

ADDENDUM A

INTRODUCTION TO ADDENDUM A

This document contains the input data used in the Universal SCF determination in Methodology II, (Chapter 4), and the input data and MATLAB simulation program used in Methodology III, (Chapter 6). The document also defines the various parameters used in these practical sessions.

UNIVERSAL SCF Determination Data

The input data used in Methodology I, is available in Chapter 3 of the dissertation document.

Calculation of Universal SCF Data for Methodology II

This consisted of Probability of Error, P_b , and K the number of users. Equation (4-26) in Chapter 4, was employed in these calculations. The data in Tables 1-1 to 1-5, was used to plot the Probability of Error versus K graphs of Figures 4-1 to 4-11, in Chapter 4 of the dissertation document.

K users	Pb at SCF=0.47	Pb at SCF=0.48	Pb at SCF=0.49	Pb at SCF=0.50	Pb at SCF=0.51	Pb at SCF=0.52	Pb at SCF=0.53	Pb at SCF=0.54
5	4.94E-04	4.71E-04	4.50E-04	4.30E-04	4.12E-04	3.95E-04	3.80E-04	3.66E-04
10	3.86E-03	3.72E-03	3.60E-03	3.50E-03	3.40E-03	3.33E-03	3.26E-03	3.21E-03
15	1.43E-02	1.43E-02	1.43E-02	1.44E-02	1.45E-02	1.47E-02	1.51E-02	1.55E-02
20	3.83E-02	3.94E-02	4.60E-02	4.25E-02	4.44E-02	4.67E-02	4.92E-02	5.21E-02
25	8.38E-02	8.84E-02	9.35E-02	9.93E-02	1.06E-01	1.12E-01	1.20E-01	1.28E-01
30	1.61E-01	1.65E-01	1.75E-01	1.86E-01	1.98E-01	2.10E-01	2.32E-01	2.35E-01

Table A-1: Calculated Data for K and P_b , (range SCF =0.47 to 0.54)

K users	Pb at SCF=0.55	Pb at SCF=0.56	Pb at SCF=0.57	Pb at SCF=0.58	Pb at SCF=0.59	Pb at SCF=0.60	Pb at SCF=0.61	Pb at SCF=0.62
5	3.53E-04	3.40E-04	3.29E-04	3.19E-04	3.10E-04	3.02E-04	2.95E-04	2.88E-04
10	3.17E-03	3.15E-03	3.14E-03	3.14E-03	3.16E-03	3.19E-03	3.24E-03	3.30E-03
15	1.59E-02	1.65E-02	1.72E-02	1.80E-02	1.89E-02	2.00E-02	2.12E-02	2.25E-02
20	5.54E-02	5.90E-02	6.30E-02	6.74E-02	7.23E-02	7.76E-02	8.33E-02	8.94E-02
25	1.37E-01	1.46E-01	1.56E-01	1.66E-01	1.76E-01	1.87E-01	1.99E-01	2.10E-01
30	2.48E-01	2.61E-01	2.74E-01	2.87E-01	2.99E-01	3.12E-01	3.24E-01	3.35E-01

Table A-2: Calculated Data for K and P_b , (range SCF =0.55 to 0.62)

K users	Pb at SCF=0.63	Pb at SCF=0.64	Pb at SCF=0.65	Pb at SCF=0.66	Pb at SCF=0.67	Pb at SCF=0.68	Pb at SCF=0.69	Pb at SCF=0.70
5	2.83E-04	2.78E-04	2.74E-04	2.70E-04	2.68E-04	2.66E-04	2.64E-04	2.64E-04
10	3.37E-03	3.47E-03	3.58E-03	3.72E-03	3.87E-03	4.05E-03	4.25E-03	4.49E-03
15	2.41E-02	2.57E-02	2.76E-02	2.97E-02	3.20E-02	3.60E-02	3.73E-02	4.03E-02
20	9.60E-02	1.03E-01	1.10E-01	1.18E-01	1.26E-01	1.35E-01	1.44E-01	1.53E-01
25	2.22E-01	2.33E-01	2.45E-01	2.56E-01	2.68E-01	2.79E-01	2.91E-01	3.01E-01
30	3.47E-01	3.58E-01	3.68E-01	3.78E-01	3.87E-01	3.96E-01	4.04E-01	4.12E-01

Table A-3: Calculated Data for K and P_b , (range SCF =0.63 to 0.70)

K users	Pb at SCF=0.71	Pb at SCF=0.72	Pb at SCF=0.73	Pb at SCF=0.74	Pb at SCF=0.75	Pb at SCF=0.76	Pb at SCF=0.77	Pb at SCF=0.78
5	2.64E-04	2.65E-04	2.66E-04	2.69E-04	2.72E-04	2.76E-04	2.80E-04	2.86E-04
10	4.75E-03	5.04E-03	5.37E-03	5.73E-03	6.14E-03	6.60E-03	7.10E-03	7.66E-03
15	4.35E-02	4.70E-02	5.08E-02	5.49E-02	5.92E-02	6.39E-02	6.88E-02	7.40E-02
20	1.62E-01	1.72E-01	1.81E-01	1.91E-01	2.01E-01	2.11E-01	2.21E-01	2.31E-01
25	3.12E-01	3.23E-01	3.33E-01	3.42E-01	3.52E-01	3.61E-01	3.69E-01	3.77E-01
30	4.20E-01	4.27E-01	4.33E-01	4.39E-01	4.44E-01	4.50E-01	4.54E-01	4.59E-01

Table A-4: Calculated Data for K and P_b , (range SCF =0.71 to 0.78)

K users	Pb at SCF=0.79	Pb at SCF=0.80	Pb at SCF=0.81	Pb at SCF=0.82	Pb at SCF=0.83	Pb at SCF=0.84	Pb at SCF=0.85	Pb at SCF=0.86
5	2.92E-04	3.00E-04	3.08E-04	3.18E-04	3.28E-04	3.40E-04	3.53E-04	3.68E-04
10	8.28E-03	8.96E-03	9.70E-03	1.05E-02	1.14E-02	1.24E-02	1.35E-02	1.46E-02
15	7.94E-02	8.51E-02	9.11E-02	9.74E-02	1.04E-01	1.10E-01	1.17E-01	1.24E-01
20	2.41E-01	2.55E-01	2.60E-01	2.70E-01	2.79E-01	2.89E-01	2.98E-01	3.06E-01
25	3.85E-01	3.93E-01	4.00E-01	4.07E-01	4.13E-01	4.19E-01	4.25E-01	4.30E-01
30	4.63E-01	4.67E-01	4.70E-01	4.73E-01	4.76E-01	4.79E-01	4.81E-01	4.84E-01

Table A-5: Calculated Data for K and P_b , (range SCF =0.79 to 0.86)

The values of spreading gain $N = 31$, and $E_B/N_O = 10dB$, were used in the calculations. The graphs were plotted in Microsoft Excel.

