24
3.2 One-dimensional computational cost comparison	24
3.3 Formulation of CA problem 1 investigated	26
3.4 Formulation of CA problem 2 investigated	26
3.5 Formulation of CA problem 3 investigated	26
3.6 Extended neighborhood description	27
3.7 Moore neighborhood description	27
3.8 Extended neighborhood RMS error comparison	34
3.9 Extended neighborhood RMS error closer comparison	34
3.10 Extended neighborhood computational cost comparison	35
3.11 Problem 1 FEM 8×8 stress plot	36
3.12 Problem 1 CA optimized 32 cell states stress plot	36
3.13 Problem 1 FDM 4 neighbors stress plot	36
3.14 Problem 1 CA optimized 1024 cell states stress plot	36
3.15 Problem 1 CA optimized 32768 cell states stress plot	36
3.16 Problem 1 Extended FDM stress plot	36
3.17 Cell state accuracy round off occurrence	38
3.18 Problem 1 FEM 16×16 stress plot	39
3.19 Problem 1 FDM 4 neighbors stress plot	39

3.20 Problem 1 CA optimized 32 cell states stress plot	39
3.21 Problem 1 CA optimized 256 cell states stress plot	39
3.22 Problem 1 CA optimized 256 cell states stress plot	39
3.23 Problem 1 CA optimized 32768 cell states stress plot	39
3.24 Problem 2 BEM 16×16 stress plot	41
3.25 Problem 2 FDM 4 neighbors stress plot	41
3.26 Problem 2 CA optimized 32 cell states stress plot	41
3.27 Problem 2 CA optimized 256 cell states stress plot	41
3.28 Problem 2 CA optimized 2048 cell states stress plot	41
3.29 Problem 2 CA optimized 32768 cell states stress plot	41
3.30 Problem 2 BEM 8×8 stress plot	42
3.31 Problem 2 BEM 16×16 stress plot	42
3.32 Problem 2 FEM 8×8 stress plot	42
3.33 Problem 2 FEM 16×16 stress plot	42
3.34 Problem 3 FEM 8×8 stress plot	44
3.35 Problem 3 CA optimized 32 cell states stress plot	44
3.36 Problem 3 CA optimized 64 cell states stress plot	44
3.37 Problem 3 CA optimized 512 cell states stress plot	44
3.38 Problem 3 CA optimized 1024 cell states stress plot	44
3.39 Problem 3 CA optimized 32768 cell states stress plot	44
3.40 Problem 3 FEM 16×16 stress plot	46
3.41 Problem 3 CA optimized 32 cell states stress plot	46
3.42 Problem 3 CA optimized 128 cell states stress plot	46
3.43 Problem 3 CA optimized 512 cell states stress plot	46
3.44 Problem 3 CA optimized 2048 cell states stress plot	46
3.45 Problem 3 CA optimized 32768 cell states stress plot	46
3.46 Problem 3 FEM 16×16 stress plot	48
3.47 Problem 3 CA optimized 64 cell states stress plot	48
3.48 Problem 3 CA optimized 128 cell states stress plot	48
3.49 Problem 3 CA optimized 512 cell states stress plot	48
3.50 Problem 3 CA optimized 8192 cell states stress plot	48
3.51 Problem 3 CA optimized 32768 cell states stress plot	48
3.52 Asymmetric neighborhood problem description	49
3.53 Asymmetric rule orientation for Problem 3 FEM 8×8 1024 cell states	50
3.54 Asymmetric rule one problem 3 stress plot, FEM 8×8 1024 cell states	51

3.55 Asymmetric rule two problem 3 stress plot, FEM 8×8 1024 cell states	51
3.56 Asymmetric rule three problem 3 stress plot, FEM 8×8 1024 cell states	51
3.57 Asymmetric rule four problem 3 stress plot, FEM 8×8 1024 cell states	51
3.58 Asymmetric rule five problem 3 stress plot, FEM 8×8 1024 cell states	51
3.59 Asymmetric rule six problem 3 stress plot, FEM 8×8 1024 cell states	51
4.1 Photo of the 18 node Linux “Souper” Computer, named GOH, constructed in this study	60
4.2 XPVM screen shot	61
4.3 Original square lattice	63
4.4 Four sub-lattice split	63
4.5 Nine sub-lattice split	63
4.6 Typical convergence for four sub-lattices	70
4.7 GA calculation with nine population members	71
A.1 The main coordinates, displacements, stresses and tractions in three dimensions	81
A.2 One-dimensional bar problem	83
A.3 Equilibrium of an infinitesimal bar element	83
A.4 Finite difference two-dimensional grid	87
A.5 Finite difference torsion bar example cross section	88
A.6 Typical ritz function used in the analysis of one-dimensional bar problem . .	94
A.7 Linear combination of the ritz functions	94
A.8 Simple bar FEM mesh	95
A.9 Simple membrane FEM element	97
A.10 FEM element patch test	102
A.11 The fundamental solution in two dimensions BEM	107
A.12 Constant element solution BEM	110
A.13 Corner point	110
A.14 Simple boundary element problem	112
A.15 Applying boundary conditions	112
A.16 Applying complex load	113
A.17 Constant deformation of a simple geometry	113
A.18 Constant deformation of a refined mesh	114
C.1 Boundary cell calculation	124
C.2 CA simulation main	125
C.3 Stress contour plot	126