P^3MUD (PPPMUD) MATLAB Program

Overview of P^3MUD MATLAB Program Structure

The program to simulate the P^3MUD outputs was originally obtained from the shareware MATLAB software employed by Sridhar Rajagopal *et al.*[7], for determining the CDMA/WCDMA performances at Rice University, Houston, Texas. Thus, the P^3MUD program uses the structures of the shareware program as a base to build on, and the program modules that have been developed are similar in some instances to the original modules, but different in others as seen in figure A-1, and in the comparison of Table A-6.

ITEM	PPPMUD	Conventional PIC MUD	Comment
1	tester.m		For PPPMUD, tests validity of input data functions in Information4.m
2	Information4.m		For PPPMUD, main executable program, controlling input and output data and GUI activation. It also contains the Conventional Matched Filter Receiver program code and the Single-user optimum detector code for the respective error bound graphs.
3	Optimum_detect.m	detect_pipe.m	For Conventional MUD, main executable program, but for PPPMUD is a function where code syntax has been optimised. Program generates channel estimate parameters for the randomly selected users' data which is spread before transmission over channel. Program performs Maximum Likelihood channel estimation process and outputs used in Matched Filter & Multistage PIC Detector stages. Resultant Output is detected bits and error count from detection process, as well as graphical BER vs SNR, with additional BER vs K (simultaneous users) for PPPMUD
4	gendata.m	gendata.m	Function for generating randomly selected users and data and spreading codes, channel estimate parameters to be used in detection process
5	genseq.m	genseq.m	function to generate spreading code sequences
6	splitAmatrix.m	SplitAmatrix.m	Function to assist in manipulating matrices efficiently in detection process calculations
7	SCF.m		For PPPMUD, function activates the soft cancellation factor compensator mechanism

Table A-6: Comparison of P^3 MUD and Conventional PIC MUD program structures

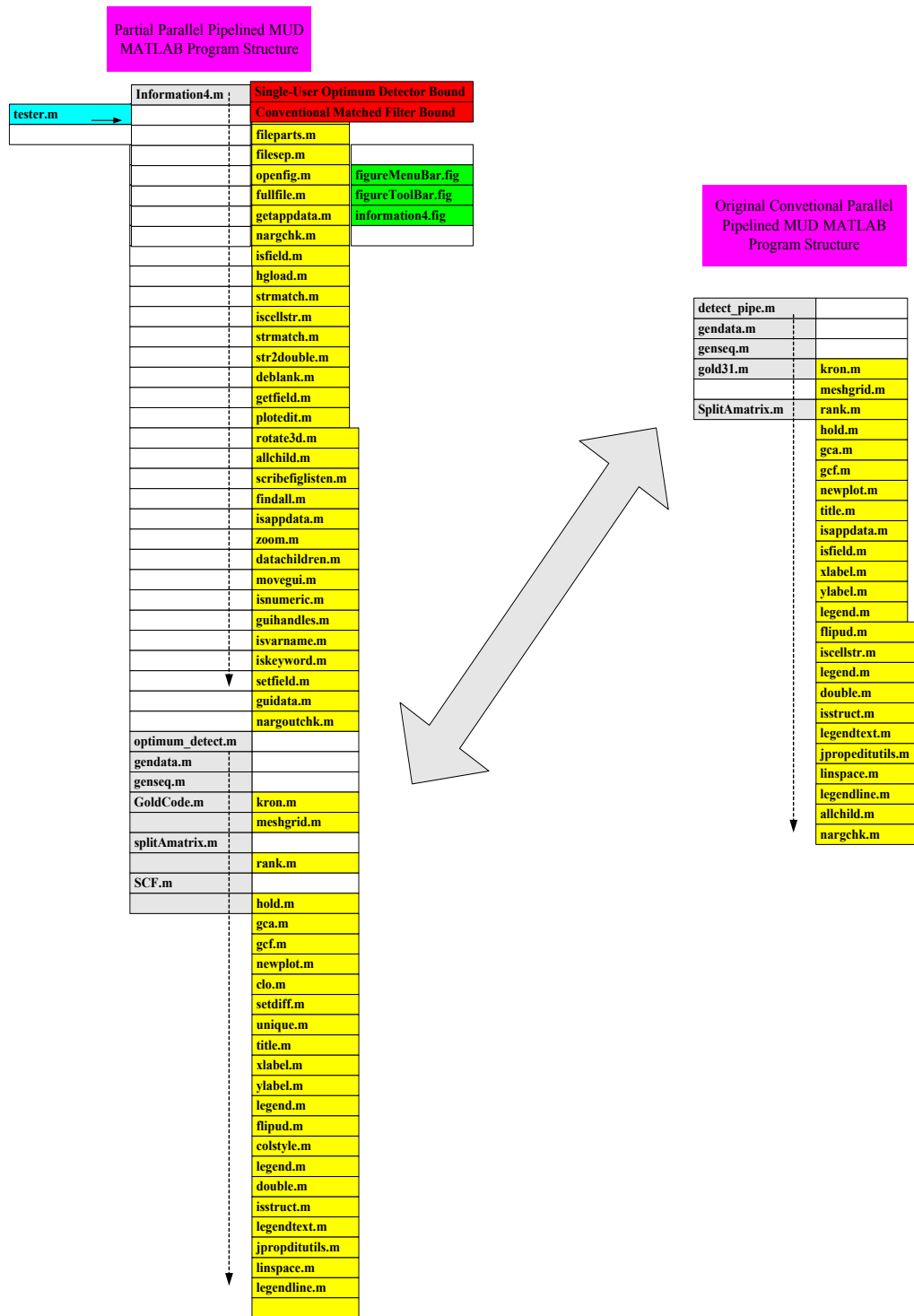


Figure A-1: Overview of P^3MUD MATLAB Program Structure

P³MUD Program Description

The program basically simulates a CDMA system in MATLAB, with the process consisting of the transmission of randomly selected user data bits over a channel, and detection of those bits at the receiver side by comparing the preamble and transmitted bits. The number of errors is counted and forms the input to the BER output graphs, which is a measure of the efficiency of the detection scheme. The standard optimum detection graphs are also included as a comparison measure.

MATLAB Program Assumptions

The MATLAB code version assumes a simplistic AWGN channel model, which supports Walsh and Gold codes for asynchronous detection. Also no pulse shaping or fading is assumed, with the receiver consisting of a single antenna case. Multi-path propagation is supported. There is no source/channel coding for the algorithms used.

Multuser Channel Estimation and Detection

If we assume Binary Phase Shift Keying (BPSK) modulation for the transmitted signal, the scheme uses spread spectrum signalling, where each active user uses a unique signature sequence or spreading code to modulate the data bits. The receiver system receives a summation of the signals of all the active users after they travel through different paths in the channel. These paths will induce different delays, attenuations and phase-shifts to their signals. Also, the signals from different users interfere with each other in addition to the Additive White Gaussian noise (AWGN) present in the channel. Thus, the multuser channel estimation consists of the joint estimation of these unknown parameters for all users in order to mitigate these undesirable effects and accurately detect the received bits of the different users. Also, the multuser detection refers to the detection of received bits for all users jointly by cancelling the interference between the different users.

In the MATLAB program, the channel estimation scheme is enhanced for an iterative scheme that avoids matrix inversions and has a simple fixed point architecture. The multuser detection is enhanced for a highly pipelined and bit-oriented scheme.

Another advantage of scheme is that there is no division except for multiplication by convergence parameter μ which can be implemented as a right-shift, by making it a power of two. This can be done as the algorithm converges for a wide range of μ . For simulation purposes, a Gold code of length 31 was assumed. This code was chosen for WCDMA [19] as it has desirable auto-correlation and cross-correlation properties for asynchronous transmission scheme.

Pipelined Multiuser Detection Process

The stages in the multistage detector are efficiently pipelined to avoid edge computations and to work on a bit streaming basis. This is equivalent to the normal detection of a block of infinite length, detected in a simple pipelined fashion. Also the computations can be reduced to work on smaller matrix sets. The computations performed on the intermediate bits reduce to

$$L = \Re \left[\hat{A}_1^H \hat{A}_0 \right]. \quad (\text{A.1})$$

$$C = \Re \left[\hat{A}_0^H \hat{A}_0 + \hat{A}_1^H \hat{A}_1 - \text{diag} \left(\hat{A}_0^H \hat{A}_0 + \hat{A}_1^H \hat{A}_1 \right) \right]. \quad (\text{A.2})$$

$$y_i^{(l)} = y_i^{(0)} - L \hat{d}_{i-1}^{(l-1)} - C \hat{d}_i^{(l-1)} - L^T \hat{d}_{i+1}^{(l-1)}. \quad (\text{A.3})$$

$$y_i^{(l)} = y_i^{(0)} - (\text{SCF}) L \hat{d}_{i-1}^{(l-1)} - (\text{SCF}) C \hat{d}_i^{(l-1)} - (\text{SCF}) L^T \hat{d}_{i+1}^{(l-1)}. \quad (\text{A.4})$$

$$\hat{d}_i^{(l)} = \text{sign} = (y_i^{(l)}). \quad (\text{A.5})$$

where $y_i^{(l)}$ and $\hat{d}_i^{(l)}$ are the soft and hard decisions respectively, after each stage of the multistage detector. Refer to Chapter 5 and 6 for other symbol definitions. These computations are iterated for $l = 1, 2, \dots, M$ where M is the maximum number of iterations chosen for convergence (typically, 3). Equation (A.3) represents subtracting the interference from the past bit of users, who have more delay, and the future bits of the users, who have less delay than the desired user. Equation (A.4) is the Soft Cancellation implementation of equation (A.3).

Running the P^3MUD Program and Parameter Settings

The Program was run on MATLAB Version 6.1.0, Release 12.1. Typing in the command ‘information4’, starts the execution of the program. Depending on the number of bits being transmitted, if less than 100000, than the program can be executed on a Pentium III, 500MHz processor system, with the execution time dependent on the bits transmitted. A virtual memory setting of 900 Mb is sufficient. This is done by varying the ‘Ld’ variable in the ‘Optimum_detect’ program. For transmitted bits above 100000, precisely 2000000 bits, this was done on a Dell with Intel Xeon Processor 2.20 GHz. The virtual memory was set to 4 Gb. The program execution took 40 minutes for different settings of the SCF value. The parameters are input in the GUI after it is called up as shown in the diagram below. The simulations used a μ value of 1/300, and the number of paths $P=4$. For the Single-user Optimum Detector Bound, $\rho = 0$, was used, and for the Conventional Matched Filter Bound, $\rho = 0.16$, was used.

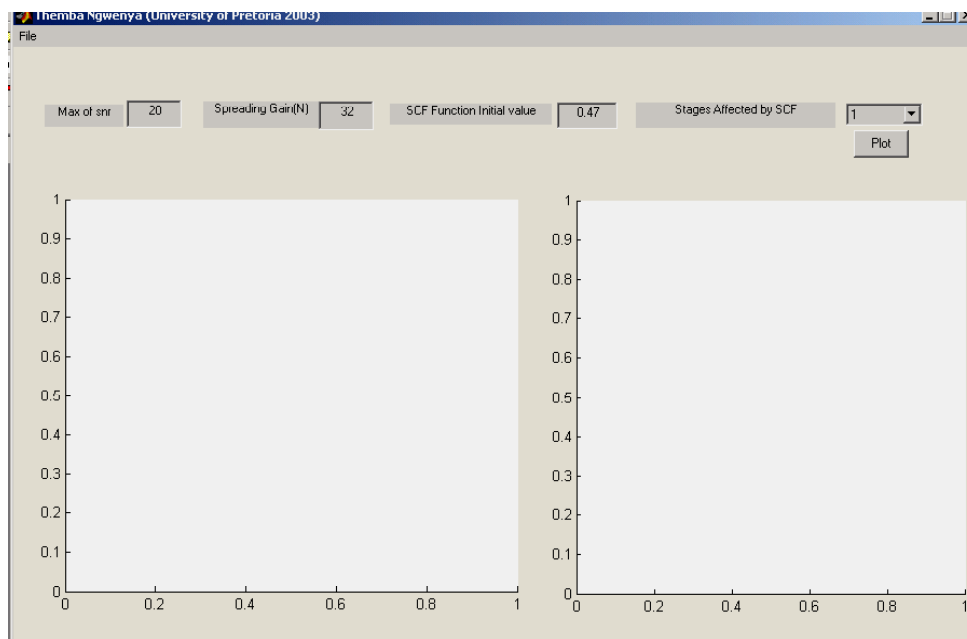


Figure A-2: Default Program GUI to enter variable data

That is for example, for constant number of users k , the BER is varied with the SNR, and also, for constant SNR, the BER is varied with k . Also input is the SCF value. If the Compensator mechanism is to be used, when using the $SCF_{UNV} = 0.57$ value, then the SCF.m file is loaded with the appropriate fractional values, i.e 0.15, 0.25..etc, otherwise these fractional values can be set to zero when varying other SCF values not SCF_{UNV} .

A sample of the output graphs is shown in figure A-3.