C.4	Genetic algorithm	127
C.5	CA parallel implementation number one	128
C.6	CA parallel implementation number two	129
C.7	CA parallel implementation number three	130
C.8	GA parallel implementation	131

2.1	A simple one-dimensional, two state, cellular automaton	1
2.2	Number of possible combinations	1
2.3	Parallel update	2
2.4	Neighborhood size difference for different rules	2
2.5	Internal Computer Representation for a parallel CA which generates a dual lattice	2

3.1	Displacement error comparison of FEM and CA in two dimensions (2D)	3
3.2	Optimized rules for 8 x 8 square Mooney-Rivlin problem	3
3.3	Optimized rules for 16 x 16 square Mooney-Rivlin problem	3
3.4	Optimized rules for 8 x 8 square Mooney-Rivlin problem	3
3.5	Optimized rules for 16 x 16 square Mooney-Rivlin problem	3
3.6	Optimized rules for 8 x 8 square Mooney-Rivlin problem	3
3.7	Optimized rules for 16 x 16 square Mooney-Rivlin problem	3
3.8	Optimized rules for 8 x 8 FEM problem	3

3.9	Segregated block update problem with 5778 nodes for a 16 x 16 square Mooney-Rivlin problem	3
3.10	Local convergence speed improvement for a 16 x 16 square Mooney-Rivlin problem	3
3.11	Parallel static uniaxial performance of CA and FEM	3

A.1	Established neighborhood difference comparison and parallelization	1
A.2	Displacements calculated by FEM and CA for the same mesh	1
A.3	Stresses Calculated by FEM, single and coarse mesh	1
A.4	External stresses (FEM)	1
A.5	External stresses refined mesh (FEM)	1
A.6	Internal displacements refined mesh (FEM)	1

List of Tables

2.1	A simple one-dimensional, two state, cellular automata	6
2.2	Number of possible combinations	14
2.3	Possible precision	15
2.4	Neighborhood size difference for difference mesh types	18
2.5	Internal Computer Representation for a complicated CA mapped to a square computational lattice	19
3.1	Displacement error comparison of BEM and CA in comparison to FEM	28
3.2	Optimized rules for 8×8 mesh on Extended neighborhood FEM problem 1 .	33
3.3	Optimized rules for 16×16 mesh on Moore neighborhood FEM problem 1 .	37
3.4	Optimized rules for 16×16 mesh on Moore neighborhood BEM problem 2 .	40
3.5	Optimized rules for 8×8 mesh on Moore neighborhood FEM problem 3 .	43
3.6	Optimized rules for 16×16 mesh on Moore neighborhood FEM Problem 3 .	45
3.7	Optimized rules for 16×16 mesh for more cell states on a Moore neighborhood FEM Problem 3	47
3.8	Optimized rules 8×8 FEM problem 3 (asymmetric)	49
4.1	Sequential block update method with 32768 cell states and finite difference rule(N, Number of sub-lattices)	65
4.2	Local convergence speed improvement for 4 sub-lattices	66
4.3	Parallel computing speed performance of CA with PVM	69
A.1	Established finite difference computational molecules	92
A.2	Displacements calculated by FEM (single membrane element)	101
A.3	Stresses Calculated by FEM (single membrane element)	102
A.4	Internal stresses (BEM)	114
A.5	Internal stresses refined mesh (BEM)	115
A.6	Internal displacements refined mesh (BEM)	115

List of Abbreviations

1-D	One dimensional
2-D	Two dimensional
3-D	Three dimensional
BEM	Boundary element method
CA	Cellular automata
CPU	Central processing unit
CSE	Computational science and engineering
FDM	Finite difference method
FEM	Finite element method
GA	Genetic algorithm
IPC	Inter-process communications
MIMD	Multiple instruction multiple data
MPP	Massive parallel processors
NFS	Networked file system
NOW	Network of workstations
OS	Operating system
PDE	Partial differential equation
PVM	Parallel virtual machine
RISC	Reduced instruction set computing
RMS	Root mean square
SIMD	Single instruction multiple data
VLSI	Very large scale integration