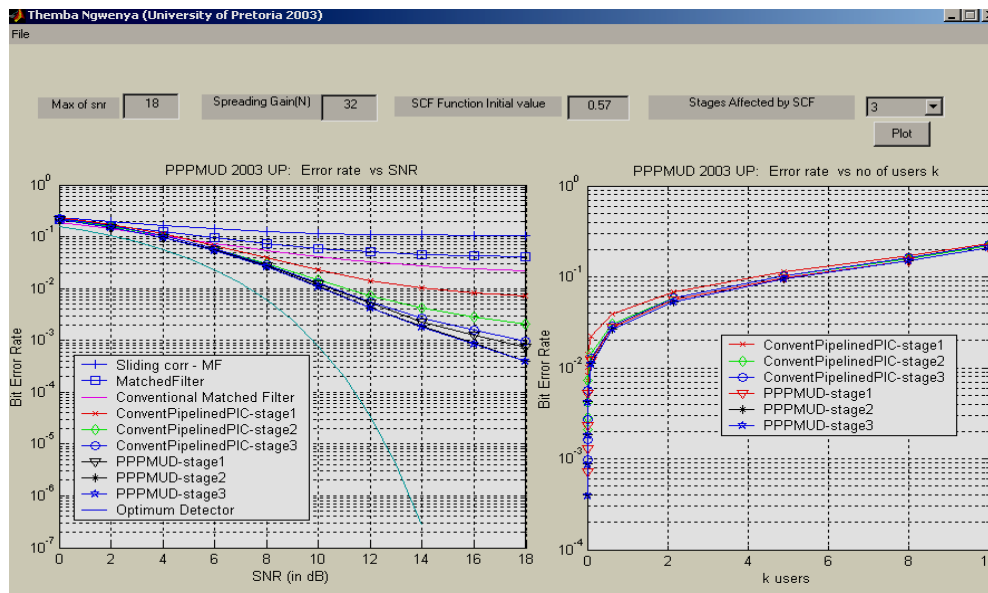


Figure A-3: BER vs SNR at constant k ($k=10$), and BER vs k at constant SNR (SNR=18).

It is seen from figure A-3, that the SCF_{UNV} value of 0.57 is being used, indicating that the compensator mechanism is also in use. The output graphs indicate the comparisons between the various detection schemes, i.e.,

For the BER versus SNR case:

- Sliding correlator Matched Filter
- The Matched Filter (first stage of Multiuser Detectors)
- The Verdu Matched Filter Approximate Detector
- Three stages of Conventional Bit-Streaming Pipe-lined Multiuser detection
- Three stages of Partial Parallel Pipelined Multiuser Detection
- The Verdu Single-user Optimum Detector

For the BER versus k case:

- Three stages of Conventional Bit-Streaming Pipelined Multiuser detection
- Three stages of Partial Parallel Pipelined Multiuser Detection

MATLAB Program

The MATLAB Program Modules that have been attached are:

- Information4.m
- Tester.m
- Optimum_detect.m
- Gendata.m
- Genseq.m
- SCF.m
- SplitAmatrix.m

The software version is also included and will be available from my supervisor, Professor Louis Linde, at the Centre For Radio & Digital Communication (CRDC) at the Department of Electrical, Electronic & Computer Engineering, University of Pretoria.

Information4.m

```

function varargout = Tester(varargin)
% INFORMATION4 Application M-file for information4.fig
% FIG = INFORMATION4 launch information4 GUI.
% INFORMATION4('callback_name', ...) invoke the named callback.
% Last Modified by Themba v2.0 27-April-2004 22:43:32
if nargin == 0 % LAUNCH GUI
    fig = openfig(mfilename,'reuse');
    % Generate a structure of handles to pass to callbacks, and store it.
    handles = guihandles(fig);
    guidata(fig, handles);
    if nargout > 0
        varargout{1} = fig;
    end
elseif ischar(varargin{1}) % INVOKE NAMED SUBFUNCTION OR CALLBACK
    try
        if (nargout)
            [varargout{1:nargout}] = feval(varargin{:}); %
FEVAL switchyard
        else
            feval(varargin{:}); % FEVAL switchyard
        end
    catch
        disp(lasterr);
    end
end

```

```

%| ABOUT CALLBACKS:
%| GUIDE automatically appends subfunction prototypes to this file, and
%| sets objects' callback properties to call them through the FEVAL
%| switchyard above. This comment describes that mechanism.
%|%| Each callback subfunction declaration has the following form:
%| <SUBFUNCTION_NAME>(H, EVENTDATA, HANDLES, VARARGIN)
%|%| The subfunction name is composed using the object's Tag and the
%| callback type separated by '_', e.g. 'slider2_Callback',
%| 'figure1_CloseRequestFcn', 'axis1_ButtondownFcn'.
%|%| H is the callback object's handle (obtained using GCBO).
%|%| EVENTDATA is empty, but reserved for future use.
%|%| HANDLES is a structure containing handles of components in GUI using
%| tags as fieldnames, e.g. handles.figure1, handles.slider2. This
%| structure is created at GUI startup using GUIHANDLES and stored in
%| the figure's application data using GUIDATA. A copy of the structure
%| is passed to each callback. You can store additional information in
%| this structure at GUI startup, and you can change the structure
%| during callbacks. Call guidata(h, handles) after changing your
%| copy to replace the stored original so that subsequent callbacks see
%| the updates. Type "help guihandles" and "help guidata" for more
%| information.
%|%| VARARGIN contains any extra arguments you have passed to the
%| callback. Specify the extra arguments by editing the callback
%| property in the inspector. By default, GUIDE sets the property to:
%| <MFILENAME>(<SUBFUNCTION_NAME>', gcbo, [], guidata(gcbo))
%| Add any extra arguments after the last argument, before the final
%| closing parenthesis.

```

```

% -----
function varargout = pushbutton1_Callback(h, eventdata, handles, varargin)
% this function is called when the plot button is pressed
%i1=get(handles.txtNoUsers,'String');
% first do some validation tests
    % test for a valid value of the no of users
    if isempty(str2num(get(handles.txtNoUsers,'String')))
        set(handles.errmsg,'Visible','on');
        set(handles.errmsg,'String','no of users not numeric'); % on error display error message
        return ;
    elseif floor(str2num(get(handles.txtNoUsers,'String'))) > 32 |
floor(str2num(get(handles.txtNoUsers,'String')))<2
        set(handles.errmsg,'Visible','on');
        set(handles.errmsg,'String','no of users greater than 32 or less than 2 not supported'); % on
error display error message
        return;
    end
    %test for a valid value for the spread gain
    if isempty(str2num(get(handles.txtSpreadGain,'String')))
        set(handles.errmsg,'Visible','on');
        set(handles.errmsg,'String','Spread Gain not numeric'); % on error display error message
        return ;
    elseif floor(str2num(get(handles.txtSpreadGain,'String'))) > 32 |
floor(str2num(get(handles.txtSpreadGain,'String'))) <=0
        set(handles.errmsg,'Visible','on');
        set(handles.errmsg,'String','invalid sread gain cannot be less than or equal to zero or greater
than 32');
        return;
    end
    %test for a valid value for the SCF starting value
    if isempty(str2num(get(handles.txtSCF,'String')))
        set(handles.errmsg,'Visible','on');
        set(handles.errmsg,'String','SCF start not numeric'); % on error display error message
        return ;
    elseif str2num(get(handles.txtSCF,'String')) > 1 | str2num(get(handles.txtSCF,'String')) <= 0
        set(handles.errmsg,'Visible','on');
        set(handles.errmsg,'String','invalid value for SCF cannot be less than or equal to zero or
greater than one');
        return;
    end
    set(handles.errmsg,'Visible','off'); % if no error make the error textbox invisible
    maxsnr=0;
    maxsnr=floor(str2num(get(handles.txtNoUsers,'String'))); %get the no of user
    spreadgain=0;
    spreadgain=floor(str2num(get(handles.txtSpreadGain,'String'))); %get the spread gain
    SCFstart=0.47;
    SCFstart=str2num(get(handles.txtSCF,'String')); % get the correlator initial value
    stages=get(handles.cmbStages,'Value');
    maxnusers=0; % initialise max no of users
        maxnusers=floor(maxsnr/2) + 1; % get the maximum no of users
    i=1;
        for i=1:maxnusers % fill matrix with the no of users
            kval(i)=(maxnusers) * (((maxnusers - i)/maxnusers)^(i-1));

```

end

```
[error_slvec,error_vec,err1_vec,err2_vec,err3_vec,epart1_vec,epart2_vec,epart3_vec,snr] = ...
    optimum_detect(maxnusers,spreadgain,SCFstart,stages); % function call to do the required
calculations to return the parameters
```

```
%MATLAB code for Single User Optimum Detector:
ro=0.00;
range = [0 14];
k=[0 1 2 6];
for na1=range(1):range(2)
nna1(na1-range(1)+1) = 10^(na1/10);
end;
[k1 k2]=size(k);
plt = zeros(range(2)-range(1),k2);
for i=1:k2
for j=1:range(2)-range(1)+1
a1=nna1(j);
a2=k(i)*nna1(j);
if (a1>a2*ro)
plt(j,i)=0.25*erfc(sqrt(a1-a2*ro)/sqrt(2))+0.25*erfc(sqrt(a1+a2*ro)/sqrt(2));
end;
if(a1<= a2*ro)
plt(j,i)=0.5*(1-erfc(sqrt(a2*ro-a1)/sqrt(2)))/2+0.25*erfc(sqrt(a1+a2*ro)/sqrt(2));
end;
end;
end;
end;
n=range(1):range(2);
```

```
%MATLAB for Conventional Matched Filter:
ro=0.16;
range=[0 18];
nou = 10;

for i=range(1):range(2);

nna1(i-range(1)+1)=sqrt(10^(i/10));
end;
for k=1:(range(2)-range(1)+1)
end;

xr =range(1):range(2);
for i=range(1):range(2)
temp(i-range(1)+1)=0.5*erfc(nna1(i-range(1)+1)/(sqrt(2)*sqrt(1+(nou-1)*ro^2*nna1(i-
range(1)+1)^2)));
end;
```

```
axes(handles.axes1); % set axes 1 as the current drawing view
hold off; % erase any previous drawings
```

```
semilogy(snr,error_slvec,'-+'); % plot graph with y axis in logarithmic plot of base 10 (sliding
correlator),x snr
```

```

hold on; % dont erase the drawing view draw on top
semilogy(snr,error_vec,'-s'); % plot graph with y axis in logarithmic plot of base 10 (error
vector),x snr
hold on; % dont erase the drawing view draw on top
semilogy(xr, temp,'-m'); %plot Conventional Matched Filter analytical results
hold on;
semilogy(snr,err1_vec,'-xr'); % plot graph with y axis in logarithmic plot of base 10 (PIC 1),x snr
hold on; % dont erase the drawing view draw on top
semilogy(snr,err2_vec,'-dg'); % plot graph with y axis in logarithmic plot of base 10 (PIC 2),x snr
hold on; % dont erase the drawing view draw on top
semilogy(snr,err3_vec,'-o'); % plot graph with y axis in logarithmic plot of base 10 (PIC 3),x snr
hold on; % dont erase the drawing view draw on top
semilogy(snr,epart1_vec,'-vk'); % plot graph with y axis in logarithmic plot of base 10 (epart1),x
snr
hold on; % dont erase the drawing view draw on top
semilogy(snr,epart2_vec,'-*k'); % plot graph with y axis in logarithmic plot of base 10 (epart2),x
snr
hold on; % dont erase the drawing view draw on top
semilogy(snr,epart3_vec,'-p'); % plot graph with y axis in logarithmic plot of base 10 (epart3),x
snr
hold on; % dont erase the drawing view draw on top
grid
semilogy(n,plt,'-');%Plot single user optimum detector
hold on;

title('PPPMUD 2003 UP: Error rate vs SNR');
xlabel('SNR (in dB)');
ylabel('Bit Error Rate');
legend('Sliding corr - MF','MatchedFilter','Conventional Matched Filter','ConventPipelinedPIC-
stage1','ConventPipelinedPIC-stage2','ConventPipelinedPIC-stage3','PPPMUD-stage1','PPPMUD-
stage2','PPPMUD-stage3','Optimum Detector');

axes(handles.axes2); % make axes 2 the current drawing view
hold off; % erase any previous drawings on axis

semilogy(kval,err1_vec,'-xr'); % plot graph with y axis in logarithmic plot of base 10 (PIC 1),x
users k
hold on; % dont erase the drawing view draw on top
semilogy(kval,err2_vec,'-dg'); % plot graph with y axis in logarithmic plot of base 10 (PIC 2),x
users k
hold on; % dont erase the drawing view draw on top
semilogy(kval,err3_vec,'-o'); % plot graph with y axis in logarithmic plot of base 10 (PIC 3),x
users k
hold on; % dont erase the drawing view draw on top
semilogy(kval,epart1_vec,'-vr'); % plot graph with y axis in logarithmic plot of base 10 (epart1),x
users k
hold on; % dont erase the drawing view draw on top
semilogy(kval,epart2_vec,'-*k'); % plot graph with y axis in logarithmic plot of base 10 (epart2),x
users k
hold on; % dont erase the drawing view draw on top
semilogy(kval,epart3_vec,'-p');% plot graph with y axis in logarithmic plot of base 10 (epart3),x
users k

```

```

hold on; % dont erase the drawing view draw on top
grid
hold on;
title('PPPMUD 2003 UP: Error rate vs no of users k');
xlabel('k users');
ylabel('Bit Error Rate');
legend('ConventPipelinedPIC-stage1','ConventPipelinedPIC-stage2','ConventPipelinedPIC-
stage3','PPPMUD-stage1','PPPMUD-stage2','PPPMUD-stage3');

```

```

% -----
function varargout = txtNoUsers_ButtonDownFcn(h, eventdata, handles, varargin)
% -----
function varargout = txtNoUsers_Callback(h, eventdata, handles, varargin)
% -----
function varargout = pushbutton1_ButtonDownFcn(h, eventdata, handles, varargin)
% -----
function varargout = txtSpreadGain_Callback(h, eventdata, handles, varargin)
% -----
function varargout = TxtSCF_Callback(h, eventdata, handles, varargin)
% -----
function varargout = cmbStages_Callback(h, eventdata, handles, varargin)

```

Tester.m

```

function tester

F= 20* ones(1,11);

i=1;

%F(1)=12

for i=1:F

disp(num2str(i));

end

i=11

w(i)=2.0/(F(i)*30.0)

```

Optimum_detect.m

```

function [error_slvec,error_vec,err1_vec,err2_vec,err3_vec,epart1_vec,epart2_vec,epart3_vec,snr]
= optimum_detect(LN,N,SCFstart,stages)

% Program for maximum likelihood estimation and multiuser detection

```

```

% Originally written by Sridhar Rajagopal sridhar@rice.edu
% http://www.ece.rice.edu/~sridhar
%% Modified by Themba Ngwenya, themba.ngwenya@ericsson.com
% University of Pretoria, Pretoria, South Africa 2003
% LN is the no of user
% N is the Spread gain
% SCFstart is the SCF start value
% stages is the no of PIC stages affected by the Function
% error_slvec is sliding correlator vector
% error_vec is matched filter
% err1_vec PIC stage 1
% err2_vec PIC stage 2
% err3_vec PIC stage 3
% epart1_vec epart1
% epart2_vec epart2
% epart3_vec epart3
% should warn if no of users exceed 32 because of K it should always be <= N
ij=1;
for ij=1:LN
    snr(ij)=(ij-1)*2;
end
K = 20*ones(1,LN); % 1rix of 20 by 11 matrix of onesfor k = 1:length(snr)
for k = 1:LN
    % N =32; this is now a program parameter
    L = 200;sinr = 0;P =4;
    rand('state',0);
    randn('state',0);
% Estimation part

```

```

[r, codes, bits, atau, aamp] = gendata(N, K(k), sinr, snr(k), L, P);
bt = kron(bits(:, 1:L), [1; 0]) + kron(bits(:, 2:L+1), [0; 1]);
Yest = zeros(2*K(k), N);
Rbb = zeros(2*K(k), 2*K(k));
Rbr = zeros(2*K(k), N);
Windowsize = L+1;
mu = 1/5000;
for (i = 1:L)
    if (i < Windowsize)
        Rbb = Rbb + (bt(:, i)*bt(:, i)');
        Rbr = Rbr + (bt(:, i)*r(:, i)');
    else
        Rbb = Rbb + bt(i)*bt(i)' - bt(i-Windowsize)*bt(i-Windowsize)';
        Rbr = Rbr + (bt(i)*r(i)' - bt(i-Windowsize)*r(i-Windowsize)');
    end;
    Yest = Yest - mu*(Rbb*Yest - Rbr);
end;
Y = Yest';
%Y = Rbr';
%size(Y);
A0 = []; A1 = [];
for i = 1:2*K(k)
    a = mod(i, 2);
    if (a ~= 0)
        A0 = [A0 Y(:, i)];
    else
        A1 = [A1 Y(:, i)];
    end;
end;

```

```

        end;

    Rbr = Rbr'; % Comparison with sliding correlator

    A0sl = []; A1sl = [];

    for i= 1:2*K(k)

        a = mod(i,2);

            if(a ~= 0)

                A0sl = [A0sl (Rbr(:,i))/L];

            else

                A1sl = [A1sl (Rbr(:,i))/L];

            end;

        end;

    Lmat = real(A1'*A0);

    C = real(A0'*A0 + A1'*A1 -diag(diag(A0'*A0 + A1'*A1 )));

    error = 0;

    err1 = 0;

    err2 = 0;

    err3 = 0;

    epart1 = 0;

    epart2 = 0;

    epart3 = 0;

    errorsl = 0;

    error1= zeros(1,3);

    picerror=zeros(1,3);

    Ld = round(100000);% loading preamble bits

    y = zeros(K(k),Ld);

    d = y;

    dsl = y;

    ytemp = y;

```

```

ysl = y;

% Detection part

rand('state',0);

randn('state',0)

[r,codes,bits,atau,aamp] = gendata(N,K(k),sinr,snr(k),Ld,P);

r = reshape(r,N,Ld);

% Matched Filter - MF, makes initial detection of transmitted bits,and the soft and hard outputs fed
to Multiuser Detection stage

for(i=1:Ld)

    if (i==1)

        y(:,i) = real(A0*r(:,i));

        ysl(:,i) = real(A0sl*r(:,i));

    else

        y(:,i) = real(A1*r(:,i-1) + A0*r(:,i));

        ysl(:,i) = real(A1sl*r(:,i-1) + A0sl*r(:,i));

    end;

    y(:,i);

    d(:,i) = sign(y(:,i));

    for(j=1:K(k))

        if( d(j,i) ~= bits(j,i))

            error = error +1;

        end;

    end;

    dsl(:,i) = sign(ysl(:,i));

    for(j=1:K(k))

        if( dsl(j,i) ~= bits(j,i))

            errorsl = errorsl +1;

        end;

```

```

    end;

end;

%Detection Stages for Conventional and PPPMUD

% Conventional Parallel Pipelined Multiuser Detector

% PIC - Stage 1 ,2 and 3

ij=1;

for(ij=1:3)

    for(i=1:Ld)

        if(i==1)

            ytemp(:,i) = y(:,i) - C*d(:,i) - Lmat'*d(:,i+1); % first row

        elseif (i ==Ld)

            ytemp(:,i) = y(:,i) - Lmat*d(:,i-1) - C*d(:,i); % other rows

        else

            ytemp(:,i) = y(:,i) - Lmat*d(:,i-1) - C*d(:,i) - Lmat'*d(:,i+1); % last row

        end;

        d(:,i) = sign(ytemp(:,i)); % get the sign

        for(j =1:K(k))

            if( d(j,i) ~= bits(j,i))

                picerror(ij) = picerror(ij) +1; % increment the bit error count

            end;

        end;

    end;

end;

end

% Partial Parallel Pipelined Multiuser Detector - PPPMUD

% The SCF multiplies the channel gain estimates before subtraction from received signal

ij=1;

for(ij=1:3)

    for(i=1:Ld)

```

```

    if(i==1)

        ytemp(:,i) = y(:,i) - SCF(snr(k),ij,SCFstart,stages)*C*d(:,i) -
        SCF(snr(k),ij,SCFstart,stages)*Lmat*d(:,i+1); % first row

    elseif (i ==Ld)

        ytemp(:,i) = y(:,i) - SCF(snr(k),ij,SCFstart,stages)*Lmat*d(:,i-1) -
        SCF(snr(k),ij,SCFstart,stages)*C*d(:,i); %second row

    else

        ytemp(:,i) = y(:,i) - SCF(snr(k),ij,SCFstart,stages)*Lmat*d(:,i-1) -
        SCF(snr(k),ij,SCFstart,stages)*C*d(:,i) - ...

        SCF(snr(k),ij,SCFstart,stages)*Lmat*d(:,i+1); % last row

    end;

    d(:,i) = sign(ytemp(:,i));

    for(j =1:K(k))

        if( d(j,i) ~= bits(j,i))

            error1(ij) = error1(ij) +1;

            end;

        end;

    end;

end

ind=K(k)*Ld;

error_slvec(k) = errorsl/ind; % sliding correlator

error_vec(k) = error/ind;    % error

err1_vec(k) = picerror(1)/ind; % error in PIC stage 1

err2_vec(k) = picerror(2)/ind; % error in PIC stage 2

err3_vec(k) = picerror(3)/ind; % error in PIC stage 3

epart1_vec(k) = error1(1)/ind; % error in PPPMUD Stage 1

epart2_vec(k) = error1(2)/ind; % error in PPPMUD stage 2

epart3_vec(k) = error1(3)/ind; % error in PPPMUD stage 3

```

end;

Gendata.m

```
function [y, codes, bits, tau, amplitude, dim] = gendata(n, k, sinr, snr, L, P, a)

%GENDATA Generate Direct-sequence CDMA antenna data

%%      function [y, codes, bits, tau, amplitude, dim] = gendata(n, k, sinr, snr, L, P, a)
%      PARAMETER:
%      n = Spreading gain (i.e. # of chips/symbol)
%      k = Number of users
%      sinr = Signal-to-interference noise ratio (in dB)
%      snr = Signal-to-noise ratio (in dB)
%      L = Number of snapshots to be obtained. Each column of y
%           corresponds to 1 snapshot (i.e. "n" chips) of data.
%      P = Number of Paths
%      a = Optional parameter which defines the spreading waveforms.
%           If the parameter is undefined, it will be generated
%           internally.
%      OUTPUT:
%      y = Observed data corrupted by noise ( N*L)
%      codes = The codes of the various users, obtained from Gold code 31(N*K)
%      bits = The sequence of bits which are transmitted( K*(L+1)
%            observation length +1)
%      tau = The delays of the various bits.
%((K*P) * 1) K user's P paths
%      amplitude = The amplitude of the various bits
%( 1 * (K*P))
%      dim : The total number of orthogonal dimensions required.
%           Genseq(n,i) is used to generate the
```

```

%      spreading waveform for user i
%
%      Initially Written by : Kishore Kota,Chaitali Sengupta
%      Modified by : Sridhar Rajagopal
% Generate the spreading sequences
% Fill the Codes matrix with the Gold Code corresponding to the
% randomly selected user.
if ( nargin == 6)
codes = zeros(n,k);
maxusers = genseq(n);
[tmp index] = sort(rand(maxusers,1));
for i=1:min([k maxusers])
    codes(:,i) = genseq(n,index(i));
end
if (k > maxusers)
    for i=(maxusers+1):k
        codes(:,i) = sign(randn(n,1));
    end
end
end
a = kron(ones(1,P),codes);
% Make them asynchronous; Generate random delays
tau = ((n-2)/P)*rand(k,1);
for p=2:P
    tau = [tau; ((n-1)/P)*rand(k,1)+tau((p-2)*k+1:(p-2)*k+k)];
end
tau = tau+1;
% Generate the amplitudes and MAI

```

```

mai = 10.^(-sinr*rand(1,k)/20);

mai(1) = 1.0;

amp = exp(sqrt(-1)*2*pi*rand(1,k));

amplitude=amp.*mai;

%Amplitude of Path P assumed as Amplitude/P

for p=2:P

    for i=1:k

        amplitude((p-1)*k+i) = amplitude(i)/p;

    end

end

% estimate noise variance

var = sqrt(n)*10^(-snr/20);

% Generate random data(currently it is uncorrelated)

bits = round(round(rand(k,L+1)) - .5*ones(k,L+1));

x = kron(ones(P,1),bits);

% Generate random noise

noise = (randn(n,L) + sqrt(-1)*randn(n,L))*var*sqrt(0.5);

% Generate the data

[aleft, aright] = splitAmatrix(a,tau);

%plits a into aleft and aright matrices

xx = diag([amplitude'; amplitude']) * [x(:,1:L); x(:,2:L+1)];

y = (aleft+aright) * xx;

dim=rank(y);

y = y + noise;

```

Genseq.m

```

function [code] = genseq(n, k)

%GENSEQ  Generate a m-sequence

```

```

%      function [code] = genseq(n, k)
%      n = length of the m-sequence
%      k = index into the sequence table
%      code = a vector containing the m-sequence
%%     If the parameter "k" is missing, then the function returns with
%      the number of codes of length "n" currently implemented.
%%     NOTE: Currently the sequence table is implemented only for n=31
%%     Written by : Kishore Kota

gold=0;

if (n == 31)

    [GC]=GoldCode(31);

    gold = 1;

    seqtable = [0 1 1 1 0 0; ...
                0 0 1 0 1 0; ...
                1 0 1 0 0 1; ...
                1 0 1 1 1 1; ...
                1 1 1 0 1 1; ...
                ];

elseif (n == 3)

    seqtable = [1 1 1]';

elseif (n == 7)

    gold=1;

    [GC]=GoldCode(7);

    seqtable = [1 1 0 1]';

elseif (n == 15)

    seqtable = [1 1 0 0 1; ...
                1 1 1 1 1]';

elseif (n == 63)

```

```

seqtable = [1 1 0 0 0 0 1; ...
            1 1 1 0 1 0 1; ...
            1 1 1 0 0 1 1; ...
            1 0 0 1 0 0 1; ...
            1 0 1 1 0 0 0; ...
            ];

elseif (n == 127)

    seqtable = [1 0 0 1 0 0 0 1; ...
               1 1 1 1 0 0 0 1; ...
               1 0 1 1 1 0 0 1; ...
               1 1 1 0 1 1 1 1; ...
               1 1 1 1 1 1 0 1; ...
               1 0 1 0 1 0 1 1; ...
               1 1 0 0 0 0 0 1; ...
               1 1 0 1 0 0 1 1; ...
               1 0 1 0 0 1 1 1; ...
               ];

elseif (n == 255)

    seqtable = [1 0 1 1 1 0 0 0 1; ...
               1 1 1 0 1 1 1 0 1; ...
               1 1 0 0 1 1 1 1 1; ...
               1 0 0 1 0 1 1 0 1; ...
               1 0 1 1 1 1 0 1 1; ...
               1 1 1 0 0 1 1 1 1; ...
               1 1 0 1 0 1 0 0 1; ...
               1 1 1 0 1 0 1 1 1; ...
               1 1 0 0 1 0 0 0 0; ...
               1 0 1 0 0 1 1 0 1; ...

```

```

1 1 0 1 0 0 0 1 1; ...
1 1 0 0 0 1 1 0 1; ...
1 1 0 1 1 0 0 0 1; ...
1 1 1 1 1 1 0 0 1; ...
1 1 1 1 1 0 1 0 1; ...
1 1 0 0 0 0 1 1 1; ...
1 0 0 1 1 1 0 0 1; ...
1 1 1 1 1 0 0 0 0; ...
1 1 1 0 0 0 0 0 0; ...
];

elseif (n == 511)
    seqtable = [1 0 0 0 1 0 0 0 0 1; ...
1 0 0 1 1 0 1 0 0 1; ...
1 0 0 0 1 1 1 0 0 1; ...
1 0 0 1 1 0 0 1 0 1; ...
1 1 0 0 1 0 0 0 1 1; ...
1 0 1 1 0 1 0 0 0 1; ...
1 1 1 0 1 1 1 0 0 1; ...
1 0 0 0 0 1 1 0 1 1; ...
1 1 0 1 1 0 1 1 0 1; ...
1 0 1 0 0 0 0 1 1 1; ...
1 1 1 0 1 0 0 0 0 1; ...
1 0 0 1 0 1 1 1 1 1; ...
1 1 0 0 0 1 1 1 1 1; ...
1 1 1 1 0 0 0 1 1 1; ...
1 1 0 1 0 1 1 0 1 1; ...
1 0 0 0 0 0 0 1 1; ...
1 1 1 1 0 1 1 0 0 1; ...

```

```

        1 0 1 1 0 0 1 1 1 1; ...
        1 1 1 0 1 1 1 0 1 1; ...
        1 1 0 1 0 0 1 1 1 1; ...
        1 0 1 1 1 1 1 0 0 1; ...
        1 0 1 0 1 0 1 1 1 1; ...
        1 0 1 0 1 0 0 1 0 1; ...
        1 0 1 1 1 1 0 1 0 1; ...
        1 1 0 1 0 0 0 0 0 0; ...
        1 1 0 1 1 1 1 1 1 1; ...
        1 0 0 1 0 0 1 0 1 1; ...
        1 0 1 0 1 0 0 0 1 1; ...
        1 1 1 0 1 1 0 1 0 1; ...
    ];

elseif(n == 1023)
    seqtable = [ 1 0 0 1 0 0 0 0 0 0 1; ...
                %1 1 1 1 0 0 0 0 0 0 1; ...
                1 0 1 1 0 0 0 0 1 0 1; ...
                1 0 0 1 1 1 1 1 1 1 1; ...
                %1 1 1 1 0 1 0 1 0 0 1; ...
                %1 0 1 0 1 1 0 0 0 0 1; ...
                1 1 1 1 0 1 1 0 0 0 1; ...
                1 0 1 1 0 0 1 0 1 1 1; ...
                1 1 0 1 1 1 1 1 1 0 1; ...
                1 1 0 1 1 0 0 0 0 0 1; ...
                1 1 0 0 0 1 0 0 1 0 1; ...
                1 0 0 0 1 1 0 0 1 0 1; ...
                1 1 0 0 1 0 0 0 0 1 1; ...
                1 1 0 0 0 1 1 0 1 1 1; ...

```

```

1 0 1 0 0 1 1 1 1 0 1; ...
1 0 0 1 1 0 0 0 1 0 1; ...
1 1 1 1 1 1 1 0 0 1 1; ...
1 0 1 0 1 0 1 0 1 1 1; ...
1 1 1 1 0 0 0 1 1 0 1; ...
1 0 0 1 1 1 0 0 1 1 1; ...
1 1 0 0 1 0 1 1 0 1 1; ...
1 1 1 0 0 0 1 0 1 1 1; ...
1 1 0 0 1 0 0 1 1 1 1; ...
1 1 1 0 0 0 1 1 1 0 1; ...
1 1 1 0 1 0 1 1 0 0 1; ...
1 0 1 0 1 1 0 1 0 1 1; ...
1 0 1 1 0 1 0 0 0 0 1; ...
1 0 1 1 1 1 1 0 1 1 1; ...
1 0 0 1 1 1 1 0 0 1 1; ...
1 1 1 0 0 1 0 0 0 0 1; ...
1 0 1 0 1 0 0 0 0 1 1; ...
1 1 1 1 1 0 1 1 0 1 1; ...
1 0 0 1 0 0 0 1 0 1 1; ...
];

```

```

elseif ((log2(n)-floor(log2(n))) == 0)
    % Code is a power of 2 then use Walsh codes.....
    H = 1;gold = 1;
for i=1:ceil(log2(n))
    H = [ H H;H -H];
end;
GC = H;

```

```

%code = seqtable(1:k,:);

%return;

else

    n

    error('Table not yet implemented the above value of N');

end

if (nargin == 1)

    if (gold == 0)

        code = length(seqtable(1,:));

        return

    else

        code = length(GC(:,1));

        return

    end

end

% If it is a gold code simply retrieve it from the table and return

if (gold==1)

    code = GC(k,:);

    return

end

if ((log2(n)-floor(log2(n))) == 0)

code = GC(1:k,:);

return;

return;

end;

stages = floor(1.442695*log(n) + 1.0);

maxnum = 2^stages;

init = zeros(stages + 1,1); init(1) = 1;

```

```

perm = zeros(stages+1, stages+1);

for i=2:stages+1
    perm(i,i-1) = 1;
end

register = init;

sequence = seqtable(:,k);

for i=1:n
    register = perm*register;

    code(i) = register(stages+1);

    if (code(i) == 0)
        code(i) = -1;
    end

    mask = register & sequence;

    for j=1:size(mask)
        register(1) = xor(register(1), mask(j));
    end
end

```

SCF.m

```

function r=SCF(k,ki,start,stagesaffected)

% this is the Compensator mechanism function

% k is the snr based on the no of users

% ki is an integral value representing the particular PIC stage

% stagesaffected is the no of stages of the PIC algorithm affected by this function

% start is the starting value for this function

if stagesaffected <=0 or stagesaffected >3
    stagesaffected=1;
end

if ki > stagesaffected

```

```

    r=1;

    return;

end

r=start;

if k > 2 & k <= 8

    r = r + 0.15;

elseif k>2 & k<=12

    r = r + 0.25;

elseif k > 2 & k <=35

    r = r + 0.35;

else

    r=r;

end

```

SplitAmatrix

```

function [aleft, aright] = splitAmatrix(a,tau)

% function [aleft, aright] = shiftsteeringmatrix(a,tau)

% Splits the a matrix ( n* (p*k)) into aleft and aright matrices (n* 2*(p*k))

% Note : k used below in this code is NOT the number of users; it is K*P

[n,k] = size(a);

k = min([k max(size(tau))]);

aleft = zeros(n,2*k);

aright = zeros(n,2*k);

tau = rem(tau + n*ones(size(tau)), n);

frac = tau - floor(tau);

for i=1:k

    s = floor(tau(i));

    if (s ~= 0)

```



```
    aleft(1:s,i) = (1-frac(i)) * a(n-s+1:n,i);  
end  
aleft(s+1:n,k+i) = (1-frac(i)) * a(1:n-s,i);  
aright(1:s+1,i) = frac(i) * a(n-s:n,i);  
if (s ~= n-1)  
    aright(s+2:n, k+i) = frac(i) * a(1:n-s-1,i);  
end  
end
```

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